

STM32L0xx_Nucleo_32 BSP User Manual

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Private Function Prototypes

NUCLEO 32

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- __STM32L0XX_NUCLEO_32_BSP_VERSION : [stm32l0xx_nucleo_32.c](#)
- __STM32L0XX_NUCLEO_32_BSP_VERSION_MAIN : [stm32l0xx_nucleo_32.c](#)
- __STM32L0XX_NUCLEO_32_BSP_VERSION_RC : [stm32l0xx_nucleo_32.c](#)
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- ADCx_Init() : [stm32l0xx_nucleo_32.c](#)
- ADCx_MspInit() : [stm32l0xx_nucleo_32.c](#)

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- BSP_JOY_GetState() : [stm32l0xx_nucleo_32.h](#) ,
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- I2C1_Error() : [stm32l0xx_nucleo_32.c](#) , [stm32l0xx_nucleo_32.h](#)
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- BSP_GetVersion() : [stm32l0xx_nucleo_32.c](#) , [stm32l0xx_nucleo_32.h](#)
- BSP_JOY_GetState() : [stm32l0xx_nucleo_32.h](#) , [stm32l0xx_nucleo_32.c](#)
- BSP_JOY_Init() : [stm32l0xx_nucleo_32.c](#) , [stm32l0xx_nucleo_32.h](#)
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- NUCLEO_SPIx_CLK_ENABLE : [stm32l0xx_nucleo_32.h](#)
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- SD_CS_GPIO_CLK_DISABLE : [stm32l0xx_nucleo_32.h](#)
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- SD_CS_PIN : [stm32l0xx_nucleo_32.h](#)
- SD_DUMMY_BYTE : [stm32l0xx_nucleo_32.c](#)
- SD_NO_RESPONSE_EXPECTED : [stm32l0xx_nucleo_32.c](#)

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stm32l0xx_nucleo_32.c File Reference

This file provides set of firmware functions to manage: [More...](#)

```
#include "stm32l0xx_nucleo_32.h"
```

[Go to the source code of this file.](#)

Defines

#define	__STM32L0XX_NUCLEO_32_BSP_VERSION_MAIN	(0x01)
	STM32L0XX NUCLEO BSP Driver version number.	
#define	__STM32L0XX_NUCLEO_32_BSP_VERSION_SUB1	(0x00)
#define	__STM32L0XX_NUCLEO_32_BSP_VERSION_SUB2	(0x03)
#define	__STM32L0XX_NUCLEO_32_BSP_VERSION_RC	(0x00)
#define	__STM32L0XX_NUCLEO_32_BSP_VERSION	
#define	SD_DUMMY_BYTE	0xFF
	LINK SD Card.	
#define	SD_NO_RESPONSE_EXPECTED	0x80

Functions

	static void	SPIx_Init (void) Initializes SPI HAL.
	static void	SPIx_Write (uint8_t Value) SPI Write a byte to device.
	static uint32_t	SPIx_Read (void) SPI Read 4 bytes from device.
	static void	SPIx_Error (void) SPI error treatment function.
	static void	SPIx_Msplinit (SPI_HandleTypeDef *hspi) Initializes SPI MSP.
	void	SD_IO_Init (void) Initializes the SD Card and put it into StandBy State (Ready for data transfer).
HAL_StatusTypeDef		SD_IO_WriteCmd (uint8_t Cmd, uint32_t Arg, uint8_t Crc, uint8_t Response) Sends 5 bytes command to the SD card and get response.
HAL_StatusTypeDef		SD_IO_WaitResponse (uint8_t Response) Waits response from the SD card.
	void	SD_IO_WriteDummy (void) Sends dummy byte with CS High.
	void	SD_IO_WriteByte (uint8_t Data) Writes a byte on the SD.
	uint8_t	SD_IO_ReadByte (void) Reads a byte from the SD.
	void	LCD_IO_Init (void) Initializes the LCD.
	void	LCD_IO_WriteData (uint8_t Data) Writes data to select the LCD register.
	void	LCD_IO_WriteMultipleData (uint8_t *pData, uint32_t Size)

	Write register value.
void	LCD_IO_WriteReg (uint8_t LCDReg) Writes command to select the LCD register.
void	LCD_Delay (uint32_t Delay) Wait for loop in ms.
static void	ADCx_Init (void) Initializes ADC HAL.
static void	ADCx_Msplnit (ADC_HandleTypeDef *hadc) Initializes ADC MSP.
uint32_t	BSP_GetVersion (void) This method returns the STM32L0XX NUCLEO BSP Driver revision.
void	BSP_LED_Init (Led_TypeDef Led) Configures LED GPIO.
void	BSP_LED_On (Led_TypeDef Led) Turns selected LED On.
void	BSP_LED_Off (Led_TypeDef Led) Turns selected LED Off.
void	BSP_LED_Toggle (Led_TypeDef Led) Toggles the selected LED.
void	I2C1_Init (void) I2C Bus initialization.
void	I2C1_Write (uint8_t Addr, uint8_t Reg, uint8_t Value) Writes a single data.
uint8_t	I2C1_Read (uint8_t Addr, uint8_t Reg) Reads a single data.
HAL_StatusTypeDef	I2C1_ReadBuffer (uint16_t Addr, uint8_t Reg, uint16_t RegSize, uint8_t *pBuffer, uint16_t Length) Reads multiple data on the BUS.
HAL_StatusTypeDef	I2C1_IsDeviceReady (uint16_t DevAddress, uint32_t Trials) Checks if target device is ready for

	communication.
HAL_StatusTypeDef	I2C1_WriteBuffer (uint16_t Addr, uint8_t Reg, uint16_t RegSize, uint8_t *pBuffer, uint16_t Length) Write a value in a register of the device through BUS.
void	I2C1_Error (void) Manages error callback by re-initializing I2C.
void	I2C1_MspInit (I2C_HandleTypeDef *hi2c) I2C MSP Initialization.
uint8_t	BSP_JOY_Init (void) Configures joystick available on adafruit 1.8" TFT shield managed through ADC to detect motion.
JOYState_TypeDef	BSP_JOY_GetState (void) Returns the Joystick key pressed.

Variables

GPIO_TypeDef *	LED_PORT [LEDn] = { LED3_GPIO_PORT }
const uint16_t	LED_PIN [LEDn] = { LED3_PIN }
uint32_t	I2c1Timeout = BSP_I2C1_TIMEOUT_MAX BUS variables.
I2C_HandleTypeDef	heval_I2c1
uint32_t	SpixTimeout = NUCLEO_SPIx_TIMEOUT_MAX
static SPI_HandleTypeDef	hnucleo_Spi
static ADC_HandleTypeDef	hnucleo_Adc
static ADC_ChannelConfTypeDef	sConfig

Detailed Description

This file provides set of firmware functions to manage:

Author:

MCD Application Team

- LEDs and push-button available on STM32L0XX-Nucleo Kit from STMicroelectronics

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Definition in file [stm32l0xx_nucleo_32.c](#).

STM32L0xx_Nucleo_32 BSP User Manual

Main Page	Modules	Files	Directories	
File List	Globals			
Firmware	Drivers	BSP	STM32L0xx_Nucleo_32	Defines Enumerations Functions

stm32l0xx_nucleo_32.h File Reference

This file contains definitions for: [More...](#)

```
#include "stm32l0xx_hal.h"
```

[Go to the source code of this file.](#)

Defines

```
#define LEDn 1
#define LED3_PIN GPIO_PIN_3
#define LED3_GPIO_PORT GPIOB
#define LED3_GPIO_CLK_ENABLE() __HAL_RCC_GPIOB_CLK_ENABLE()
#define LED3_GPIO_CLK_DISABLE() __HAL_RCC_GPIOB_CLK_DISABLE()
#define LEDx_GPIO_CLK_ENABLE(__INDEX__) do {LED3_GPIO_CLK_ENABLE();} while(0)
#define LEDx_GPIO_CLK_DISABLE(__INDEX__) LED3_GPIO_CLK_DISABLE()
#define BSP_I2C1 I2C1
#define BSP_I2C1_CLK_ENABLE() __HAL_RCC_I2C1_CLK_ENABLE()
#define BSP_I2C1_CLK_DISABLE() __HAL_RCC_I2C1_CLK_DISABLE()
#define BSP_I2C1_FORCE_RESET() __HAL_RCC_I2C1_FORCE_RESET()
#define BSP_I2C1_RELEASE_RESET() __HAL_RCC_I2C1_RELEASE_RESET()
#define BSP_I2C1_SCL_PIN GPIO_PIN_6 /* PB.6 add wire between
#define BSP_I2C1_SDA_PIN GPIO_PIN_7 /* PB.7 add wire between
#define BSP_I2C1_GPIO_PORT GPIOB /* GPIOB */
#define BSP_I2C1_GPIO_CLK_ENABLE() __HAL_RCC_GPIOB_CLK_ENABLE()
#define BSP_I2C1_GPIO_CLK_DISABLE() __HAL_RCC_GPIOB_CLK_DISABLE()
#define BSP_I2C1_SCL_SDA_AF GPIO_AF1_I2C1
#define BSP_I2C1_TIMEOUT_MAX 1000
#define I2C1_TIMING 0x009080B5
#define NUCLEO_SPIx SPI1
#define NUCLEO_SPIx_CLK_ENABLE() __HAL_RCC_SPI1_CLK_ENABLE()
#define NUCLEO_SPIx_SCK_AF GPIO_AF0_SPI1
#define NUCLEO_SPIx_SCK_GPIO_PORT GPIOA
#define NUCLEO_SPIx_SCK_PIN GPIO_PIN_11
#define NUCLEO_SPIx_SCK_GPIO_CLK_ENABLE() __HAL_RCC_GPIOA_CLK_ENABLE()
#define NUCLEO_SPIx_SCK_GPIO_CLK_DISABLE() __HAL_RCC_GPIOA_CLK_DISABLE()
#define NUCLEO_SPIx_MISO_MOSI_AF GPIO_AF0_SPI1
#define NUCLEO_SPIx_MISO_MOSI_GPIO_PORT GPIOB
#define NUCLEO_SPIx_MISO_MOSI_GPIO_CLK_ENABLE() __HAL_RCC_GPIOB_CLK_ENABLE()
#define NUCLEO_SPIx_MISO_MOSI_GPIO_CLK_DISABLE() __HAL_RCC_GPIOB_CLK_DISABLE()
```

```

#define NUCLEO_SPIx_MISO_PIN GPIO_PIN_4
#define NUCLEO_SPIx_MOSI_PIN GPIO_PIN_5
#define NUCLEO_SPIx_TIMEOUT_MAX 1000
#define SD_CS_LOW() HAL_GPIO_WritePin(SD_CS_GPIO_PORT,
SD Control Lines management.
#define SD_CS_HIGH() HAL_GPIO_WritePin(SD_CS_GPIO_PORT,
#define LCD_CS_LOW() HAL_GPIO_WritePin(LCD_CS_GPIO_PORT,
GPIO_PIN_RESET)
LCD Control Lines management.
#define LCD_CS_HIGH() HAL_GPIO_WritePin(LCD_CS_GPIO_PORT,
GPIO_PIN_SET)
#define LCD_DC_LOW() HAL_GPIO_WritePin(LCD_DC_GPIO_PORT,
GPIO_PIN_RESET)
#define LCD_DC_HIGH() HAL_GPIO_WritePin(LCD_DC_GPIO_PORT,
GPIO_PIN_SET)
#define SD_CS_PIN GPIO_PIN_5
SD Control Interface pins.
#define SD_CS_GPIO_PORT GPIOB
#define SD_CS_GPIO_CLK_ENABLE() __HAL_RCC_GPIOB_CLK_
#define SD_CS_GPIO_CLK_DISABLE() __HAL_RCC_GPIOB_CLK_
#define LCD_CS_PIN GPIO_PIN_6
LCD Control Interface pins.
#define LCD_CS_GPIO_PORT GPIOB
#define LCD_CS_GPIO_CLK_ENABLE() __HAL_RCC_GPIOB_CLK
#define LCD_CS_GPIO_CLK_DISABLE() __HAL_RCC_GPIOB_CLK
#define LCD_DC_PIN GPIO_PIN_9
LCD Data/Command Interface pins.
#define LCD_DC_GPIO_PORT GPIOA
#define LCD_DC_GPIO_CLK_ENABLE() __HAL_RCC_GPIOA_CLK
#define LCD_DC_GPIO_CLK_DISABLE() __HAL_RCC_GPIOA_CLK
#define NUCLEO_ADCx ADC1
ADC Interface pins used to detect motion of Joystick available
#define NUCLEO_ADCx_CLK_ENABLE() __HAL_RCC_ADC1_CLK
#define NUCLEO_ADCx_GPIO_PORT GPIOB

```

```
#define NUCLEO_ADCx_GPIO_PIN GPIO_PIN_0
#define NUCLEO_ADCx_GPIO_CLK_ENABLE() __HAL_RCC_GPIOC_CLK_ENABLE()
#define NUCLEO_ADCx_GPIO_CLK_DISABLE() __HAL_RCC_GPIOC_CLK_DISABLE()
```

Enumerations

```
enum  Led_TypeDef { LED3 = 0, LED_GREEN = LED3 }  
      JOYState_TypeDef {  
enum  JOY_NONE = 0, JOY_SEL = 1, JOY_DOWN = 2,  
      JOY_LEFT = 3,  
      JOY_RIGHT = 4, JOY_UP = 5  
      }
```

Functions

	void I2C1_Init (void) I2C Bus initialization.
	void I2C1_Error (void) Manages error callback by re-initializing I2C.
	void I2C1_Msplnit (I2C_HandleTypeDef *hi2c) I2C MSP Initialization.
	void I2C1_Write (uint8_t Addr, uint8_t Reg, uint8_t Value) Writes a single data.
	uint8_t I2C1_Read (uint8_t Addr, uint8_t Reg) Reads a single data.
HAL_StatusTypeDef	I2C1_WriteBuffer (uint16_t Addr, uint8_t Reg, uint16_t RegSize, uint8_t *pBuffer, uint16_t Length) Write a value in a register of the device through BUS.
HAL_StatusTypeDef	I2C1_ReadBuffer (uint16_t Addr, uint8_t Reg, uint16_t RegSize, uint8_t *pBuffer, uint16_t Length) Reads multiple data on the BUS.
HAL_StatusTypeDef	I2C1_IsDeviceReady (uint16_t DevAddress, uint32_t Trials) Checks if target device is ready for communication.
	uint32_t BSP_GetVersion (void) This method returns the STM32L0XX NUCLEO BSP Driver revision.
	void BSP_LED_Init (Led_TypeDef Led) Configures LED GPIO.
	void BSP_LED_On (Led_TypeDef Led) Turns selected LED On.

void **BSP_LED_Off** (**Led_TypeDef** Led)
Turns selected LED Off.

void **BSP_LED_Toggle** (**Led_TypeDef** Led)
Toggles the selected LED.

uint8_t **BSP_JOY_Init** (void)
Configures joystick available on adafruit 1.8" TFT shield managed through ADC to detect motion.

JOYState_TypeDef **BSP_JOY_GetState** (void)
Returns the Joystick key pressed.

Detailed Description

This file contains definitions for:

Author:

MCD Application Team

- LEDs and push-button available on STM32L0XX-Nucleo Kit from STMicroelectronics
- LCD, joystick and microSD available on Adafruit 1.8" TFT LCD shield (reference ID 802)

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Definition in file [stm32l0xx_nucleo_32.h](#).

STM32L0xx_Nucleo_32 BSP User Manual

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Modules

Here is a list of all modules:

- **BSP**
 - **NUCLEO 32**
 - **Private Defines**
 - **Private Variables**
 - **Private Function Prototypes**
 - **Private Functions**
 - **Exported Types**
 - **Exported Constants**
 - **Exported Macros**
 - **Internal Functions**
 - **Exported Functions**
 - **STM32L0XX_NUCLEO_32_LED**
 - **STM32L0XX_NUCLEO_32_BUS**
 - **STM32L0XX_NUCLEO_32_COMPONENT**

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STM32L0xx_Nucleo_32 BSP User Manual

Main Page	Modules	Files	Directories	
File List	Globals			

File List

Here is a list of all files with brief descriptions:

stm32l0xx_nucleo_32.c [code]	This file provides set of firmware functions to manage:
stm32l0xx_nucleo_32.h [code]	This file contains definitions for:

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STM32L0xx_Nucleo_32 BSP User Manual

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Directories

This directory hierarchy is sorted roughly, but not completely, alphabetically:

- **Firmware**
 - **Drivers**
 - **BSP**
 - **STM32L0xx_Nucleo_32**

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STM32L0xx_Nucleo_32 BSP User Manual

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NUCLEO 32

[BSP](#)

This file provides set of firmware functions to manage Leds and push-button available on STM32L0XX-Nucleo Kit from STMicroelectronics.

[More...](#)

Modules

Private Defines
Private Variables
Private Function Prototypes
Private Functions
Exported Types
Exported Constants

Detailed Description

This file provides set of firmware functions to manage Leds and push-button available on STM32L0XX-Nucleo Kit from STMicroelectronics.

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STM32L0xx_Nucleo_32 BSP User Manual

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Exported Constants

[NUCLEO 32](#)

Modules

Exported Macros
Internal Functions
Exported Functions
STM32L0XX_NUCLEO_32_LED
Define for STM32L0XX_NUCLEO_32 board.
STM32L0XX_NUCLEO_32_BUS
STM32L0XX_NUCLEO_32_COMPONENT

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STM32L0xx_Nucleo_32 BSP User Manual

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Private Defines

[NUCLEO 32](#)

Defines

#define	__STM32L0XX_NUCLEO_32_BSP_VERSION_MAIN	(0x01)
	STM32L0XX NUCLEO BSP Driver version number.	
#define	__STM32L0XX_NUCLEO_32_BSP_VERSION_SUB1	(0x00)
#define	__STM32L0XX_NUCLEO_32_BSP_VERSION_SUB2	(0x03)
#define	__STM32L0XX_NUCLEO_32_BSP_VERSION_RC	(0x00)
#define	__STM32L0XX_NUCLEO_32_BSP_VERSION	
#define	SD_DUMMY_BYTE	0xFF
	LINK SD Card.	
#define	SD_NO_RESPONSE_EXPECTED	0x80

Define Documentation

#define `__STM32L0XX_NUCLEO_32_BSP_VERSION`

Value:

```
((__STM32L0XX_NUCLEO_32_BSP_VERSION_MAIN << 24)\
| (__STM32L0XX_NUCLEO_32_BSP_VERSION_SUB1 << 16)\
| (__STM32L0XX_NUCLEO_32_BSP_VERSION_SUB2 << 8 )\
| (__STM32L0XX_NUCLEO_32_BSP_VERSION_RC))
```

Definition at line **62** of file `stm32l0xx_nucleo_32.c`.

Referenced by `BSP_GetVersion()`.

#define `__STM32L0XX_NUCLEO_32_BSP_VERSION_MAIN` (0x01)

STM32L0XX NUCLEO BSP Driver version number.

[31:24] main version

Definition at line **58** of file `stm32l0xx_nucleo_32.c`.

#define `__STM32L0XX_NUCLEO_32_BSP_VERSION_RC` (0x00)

[7:0] release candidate

Definition at line **61** of file `stm32l0xx_nucleo_32.c`.

#define `__STM32L0XX_NUCLEO_32_BSP_VERSION_SUB1` (0x00)

[23:16] sub1 version

Definition at line **59** of file **stm32l0xx_nucleo_32.c**.

#define __STM32L0XX_NUCLEO_32_BSP_VERSION_SUB2 (0x03)

[15:8] sub2 version

Definition at line **60** of file **stm32l0xx_nucleo_32.c**.

#define SD_DUMMY_BYTE 0xFF

LINK SD Card.

Definition at line **70** of file **stm32l0xx_nucleo_32.c**.

Referenced by **SD_IO_Init()**, and **SD_IO_WriteDummy()**.

#define SD_NO_RESPONSE_EXPECTED 0x80

Definition at line **71** of file **stm32l0xx_nucleo_32.c**.

Referenced by **SD_IO_WriteCmd()**.

STM32L0xx_Nucleo_32 BSP User Manual

[Main Page](#)[Modules](#)[Files](#)[Directories](#)[Functions](#)

Private Functions

[NUCLEO 32](#)

Functions

uint32_t	BSP_GetVersion (void) This method returns the STM32L0XX NUCLEO BSP Driver revision.
void	BSP_LED_Init (Led_TypeDef Led) Configures LED GPIO.
void	BSP_LED_On (Led_TypeDef Led) Turns selected LED On.
void	BSP_LED_Off (Led_TypeDef Led) Turns selected LED Off.
void	BSP_LED_Toggle (Led_TypeDef Led) Toggles the selected LED.
void	I2C1_Init (void) I2C Bus initialization.
void	I2C1_Write (uint8_t Addr, uint8_t Reg, uint8_t Value) Writes a single data.
uint8_t	I2C1_Read (uint8_t Addr, uint8_t Reg) Reads a single data.
HAL_StatusTypeDef	I2C1_ReadBuffer (uint16_t Addr, uint8_t Reg, uint16_t RegSize, uint8_t *pBuffer, uint16_t Length) Reads multiple data on the BUS.
HAL_StatusTypeDef	I2C1_IsDeviceReady (uint16_t DevAddress, uint32_t Trials) Checks if target device is ready for communication.
HAL_StatusTypeDef	I2C1_WriteBuffer (uint16_t Addr, uint8_t Reg, uint16_t RegSize, uint8_t *pBuffer, uint16_t Length) Write a value in a register of the device through BUS.

	void I2C1_Error (void) Manages error callback by re-initializing I2C.
	void I2C1_MspInit (I2C_HandleTypeDef *hi2c) I2C MSP Initialization.
	uint8_t BSP_JOY_Init (void) Configures joystick available on adafruit 1.8" TFT shield managed through ADC to detect motion.
JOYState_TypeDef	BSP_JOY_GetState (void) Returns the Joystick key pressed.
	static void SPIx_MspInit (SPI_HandleTypeDef *hspi) Initializes SPI MSP.
	static void SPIx_Init (void) Initializes SPI HAL.
	static uint32_t SPIx_Read (void) SPI Read 4 bytes from device.
	static void SPIx_Write (uint8_t Value) SPI Write a byte to device.
	static void SPIx_Error (void) SPI error treatment function.
	void SD_IO_Init (void) Initializes the SD Card and put it into StandBy State (Ready for data transfer).
	void SD_IO_WriteByte (uint8_t Data) Writes a byte on the SD.
	uint8_t SD_IO_ReadByte (void) Reads a byte from the SD.
HAL_StatusTypeDef	SD_IO_WriteCmd (uint8_t Cmd, uint32_t Arg, uint8_t Crc, uint8_t Response) Sends 5 bytes command to the SD card and get response.
HAL_StatusTypeDef	SD_IO_WaitResponse (uint8_t Response) Waits response from the SD card.
	void SD_IO_WriteDummy (void)

Sends dummy byte with CS High.

void **LCD_IO_Init** (void)
Initializes the LCD.

void **LCD_IO_WriteReg** (uint8_t LCDReg)
Writes command to select the LCD register.

void **LCD_IO_WriteData** (uint8_t Data)
Writes data to select the LCD register.

void **LCD_IO_WriteMultipleData** (uint8_t *pData,
uint32_t Size)
Write register value.

void **LCD_Delay** (uint32_t Delay)
Wait for loop in ms.

static void **ADCx_Msplnit** (ADC_HandleTypeDef *hadc)
Initializes ADC MSP.

static void **ADCx_Init** (void)
Initializes ADC HAL.

Function Documentation

static void [ADCx_Init](#) (void) [static]

Initializes ADC HAL.

Return values:

None

Definition at line **836** of file [stm32l0xx_nucleo_32.c](#).

References [ADCx_MsplInit\(\)](#), [hnucleo_Adc](#), and [NUCLEO_ADCx](#).

Referenced by [BSP_JOY_Init\(\)](#).

static void [ADCx_MsplInit](#) (ADC_HandleTypeDef * **hadc**) [static]

Initializes ADC MSP.

Parameters:

hadc,: ADC peripheral

Return values:

None

Definition at line **814** of file [stm32l0xx_nucleo_32.c](#).

References [NUCLEO_ADCx_CLK_ENABLE](#),
[NUCLEO_ADCx_GPIO_CLK_ENABLE](#),
[NUCLEO_ADCx_GPIO_PIN](#), and [NUCLEO_ADCx_GPIO_PORT](#).

Referenced by [ADCx_Init\(\)](#).

uint32_t [BSP_GetVersion](#) (void)

This method returns the STM32L0XX NUCLEO BSP Driver revision.

Return values:

version : 0xXYZR (8bits for each decimal, R for RC)

Definition at line **148** of file [stm32l0xx_nucleo_32.c](#).

References [__STM32L0XX_NUCLEO_32_BSP_VERSION](#).

JOYState_TypeDef BSP_JOY_GetState (void)

Returns the Joystick key pressed.

Note:

To know which Joystick key is pressed we need to detect the voltage level on each key output

- None : 3.3 V / 4095
- SEL : 1.055 V / 1308
- DOWN : 0.71 V / 88
- LEFT : 3.0 V / 3720
- RIGHT : 0.595 V / 737
- UP : 1.65 V / 2046

Return values:

JOYState_TypeDef,: Code of the Joystick key pressed.

Definition at line **896** of file [stm32l0xx_nucleo_32.c](#).

References [hnucleo_Adc](#), [JOY_DOWN](#), [JOY_LEFT](#), [JOY_NONE](#), [JOY_RIGHT](#), [JOY_SEL](#), and [JOY_UP](#).

uint8_t BSP_JOY_Init (void)

Configures joystick available on adafruit 1.8" TFT shield managed through ADC to detect motion.

Return values:

Joystickstatus (0=> success, 1=> fail)

Definition at line **867** of file **stm32l0xx_nucleo_32.c**.

References **ADCx_Init()**, **hnucleo_Adc**, and **sConfig**.

void BSP_LED_Init (Led_TypeDef Led)

Configures LED GPIO.

Parameters:

Led,: Specifies the Led to be configured. This parameter can be one of following parameters:

- LED3

Return values:

None

Definition at line **160** of file **stm32l0xx_nucleo_32.c**.

References **LED_PIN**, **LED_PORT**, and **LEDx_GPIO_CLK_ENABLE**.

void BSP_LED_Off (Led_TypeDef Led)

Turns selected LED Off.

Parameters:

Led,: Specifies the Led to be set off. This parameter can be one of following parameters:

- LED3

Return values:

None

Definition at line **196** of file [stm32l0xx_nucleo_32.c](#).

References [LED_PIN](#), and [LED_PORT](#).

void BSP_LED_On (Led_TypeDef Led)

Turns selected LED On.

Parameters:

Led,: Specifies the Led to be set on. This parameter can be one of following parameters:

- LED3

Return values:

None

Definition at line **184** of file [stm32l0xx_nucleo_32.c](#).

References [LED_PIN](#), and [LED_PORT](#).

void BSP_LED_Toggle (Led_TypeDef Led)

Toggles the selected LED.

Parameters:

Led,: Specifies the Led to be toggled. This parameter can be one of following parameters:

- LED3

Return values:

None

Definition at line **208** of file [stm32l0xx_nucleo_32.c](#).

References [LED_PIN](#), and [LED_PORT](#).

void I2C1_Error (void)

Manages error callback by re-initializing I2C.

Return values:

None

Definition at line **352** of file **stm32l0xx_nucleo_32.c**.

References **heval_I2c1**, and **I2C1_Init()**.

Referenced by **I2C1_Read()**, **I2C1_ReadBuffer()**, **I2C1_Write()**, and **I2C1_WriteBuffer()**.

void I2C1_Init (void)

I2C Bus initialization.

Return values:

None

Definition at line **223** of file **stm32l0xx_nucleo_32.c**.

References **BSP_I2C1**, **heval_I2c1**, **I2C1_MspInit()**, and **I2C1_TIMING**.

Referenced by **I2C1_Error()**.

**HAL_StatusTypeDef I2C1_IsDeviceReady (uint16_t DevAddress,
uint32_t Trials
)**

Checks if target device is ready for communication.

Note:

This function is used with Memory devices

Parameters:

DevAddress,: Target device address

Trials,: Number of trials

Return values:

HAL status

Definition at line **319** of file **stm32l0xx_nucleo_32.c**.

References **heval_I2c1**, and **I2c1Timeout**.

void I2C1_Msplnit (I2C_HandleTypeDef * hi2c)

I2C MSP Initialization.

Parameters:

hi2c,: I2C handle

Return values:

None

Definition at line **366** of file **stm32l0xx_nucleo_32.c**.

References **BSP_I2C1_CLK_ENABLE**, **BSP_I2C1_FORCE_RESET**, **BSP_I2C1_GPIO_CLK_ENABLE**, **BSP_I2C1_GPIO_PORT**, **BSP_I2C1_RELEASE_RESET**, **BSP_I2C1_SCL_PIN**, **BSP_I2C1_SCL_SDA_AF**, and **BSP_I2C1_SDA_PIN**.

Referenced by **I2C1_Init()**.

uint8_t I2C1_Read (uint8_t Addr,
uint8_t Reg

)

Reads a single data.

Parameters:

Addr,: I2C address

Reg,: Register address

Return values:

Read data

Definition at line **270** of file [stm32l0xx_nucleo_32.c](#).

References [heval_I2c1](#), and [I2C1_Error\(\)](#).

```
HAL_StatusTypeDef I2C1_ReadBuffer ( uint16_t Addr,
                                     uint8_t  Reg,
                                     uint16_t RegSize,
                                     uint8_t * pBuffer,
                                     uint16_t Length
                                     )
```

Reads multiple data on the BUS.

Parameters:

Addr : I2C Address

Reg : Reg Address

RegSize : The target register size (can be 8BIT or 16BIT)

pBuffer : pointer to read data buffer

Length : length of the data

Return values:

0 if no problems to read multiple data

Definition at line **297** of file [stm32l0xx_nucleo_32.c](#).

References [heval_I2c1](#), [I2C1_Error\(\)](#), and [I2c1Timeout](#).

```
void I2C1_Write ( uint8_t Addr,  
                  uint8_t Reg,  
                  uint8_t Value  
                )
```

Writes a single data.

Parameters:

Addr,: I2C address

Reg,: Register address

Value,: Data to be written

Return values:

None

Definition at line **250** of file [stm32l0xx_nucleo_32.c](#).

References [heval_I2c1](#), and [I2C1_Error\(\)](#).

```
HAL_StatusTypeDef I2C1_WriteBuffer ( uint16_t Addr,  
                                       uint8_t Reg,  
                                       uint16_t RegSize,  
                                       uint8_t * pBuffer,  
                                       uint16_t Length  
                                     )
```

Write a value in a register of the device through BUS.

Parameters:

Addr,: Device address on BUS Bus.

Reg,: The target register address to write
RegSize,: The target register size (can be 8BIT or 16BIT)
pBuffer,: The target register value to be written
Length,: buffer size to be written

Return values:

None

Definition at line **333** of file **stm32l0xx_nucleo_32.c**.

References **heval_I2c1**, **I2C1_Error()**, and **I2c1Timeout**.

void LCD_Delay (uint32_t Delay)

Wait for loop in ms.

Parameters:

Delay in ms.

Return values:

None

Definition at line **801** of file **stm32l0xx_nucleo_32.c**.

void LCD_IO_Init (void)

Initializes the LCD.

Return values:

None

Definition at line **678** of file **stm32l0xx_nucleo_32.c**.

References **LCD_CS_GPIO_CLK_ENABLE**, **LCD_CS_GPIO_PORT**, **LCD_CS_HIGH**, **LCD_CS_PIN**, **LCD_DC_GPIO_CLK_ENABLE**,

LCD_DC_GPIO_PORT, **LCD_DC_PIN**, and **SPIx_Init()**.

void LCD_IO_WriteData (uint8_t **Data)**

Writes data to select the LCD register.

This function must be used after **st7735_WriteReg()** function

Parameters:

Data,: data to write to the selected register.

Return values:

None

Definition at line **730** of file **stm32l0xx_nucleo_32.c**.

References **LCD_CS_HIGH**, **LCD_CS_LOW**, **LCD_DC_HIGH**, and **SPIx_Write()**.

void LCD_IO_WriteMultipleData (uint8_t * **pData,
uint32_t **Size**
)**

Write register value.

Parameters:

pData Pointer on the register value

Size Size of byte to transmit to the register

Return values:

None

Definition at line **751** of file **stm32l0xx_nucleo_32.c**.

References **hnucleo_Spi**, **LCD_CS_HIGH**, **LCD_CS_LOW**,

LCD_DC_HIGH, and **SPIx_Write()**.

void LCD_IO_WriteReg (uint8_t LCDReg)

Writes command to select the LCD register.

Parameters:

LCDReg,: Address of the selected register.

Return values:

None

Definition at line **709** of file **stm32l0xx_nucleo_32.c**.

References **LCD_CS_HIGH**, **LCD_CS_LOW**, **LCD_DC_LOW**, and **SPIx_Write()**.

void SD_IO_Init (void)

Initializes the SD Card and put it into StandBy State (Ready for data transfer).

Return values:

None

Definition at line **538** of file **stm32l0xx_nucleo_32.c**.

References **SD_CS_GPIO_CLK_ENABLE**, **SD_CS_GPIO_PORT**, **SD_CS_HIGH**, **SD_CS_PIN**, **SD_DUMMY_BYTE**, **SD_IO_WriteByte()**, and **SPIx_Init()**.

uint8_t SD_IO_ReadByte (void)

Reads a byte from the SD.

Return values:

The received byte.

Definition at line **584** of file **stm32l0xx_nucleo_32.c**.

References **SPIx_Read()**.

Referenced by **SD_IO_WaitResponse()**.

HAL_StatusTypeDef SD_IO_WaitResponse (uint8_t Response)

Waits response from the SD card.

Parameters:

Response,: Expected response from the SD card

Return values:

HAL_StatusTypeDef HAL Status

Definition at line **638** of file **stm32l0xx_nucleo_32.c**.

References **SD_IO_ReadByte()**.

Referenced by **SD_IO_WriteCmd()**.

void SD_IO_WriteByte (uint8_t Data)

Writes a byte on the SD.

Parameters:

Data,: byte to send.

Return values:

None

Definition at line **574** of file **stm32l0xx_nucleo_32.c**.

References **SPIx_Write()**.

Referenced by **SD_IO_Init()**, **SD_IO_WriteCmd()**, and **SD_IO_WriteDummy()**.

```
HAL_StatusTypeDef SD_IO_WriteCmd ( uint8_t  Cmd,  
                                   uint32_t Arg,  
                                   uint8_t  Crc,  
                                   uint8_t  Response  
                                   )
```

Sends 5 bytes command to the SD card and get response.

Parameters:

Cmd,: The user expected command to send to SD card.
Arg,: The command argument.
Crc,: The CRC.
Response,: Expected response from the SD card

Return values:

HAL_StatusTypeDef HAL Status

Definition at line **603** of file **stm32l0xx_nucleo_32.c**.

References **SD_CS_LOW**, **SD_IO_WaitResponse()**, **SD_IO_WriteByte()**, and **SD_NO_RESPONSE_EXPECTED**.

```
void SD_IO_WriteDummy ( void )
```

Sends dummy byte with CS High.

Return values:

None

Definition at line **664** of file **stm32l0xx_nucleo_32.c**.

References **SD_CS_HIGH**, **SD_DUMMY_BYTE**, and **SD_IO_WriteByte()**.

static void SPIx_Error (void) [static]

SPI error treatment function.

Return values:

None

Definition at line **519** of file **stm32l0xx_nucleo_32.c**.

References **hnucleo_Spi**, and **SPIx_Init()**.

Referenced by **SPIx_Read()**, and **SPIx_Write()**.

static void SPIx_Init (void) [static]

Initializes SPI HAL.

Return values:

None

Definition at line **443** of file **stm32l0xx_nucleo_32.c**.

References **hnucleo_Spi**, **NUCLEO_SPIx**, and **SPIx_MspInit()**.

Referenced by **LCD_IO_Init()**, **SD_IO_Init()**, and **SPIx_Error()**.

static void SPIx_MspInit (SPI_HandleTypeDef * **hspi) [static]**

Initializes SPI MSP.

Parameters:

hspl, SPI handle

Return values:

None

Definition at line 408 of file `stm32l0xx_nucleo_32.c`.

References `NUCLEO_SPIx_CLK_ENABLE`,
`NUCLEO_SPIx_MISO_MOSI_AF`,
`NUCLEO_SPIx_MISO_MOSI_GPIO_CLK_ENABLE`,
`NUCLEO_SPIx_MISO_MOSI_GPIO_PORT`,
`NUCLEO_SPIx_MISO_PIN`, `NUCLEO_SPIx_MOSI_PIN`,
`NUCLEO_SPIx_SCK_AF`,
`NUCLEO_SPIx_SCK_GPIO_CLK_ENABLE`,
`NUCLEO_SPIx_SCK_GPIO_PORT`, and `NUCLEO_SPIx_SCK_PIN`.

Referenced by `SPIx_Init()`.

static uint32_t SPIx_Read (void) [static]

SPI Read 4 bytes from device.

Return values:

Read data

Definition at line 478 of file `stm32l0xx_nucleo_32.c`.

References `hnucleo_Spi`, `SPIx_Error()`, and `SpixTimeout`.

Referenced by `SD_IO_ReadByte()`.

static void SPIx_Write (uint8_t Value) [static]

SPI Write a byte to device.

Parameters:

Value,: value to be written

Return values:

None

Definition at line **501** of file **stm32l0xx_nucleo_32.c**.

References **hnucleo_Spi**, **SPIx_Error()**, and **SpixTimeout**.

Referenced by **LCD_IO_WriteData()**, **LCD_IO_WriteMultipleData()**, **LCD_IO_WriteReg()**, and **SD_IO_WriteByte()**.

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Exported Functions

[Exported Constants](#)

Functions

uint32_t	BSP_GetVersion (void) This method returns the STM32L0XX NUCLEO BSP Driver revision.
void	BSP_LED_Init (Led_TypeDef Led) Configures LED GPIO.
void	BSP_LED_On (Led_TypeDef Led) Turns selected LED On.
void	BSP_LED_Off (Led_TypeDef Led) Turns selected LED Off.
void	BSP_LED_Toggle (Led_TypeDef Led) Toggles the selected LED.
uint8_t	BSP_JOY_Init (void) Configures joystick available on adafruit 1.8" TFT shield managed through ADC to detect motion.
JOYState_TypeDef	BSP_JOY_GetState (void) Returns the Joystick key pressed.

Function Documentation

uint32_t BSP_GetVersion (void)

This method returns the STM32L0XX NUCLEO BSP Driver revision.

Return values:

version : 0xXYZR (8bits for each decimal, R for RC)

Definition at line **148** of file **stm32l0xx_nucleo_32.c**.

References **__STM32L0XX_NUCLEO_32_BSP_VERSION**.

JOYState_TypeDef BSP_JOY_GetState (void)

Returns the Joystick key pressed.

Note:

To know which Joystick key is pressed we need to detect the voltage level on each key output

- None : 3.3 V / 4095
- SEL : 1.055 V / 1308
- DOWN : 0.71 V / 88
- LEFT : 3.0 V / 3720
- RIGHT : 0.595 V / 737
- UP : 1.65 V / 2046

Return values:

JOYState_TypeDef : Code of the Joystick key pressed.

Definition at line **896** of file **stm32l0xx_nucleo_32.c**.

References **hnucleo_Adc**, **JOY_DOWN**, **JOY_LEFT**, **JOY_NONE**, **JOY_RIGHT**, **JOY_SEL**, and **JOY_UP**.

uint8_t BSP_JOY_Init (void)

Configures joystick available on adafruit 1.8" TFT shield managed through ADC to detect motion.

Return values:

Joystickstatus (0=> success, 1=> fail)

Definition at line **867** of file **stm32l0xx_nucleo_32.c**.

References **ADCx_Init()**, **hnucleo_Adc**, and **sConfig**.

void BSP_LED_Init (Led_TypeDef Led)

Configures LED GPIO.

Parameters:

Led,: Specifies the Led to be configured. This parameter can be one of following parameters:

- LED3

Return values:

None

Definition at line **160** of file **stm32l0xx_nucleo_32.c**.

References **LED_PIN**, **LED_PORT**, and **LEDx_GPIO_CLK_ENABLE**.

void BSP_LED_Off (Led_TypeDef Led)

Turns selected LED Off.

Parameters:

Led,: Specifies the Led to be set off. This parameter can be

one of following parameters:

- LED3

Return values:

None

Definition at line **196** of file **stm32l0xx_nucleo_32.c**.

References **LED_PIN**, and **LED_PORT**.

void BSP_LED_On (Led_TypeDef Led)

Turns selected LED On.

Parameters:

Led,: Specifies the Led to be set on. This parameter can be one of following parameters:

- LED3

Return values:

None

Definition at line **184** of file **stm32l0xx_nucleo_32.c**.

References **LED_PIN**, and **LED_PORT**.

void BSP_LED_Toggle (Led_TypeDef Led)

Toggles the selected LED.

Parameters:

Led,: Specifies the Led to be toggled. This parameter can be one of following parameters:

- LED3

Return values:

None

Definition at line **208** of file **stm32l0xx_nucleo_32.c**.

References **LED_PIN**, and **LED_PORT**.

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STM32L0XX_NUCLEO_32_BUS

[Exported Constants](#)

Defines

```
#define BSP_I2C1 I2C1
#define BSP_I2C1_CLK_ENABLE() __HAL_RCC_I2C1_CLK_ENAB
#define BSP_I2C1_CLK_DISABLE() __HAL_RCC_I2C1_CLK_DISA
#define BSP_I2C1_FORCE_RESET() __HAL_RCC_I2C1_FORCE_F
#define BSP_I2C1_RELEASE_RESET() __HAL_RCC_I2C1_RELEA
#define BSP_I2C1_SCL_PIN GPIO_PIN_6 /* PB.6 add wire between
#define BSP_I2C1_SDA_PIN GPIO_PIN_7 /* PB.7 add wire between
#define BSP_I2C1_GPIO_PORT GPIOB /* GPIOB */
#define BSP_I2C1_GPIO_CLK_ENABLE() __HAL_RCC_GPIOB_CL
#define BSP_I2C1_GPIO_CLK_DISABLE() __HAL_RCC_GPIOB_C
#define BSP_I2C1_SCL_SDA_AF GPIO_AF1_I2C1
#define BSP_I2C1_TIMEOUT_MAX 1000
#define I2C1_TIMING 0x009080B5
#define NUCLEO_SPIx SPI1
#define NUCLEO_SPIx_CLK_ENABLE() __HAL_RCC_SPI1_CLK_E
#define NUCLEO_SPIx_SCK_AF GPIO_AF0_SPI1
#define NUCLEO_SPIx_SCK_GPIO_PORT GPIOA
#define NUCLEO_SPIx_SCK_PIN GPIO_PIN_11
#define NUCLEO_SPIx_SCK_GPIO_CLK_ENABLE() __HAL_RCC_
#define NUCLEO_SPIx_SCK_GPIO_CLK_DISABLE() __HAL_RCC_
#define NUCLEO_SPIx_MISO_MOSI_AF GPIO_AF0_SPI1
#define NUCLEO_SPIx_MISO_MOSI_GPIO_PORT GPIOB
#define NUCLEO_SPIx_MISO_MOSI_GPIO_CLK_ENABLE() __HAL
#define NUCLEO_SPIx_MISO_MOSI_GPIO_CLK_DISABLE() __HA
#define NUCLEO_SPIx_MISO_PIN GPIO_PIN_4
#define NUCLEO_SPIx_MOSI_PIN GPIO_PIN_5
#define NUCLEO_SPIx_TIMEOUT_MAX 1000
```


Define Documentation

#define BSP_I2C1 I2C1

Definition at line **119** of file **stm32l0xx_nucleo_32.h**.

Referenced by **I2C1_Init()**.

#define BSP_I2C1_CLK_DISABLE () __HAL_RCC_I2C1_CLK_DIS

Definition at line **121** of file **stm32l0xx_nucleo_32.h**.

#define BSP_I2C1_CLK_ENABLE () __HAL_RCC_I2C1_CLK_ENA

Definition at line **120** of file **stm32l0xx_nucleo_32.h**.

Referenced by **I2C1_MspInit()**.

#define BSP_I2C1_FORCE_RESET () __HAL_RCC_I2C1_FORCE_

Definition at line **122** of file **stm32l0xx_nucleo_32.h**.

Referenced by **I2C1_MspInit()**.

#define BSP_I2C1_GPIO_CLK_DISABLE () __HAL_RCC_GPIOB_

Definition at line **130** of file **stm32l0xx_nucleo_32.h**.

#define BSP_I2C1_GPIO_CLK_ENABLE () __HAL_RCC_GPIOB_ (

Definition at line **129** of file **stm32l0xx_nucleo_32.h**.

Referenced by [I2C1_Msplnit\(\)](#).

```
#define BSP_I2C1_GPIO_PORT  GPIOB /* GPIOB */
```

Definition at line [128](#) of file [stm32l0xx_nucleo_32.h](#).

Referenced by [I2C1_Msplnit\(\)](#).

```
#define BSP_I2C1_RELEASE_RESET ( )  __HAL_RCC_I2C1_RELEASE_RESET
```

Definition at line [123](#) of file [stm32l0xx_nucleo_32.h](#).

Referenced by [I2C1_Msplnit\(\)](#).

```
#define BSP_I2C1_SCL_PIN  GPIO_PIN_6 /* PB.6 add wire between
```

Definition at line [125](#) of file [stm32l0xx_nucleo_32.h](#).

Referenced by [I2C1_Msplnit\(\)](#).

```
#define BSP_I2C1_SCL_SDA_AF  GPIO_AF1_I2C1
```

Definition at line [131](#) of file [stm32l0xx_nucleo_32.h](#).

Referenced by [I2C1_Msplnit\(\)](#).

```
#define BSP_I2C1_SDA_PIN  GPIO_PIN_7 /* PB.7 add wire between
```

Definition at line [126](#) of file [stm32l0xx_nucleo_32.h](#).

Referenced by [I2C1_Msplnit\(\)](#).

#define BSP_I2C1_TIMEOUT_MAX 1000

Definition at line **138** of file **stm32l0xx_nucleo_32.h**.

#define I2C1_TIMING 0x009080B5

Definition at line **142** of file **stm32l0xx_nucleo_32.h**.

Referenced by **I2C1_Init()**.

#define NUCLEO_SPIx SPI1

Definition at line **148** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SPIx_Init()**.

#define NUCLEO_SPIx_CLK_ENABLE () __HAL_RCC_SPI1_CLK

Definition at line **149** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SPIx_MspInit()**.

#define NUCLEO_SPIx_MISO_MOSI_AF GPIO_AF0_SPI1

Definition at line **157** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SPIx_MspInit()**.

#define NUCLEO_SPIx_MISO_MOSI_GPIO_CLK_DISABLE () __H

Definition at line **160** of file **stm32l0xx_nucleo_32.h**.

#define NUCLEO_SPIx_MISO_MOSI_GPIO_CLK_ENABLE () __HAL_RCC_SPIx_CLK_ENABLE()

Definition at line **159** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SPIx_Msplnit()**.

#define NUCLEO_SPIx_MISO_MOSI_GPIO_PORT GPIOB

Definition at line **158** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SPIx_Msplnit()**.

#define NUCLEO_SPIx_MISO_PIN GPIO_PIN_4

Definition at line **161** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SPIx_Msplnit()**.

#define NUCLEO_SPIx_MOSI_PIN GPIO_PIN_5

Definition at line **162** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SPIx_Msplnit()**.

#define NUCLEO_SPIx_SCK_AF GPIO_AF0_SPI1

Definition at line **151** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SPIx_Msplnit()**.

#define NUCLEO_SPIx_SCK_GPIO_CLK_DISABLE () __HAL_RCC_SPIx_CLK_DISABLE()

Definition at line **155** of file **stm32l0xx_nucleo_32.h**.

```
#define NUCLEO_SPIx_SCK_GPIO_CLK_ENABLE ( ) __HAL_RCC_
```

Definition at line **154** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SPIx_MspltInit()**.

```
#define NUCLEO_SPIx_SCK_GPIO_PORT GPIOA
```

Definition at line **152** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SPIx_MspltInit()**.

```
#define NUCLEO_SPIx_SCK_PIN GPIO_PIN_11
```

Definition at line **153** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SPIx_MspltInit()**.

```
#define NUCLEO_SPIx_TIMEOUT_MAX 1000
```

Definition at line **168** of file **stm32l0xx_nucleo_32.h**.

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Private Variables

[NUCLEO 32](#)

Variables

GPIO_TypeDef *	LED_PORT [LEDn] = { LED3_GPIO_PORT }
const uint16_t	LED_PIN [LEDn] = { LED3_PIN }
uint32_t	I2c1Timeout = BSP_I2C1_TIMEOUT_MAX BUS variables.
I2C_HandleTypeDef	heval_I2c1
uint32_t	SpixTimeout = NUCLEO_SPIx_TIMEOUT_MAX
static SPI_HandleTypeDef	hnucleo_Spi
static ADC_HandleTypeDef	hnucleo_Adc
static ADC_ChannelConfTypeDef	sConfig

Variable Documentation

I2C_HandleTypeDef **heval_I2c1**

Definition at line **88** of file **stm32l0xx_nucleo_32.c**.

Referenced by **I2C1_Error()**, **I2C1_Init()**, **I2C1_IsDeviceReady()**, **I2C1_Read()**, **I2C1_ReadBuffer()**, **I2C1_Write()**, and **I2C1_WriteBuffer()**.

ADC_HandleTypeDef **hnucleo_Adc** **[static]**

Definition at line **97** of file **stm32l0xx_nucleo_32.c**.

Referenced by **ADCx_Init()**, **BSP_JOY_GetState()**, and **BSP_JOY_Init()**.

SPI_HandleTypeDef **hnucleo_Spi** **[static]**

Definition at line **93** of file **stm32l0xx_nucleo_32.c**.

Referenced by **LCD_IO_WriteMultipleData()**, **SPIx_Error()**, **SPIx_Init()**, **SPIx_Read()**, and **SPIx_Write()**.

uint32_t **I2c1Timeout** = **BSP_I2C1_TIMEOUT_MAX**

BUS variables.

Definition at line **87** of file **stm32l0xx_nucleo_32.c**.

Referenced by **I2C1_IsDeviceReady()**, **I2C1_ReadBuffer()**, and **I2C1_WriteBuffer()**.

const uint16_t LED_PIN[LEDn] = {LED3_PIN}

Definition at line **81** of file **stm32l0xx_nucleo_32.c**.

Referenced by **BSP_LED_Init()**, **BSP_LED_Off()**, **BSP_LED_On()**, and **BSP_LED_Toggle()**.

GPIO_TypeDef* LED_PORT[LEDn] = {LED3_GPIO_PORT}

Definition at line **80** of file **stm32l0xx_nucleo_32.c**.

Referenced by **BSP_LED_Init()**, **BSP_LED_Off()**, **BSP_LED_On()**, and **BSP_LED_Toggle()**.

ADC_ChannelConfTypeDef sConfig [static]

Definition at line **99** of file **stm32l0xx_nucleo_32.c**.

Referenced by **BSP_JOY_Init()**.

uint32_t SpixTimeout = NUCLEO_SPIx_TIMEOUT_MAX

Definition at line **92** of file **stm32l0xx_nucleo_32.c**.

Referenced by **SPIx_Read()**, and **SPIx_Write()**.

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Internal Functions

[Exported Constants](#)

Functions

	void I2C1_Init (void) I2C Bus initialization.
	void I2C1_Error (void) Manages error callback by re-initializing I2C.
	void I2C1_Msplnit (I2C_HandleTypeDef *hi2c) I2C MSP Initialization.
	void I2C1_Write (uint8_t Addr, uint8_t Reg, uint8_t Value) Writes a single data.
	uint8_t I2C1_Read (uint8_t Addr, uint8_t Reg) Reads a single data.
HAL_StatusTypeDef	I2C1_WriteBuffer (uint16_t Addr, uint8_t Reg, uint16_t RegSize, uint8_t *pBuffer, uint16_t Length) Write a value in a register of the device through BUS.
HAL_StatusTypeDef	I2C1_ReadBuffer (uint16_t Addr, uint8_t Reg, uint16_t RegSize, uint8_t *pBuffer, uint16_t Length) Reads multiple data on the BUS.
HAL_StatusTypeDef	I2C1_IsDeviceReady (uint16_t DevAddress, uint32_t Trials) Checks if target device is ready for communication.

Function Documentation

void I2C1_Error (void)

Manages error callback by re-initializing I2C.

Return values:

None

Definition at line **352** of file **stm32l0xx_nucleo_32.c**.

References **heval_I2c1**, and **I2C1_Init()**.

Referenced by **I2C1_Read()**, **I2C1_ReadBuffer()**, **I2C1_Write()**, and **I2C1_WriteBuffer()**.

void I2C1_Init (void)

I2C Bus initialization.

Return values:

None

Definition at line **223** of file **stm32l0xx_nucleo_32.c**.

References **BSP_I2C1**, **heval_I2c1**, **I2C1_MspInit()**, and **I2C1_TIMING**.

Referenced by **I2C1_Error()**.

**HAL_StatusTypeDef I2C1_IsDeviceReady (uint16_t DevAddress,
uint32_t Trials
)**

Checks if target device is ready for communication.

Note:

This function is used with Memory devices

Parameters:

DevAddress,: Target device address

Trials,: Number of trials

Return values:

HAL status

Definition at line **319** of file **stm32l0xx_nucleo_32.c**.

References **heval_I2c1**, and **I2c1Timeout**.

void I2C1_Msplnit (I2C_HandleTypeDef * hi2c)

I2C MSP Initialization.

Parameters:

hi2c,: I2C handle

Return values:

None

Definition at line **366** of file **stm32l0xx_nucleo_32.c**.

References **BSP_I2C1_CLK_ENABLE**, **BSP_I2C1_FORCE_RESET**, **BSP_I2C1_GPIO_CLK_ENABLE**, **BSP_I2C1_GPIO_PORT**, **BSP_I2C1_RELEASE_RESET**, **BSP_I2C1_SCL_PIN**, **BSP_I2C1_SCL_SDA_AF**, and **BSP_I2C1_SDA_PIN**.

Referenced by **I2C1_Init()**.

```
uint8_t I2C1_Read ( uint8_t Addr,  
                    uint8_t Reg  
                    )
```

Reads a single data.

Parameters:

Addr,: I2C address

Reg,: Register address

Return values:

Read data

Definition at line 270 of file [stm32l0xx_nucleo_32.c](#).

References [heval_I2c1](#), and [I2C1_Error\(\)](#).

```
HAL_StatusTypeDef I2C1_ReadBuffer ( uint16_t Addr,  
                                     uint8_t Reg,  
                                     uint16_t RegSize,  
                                     uint8_t * pBuffer,  
                                     uint16_t Length  
                                     )
```

Reads multiple data on the BUS.

Parameters:

Addr : I2C Address

Reg : Reg Address

RegSize : The target register size (can be 8BIT or 16BIT)

pBuffer : pointer to read data buffer

Length : length of the data

Return values:

0 if no problems to read multiple data

Definition at line **297** of file **stm32l0xx_nucleo_32.c**.

References **heval_I2c1**, **I2C1_Error()**, and **I2c1Timeout**.

```
void I2C1_Write ( uint8_t Addr,  
                  uint8_t Reg,  
                  uint8_t Value  
                )
```

Writes a single data.

Parameters:

Addr,: I2C address

Reg,: Register address

Value,: Data to be written

Return values:

None

Definition at line **250** of file **stm32l0xx_nucleo_32.c**.

References **heval_I2c1**, and **I2C1_Error()**.

```
HAL_StatusTypeDef I2C1_WriteBuffer ( uint16_t Addr,  
                                       uint8_t Reg,  
                                       uint16_t RegSize,  
                                       uint8_t * pBuffer,  
                                       uint16_t Length  
                                     )
```

Write a value in a register of the device through BUS.

Parameters:

Addr,: Device address on BUS Bus.
Reg,: The target register address to write
RegSize,: The target register size (can be 8BIT or 16BIT)
pBuffer,: The target register value to be written
Length,: buffer size to be written

Return values:

None

Definition at line **333** of file **stm32l0xx_nucleo_32.c**.

References **heval_I2c1**, **I2C1_Error()**, and **I2c1Timeout**.

STM32L0xx_Nucleo_32 BSP User Manual

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Exported Types

[NUCLEO 32](#)

Enumerations

```
enum  Led_TypeDef { LED3 = 0, LED_GREEN = LED3 }  
      JOYState_TypeDef {  
enum  JOY_NONE = 0, JOY_SEL = 1, JOY_DOWN = 2,  
      JOY_LEFT = 3,  
      JOY_RIGHT = 4, JOY_UP = 5  
      }
```

Enumeration Type Documentation

enum **JOYState_TypeDef**

Enumerator:

JOY_NONE
JOY_SEL
JOY_DOWN
JOY_LEFT
JOY_RIGHT
JOY_UP

Definition at line **69** of file **stm32l0xx_nucleo_32.h**.

enum **Led_TypeDef**

Enumerator:

LED3
LED_GREEN

Definition at line **63** of file **stm32l0xx_nucleo_32.h**.

STM32L0xx_Nucleo_32 BSP User Manual

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STM32L0XX_NUCLEO_32_COMPONENT

[Exported Constants](#)

Defines

#define	SD_CS_LOW() HAL_GPIO_WritePin(SD_CS_GPIO_PORT , GPIO_PIN_RESET) SD Control Lines management.
#define	SD_CS_HIGH() HAL_GPIO_WritePin(SD_CS_GPIO_PORT , GPIO_PIN_SET)
#define	LCD_CS_LOW() HAL_GPIO_WritePin(LCD_CS_GPIO_PORT , GPIO_PIN_RESET) LCD Control Lines management.
#define	LCD_CS_HIGH() HAL_GPIO_WritePin(LCD_CS_GPIO_PORT , GPIO_PIN_SET)
#define	LCD_DC_LOW() HAL_GPIO_WritePin(LCD_DC_GPIO_PORT , GPIO_PIN_RESET)
#define	LCD_DC_HIGH() HAL_GPIO_WritePin(LCD_DC_GPIO_PORT , GPIO_PIN_SET)
#define	SD_CS_PIN GPIO_PIN_5 SD Control Interface pins.
#define	SD_CS_GPIO_PORT GPIOB
#define	SD_CS_GPIO_CLK_ENABLE() __HAL_RCC_GPIOB_CLK_ENABLE()
#define	SD_CS_GPIO_CLK_DISABLE() __HAL_RCC_GPIOB_CLK_DISABLE()
#define	LCD_CS_PIN GPIO_PIN_6 LCD Control Interface pins.
#define	LCD_CS_GPIO_PORT GPIOB
#define	LCD_CS_GPIO_CLK_ENABLE() __HAL_RCC_GPIOB_CLK_ENABLE()
#define	LCD_CS_GPIO_CLK_DISABLE() __HAL_RCC_GPIOB_CLK_DISABLE()
#define	LCD_DC_PIN GPIO_PIN_9 LCD Data/Command Interface pins.
#define	LCD_DC_GPIO_PORT GPIOA
#define	LCD_DC_GPIO_CLK_ENABLE() __HAL_RCC_GPIOA_CLK_ENABLE()
#define	LCD_DC_GPIO_CLK_DISABLE() __HAL_RCC_GPIOA_CLK_DISABLE()
#define	NUCLEO_ADCx ADC1 ADC Interface pins used to detect motion of Joystick available

TFT shield.

```
#define NUCLEO_ADCx_CLK_ENABLE() __HAL_RCC_ADC1_CLK
```

```
#define NUCLEO_ADCx_GPIO_PORT GPIOB
```

```
#define NUCLEO_ADCx_GPIO_PIN GPIO_PIN_0
```

```
#define NUCLEO_ADCx_GPIO_CLK_ENABLE() __HAL_RCC_GPIOC
```

```
#define NUCLEO_ADCx_GPIO_CLK_DISABLE() __HAL_RCC_GPI
```

Define Documentation

#define LCD_CS_GPIO_CLK_DISABLE () __HAL_RCC_GPIOB_C

Definition at line **206** of file **stm32l0xx_nucleo_32.h**.

#define LCD_CS_GPIO_CLK_ENABLE () __HAL_RCC_GPIOB_C

Definition at line **205** of file **stm32l0xx_nucleo_32.h**.

Referenced by **LCD_IO_Init()**.

#define LCD_CS_GPIO_PORT GPIOB

Definition at line **204** of file **stm32l0xx_nucleo_32.h**.

Referenced by **LCD_IO_Init()**.

#define LCD_CS_HIGH () HAL_GPIO_WritePin(LCD_CS_GPIO_P

Definition at line **188** of file **stm32l0xx_nucleo_32.h**.

Referenced by **LCD_IO_Init()**, **LCD_IO_WriteData()**,
LCD_IO_WriteMultipleData(), and **LCD_IO_WriteReg()**.

#define LCD_CS_LOW () HAL_GPIO_WritePin(LCD_CS_GPIO_P

LCD Control Lines management.

Definition at line **187** of file **stm32l0xx_nucleo_32.h**.

Referenced by **LCD_IO_WriteData()**, **LCD_IO_WriteMultipleData()**,

and **LCD_IO_WriteReg()**.

#define LCD_CS_PIN GPIO_PIN_6

LCD Control Interface pins.

Definition at line **203** of file **stm32l0xx_nucleo_32.h**.

Referenced by **LCD_IO_Init()**.

#define LCD_DC_GPIO_CLK_DISABLE () __HAL_RCC_GPIOA_C

Definition at line **214** of file **stm32l0xx_nucleo_32.h**.

#define LCD_DC_GPIO_CLK_ENABLE () __HAL_RCC_GPIOA_C

Definition at line **213** of file **stm32l0xx_nucleo_32.h**.

Referenced by **LCD_IO_Init()**.

#define LCD_DC_GPIO_PORT GPIOA

Definition at line **212** of file **stm32l0xx_nucleo_32.h**.

Referenced by **LCD_IO_Init()**.

#define LCD_DC_HIGH () HAL_GPIO_WritePin(LCD_DC_GPIO_P

Definition at line **190** of file **stm32l0xx_nucleo_32.h**.

Referenced by **LCD_IO_WriteData()**, and
LCD_IO_WriteMultipleData().


```
#define LCD_DC_LOW ( ) HAL_GPIO_WritePin(LCD_DC_GPIO_PORT, LCD_DC_GPIO_PIN, GPIO_PIN_RESET)
```

Definition at line **189** of file [stm32l0xx_nucleo_32.h](#).

Referenced by [LCD_IO_WriteReg\(\)](#).

```
#define LCD_DC_PIN GPIO_PIN_9
```

LCD Data/Command Interface pins.

Definition at line **211** of file [stm32l0xx_nucleo_32.h](#).

Referenced by [LCD_IO_Init\(\)](#).

```
#define NUCLEO_ADCx ADC1
```

ADC Interface pins used to detect motion of Joystick available on Adafruit 1.8" TFT shield.

Definition at line **222** of file [stm32l0xx_nucleo_32.h](#).

Referenced by [ADCx_Init\(\)](#).

```
#define NUCLEO_ADCx_CLK_ENABLE ( ) __HAL_RCC_ADC1_CLK_ENABLE()
```

Definition at line **223** of file [stm32l0xx_nucleo_32.h](#).

Referenced by [ADCx_Msplnit\(\)](#).

```
#define NUCLEO_ADCx_GPIO_CLK_DISABLE ( ) __HAL_RCC_GPIOA_CLK_DISABLE()
```

Definition at line **228** of file [stm32l0xx_nucleo_32.h](#).

#define NUCLEO_ADCx_GPIO_CLK_ENABLE () __HAL_RCC_GF

Definition at line **227** of file **stm32l0xx_nucleo_32.h**.

Referenced by **ADCx_Msplnit()**.

#define NUCLEO_ADCx_GPIO_PIN GPIO_PIN_0

Definition at line **226** of file **stm32l0xx_nucleo_32.h**.

Referenced by **ADCx_Msplnit()**.

#define NUCLEO_ADCx_GPIO_PORT GPIOB

Definition at line **225** of file **stm32l0xx_nucleo_32.h**.

Referenced by **ADCx_Msplnit()**.

#define SD_CS_GPIO_CLK_DISABLE () __HAL_RCC_GPIOB_CL

Definition at line **198** of file **stm32l0xx_nucleo_32.h**.

#define SD_CS_GPIO_CLK_ENABLE () __HAL_RCC_GPIOB_CLI

Definition at line **197** of file **stm32l0xx_nucleo_32.h**.

Referenced by **SD_IO_Init()**.

#define SD_CS_GPIO_PORT GPIOB

Definition at line **196** of file **stm32l0xx_nucleo_32.h**.

Referenced by [SD_IO_Init\(\)](#).

```
#define SD_CS_HIGH ( ) HAL_GPIO_WritePin(SD_CS_GPIO_PORT,
```

Definition at line **182** of file [stm32l0xx_nucleo_32.h](#).

Referenced by [SD_IO_Init\(\)](#), and [SD_IO_WriteDummy\(\)](#).

```
#define SD_CS_LOW ( ) HAL_GPIO_WritePin(SD_CS_GPIO_PORT,
```

SD Control Lines management.

Definition at line **181** of file [stm32l0xx_nucleo_32.h](#).

Referenced by [SD_IO_WriteCmd\(\)](#).

```
#define SD_CS_PIN GPIO_PIN_5
```

SD Control Interface pins.

Definition at line **195** of file [stm32l0xx_nucleo_32.h](#).

Referenced by [SD_IO_Init\(\)](#).

STM32L0xx_Nucleo_32 BSP User Manual

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STM32L0XX_NUCLEO_32_LED

[Exported Constants](#)

Define for STM32L0XX_NUCLEO_32 board. [More...](#)

Defines

#define	LEDn	1
#define	LED3_PIN	GPIO_PIN_3
#define	LED3_GPIO_PORT	GPIOB
#define	LED3_GPIO_CLK_ENABLE()	__HAL_RCC_GPIOB_CLK_EN
#define	LED3_GPIO_CLK_DISABLE()	__HAL_RCC_GPIOB_CLK_D
#define	LEDx_GPIO_CLK_ENABLE(__INDEX__)	do {LED3_GPIO_CLK_ENABLE(); } while(0)
#define	LEDx_GPIO_CLK_DISABLE(__INDEX__)	LED3_GPIO_CLI

Detailed Description

Define for STM32L0XX_NUCLEO_32 board.

Define Documentation

#define LED3_GPIO_CLK_DISABLE () __HAL_RCC_GPIOB_CLK

Definition at line **102** of file [stm32l0xx_nucleo_32.h](#).

#define LED3_GPIO_CLK_ENABLE () __HAL_RCC_GPIOB_CLK

Definition at line **101** of file [stm32l0xx_nucleo_32.h](#).

#define LED3_GPIO_PORT GPIOB

Definition at line **100** of file [stm32l0xx_nucleo_32.h](#).

#define LED3_PIN GPIO_PIN_3

Definition at line **99** of file [stm32l0xx_nucleo_32.h](#).

#define LEDn 1

Definition at line **97** of file [stm32l0xx_nucleo_32.h](#).

#define LEDx_GPIO_CLK_DISABLE (__INDEX__) LED3_GPIO_C

Definition at line **105** of file [stm32l0xx_nucleo_32.h](#).

#define LEDx_GPIO_CLK_ENABLE (__INDEX__) do {LED3_GPI

Definition at line **104** of file [stm32l0xx_nucleo_32.h](#).

Referenced by **BSP_LED_Init()**.

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directory **Drivers**

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directory **BSP**

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directory **STM32L0xx_Nucleo_32**

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STM32L0xx_Nucleo_32 Directory Reference

Files

file [stm32l0xx_nucleo_32.c](#) [code]

This file provides set of firmware functions to manage:

file [stm32l0xx_nucleo_32.h](#) [code]

This file contains definitions for:

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STM32L0xx_Nucleo_32 BSP User Manual

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stm32l0xx_nucleo_32.h

[Go to the documentation of this file.](#)

```
00001  /**
00002      ****
00003      ****
00003      * @file      stm32l0xx_nucleo_32.h
00004      * @author    MCD Application Team
00005      * @brief     This file contains definitions
00006      for:
00006      *             - LEDs and push-button available on STM32L0XX-Nucleo Kit
00007      *             from STMicroelectronics
00008      *             - LCD, joystick and microSD available on Adafruit 1.8" TFT LCD
00009      *             shield (reference ID 802)
00010      ****
00010      ****
00011      * @attention
00012      *
00013      * <h2><center>&copy; COPYRIGHT(c) 2016 STMicroelectronics</center></h2>
00014      *
00015      * Redistribution and use in source and binary forms, with or without modification,
00016      * are permitted provided that the following conditions are met:
```

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HETHER IN CONTRACT, STRICT LIABILITY,
00034 * OR TORT (INCLUDING NEGLIGENCE OR OTHERWI
SE) ARISING IN ANY WAY OUT OF THE USE
00035 * OF THIS SOFTWARE, EVEN IF ADVISED OF THE
POSSIBILITY OF SUCH DAMAGE.

```

00036      *
00037      ****
00038      */
00039
00040 /* Define to prevent recursive inclusion ---
-----*/
00041 #ifndef __STM32L0XX_NUCLEO_32_H
00042 #define __STM32L0XX_NUCLEO_32_H
00043
00044 #ifdef __cplusplus
00045     extern "C" {
00046 #endif
00047
00048 /* Includes -----
-----*/
00049 #include "stm32l0xx_hal.h"
00050
00051
00052 /** @addtogroup BSP
00053     * @{
00054     */
00055
00056 /** @addtogroup STM32L0XX_NUCLEO_32 NUCLEO 32
00057     * @{
00058     */
00059
00060 /** @defgroup STM32L0XX_NUCLEO_32_Exported_T
types Exported Types
00061     * @{
00062     */
00063 typedef enum
00064 {
00065     LED3 = 0,
00066     LED_GREEN = LED3
00067 } Led_TypeDef;

```

```

00068
00069 typedef enum
00070 {
00071     JOY_NONE    = 0,
00072     JOY_SEL     = 1,
00073     JOY_DOWN    = 2,
00074     JOY_LEFT    = 3,
00075     JOY_RIGHT   = 4,
00076     JOY_UP      = 5
00077 } JOYState_TypeDef;
00078
00079 /**
00080  * @}
00081  */
00082
00083 /** @defgroup STM32L0XX_NUCLEO_32_Exported_C
onstants Exported Constants
00084  * @{
00085  */
00086
00087 /**
00088  * @brief          Define for STM32L0XX_NUCLEO_
32 board
00089  */
00090 #if !defined (USE_STM32L0XX_NUCLEO_32)
00091 #define USE_STM32L0XX_NUCLEO_32
00092 #endif
00093
00094 /** @addtogroup STM32L0XX_NUCLEO_32_LED
00095  * @{
00096  */
00097 #define LEDn                                     1
00098
00099 #define LED3_PIN                                G
PIO_PIN_3
00100 #define LED3_GPIO_PORT                          G
PIOB

```

```

00101 #define LED3_GPIO_CLK_ENABLE()          __H
AL_RCC_GPIOB_CLK_ENABLE()
00102 #define LED3_GPIO_CLK_DISABLE()          __H
AL_RCC_GPIOB_CLK_DISABLE()
00103
00104 #define LEDx_GPIO_CLK_ENABLE(__INDEX__)    d
o {LED3_GPIO_CLK_ENABLE(); } while(0)
00105 #define LEDx_GPIO_CLK_DISABLE(__INDEX__)   L
ED3_GPIO_CLK_DISABLE())
00106 /**
00107  * @}
00108  */
00109
00110
00111
00112 /** @addtogroup STM32L0XX_NUCLEO_32_BUS
00113  * @{
00114  */
00115 #if defined(HAL_I2C_MODULE_ENABLED)
00116 /**##### I2C2 #####
00117  */
00117 /* User can use this section to tailor I2Cx
instance used and associated resources */
00118 /* Definition for I2C1 Pins */
00119 #define BSP_I2C1                                I2C1
00120 #define BSP_I2C1_CLK_ENABLE()                    __HA
L_RCC_I2C1_CLK_ENABLE()
00121 #define BSP_I2C1_CLK_DISABLE()                    __HA
L_RCC_I2C1_CLK_DISABLE()
00122 #define BSP_I2C1_FORCE_RESET()                    __HA
L_RCC_I2C1_FORCE_RESET()
00123 #define BSP_I2C1_RELEASE_RESET()                  __HA
L_RCC_I2C1_RELEASE_RESET()
00124
00125 #define BSP_I2C1_SCL_PIN                          GPIO
_PIN_6      /* PB.6 add wire between D5 and A5 */
00126 #define BSP_I2C1_SDA_PIN                          GPIO

```

```

_PIN_7      /* PB.7 add wire between D4 and A4 */
00127
00128 #define BSP_I2C1_GPIO_PORT                      GPIO
B          /* GPIOB */
00129 #define BSP_I2C1_GPIO_CLK_ENABLE()              __HA
L_RCC_GPIOB_CLK_ENABLE()
00130 #define BSP_I2C1_GPIO_CLK_DISABLE()             __HA
L_RCC_GPIOB_CLK_DISABLE()
00131 #define BSP_I2C1_SCL_SDA_AF                      GPIO
_AF1_I2C1
00132
00133 /* Maximum Timeout values for flags waiting
00134    loops. These timeouts are not based
00135    on accurate values, they just guarantee t
hat the application will not remain
00136    stuck if the I2C communication is corrupt
ed.
00137    You may modify these timeout values depen
ding on CPU frequency and application
00138    conditions (interrupts routines ...). */

00138 #define BSP_I2C1_TIMEOUT_MAX                      1000
00139
00140 /* I2C TIMING is calculated in case of the I
2C Clock source is the SYSCCLK = 32 MHz */
00141 /* Set TIMING to 0x009080B5 to reach 100 KHz
speed (Rise time = 50ns, Fall time = 10ns) */
00142 #define I2C1_TIMING                              0x0
09080B5
00143
00144 #endif /* HAL_I2C_MODULE_ENABLED */
00145
00146 #if defined(HAL_SPI_MODULE_ENABLED)
00147 /*##### SPI1 #####
#####*/
00148 #define NUCLEO_SPIx
SPI1

```

```

00149 #define NUCLEO_SPIx_CLK_ENABLE()
    __HAL_RCC_SPI1_CLK_ENABLE()
00150
00151 #define NUCLEO_SPIx_SCK_AF
    GPIO_AF0_SPI1
00152 #define NUCLEO_SPIx_SCK_GPIO_PORT
    GPIOA
00153 #define NUCLEO_SPIx_SCK_PIN
    GPIO_PIN_11
00154 #define NUCLEO_SPIx_SCK_GPIO_CLK_ENABLE()
    __HAL_RCC_GPIOA_CLK_ENABLE()
00155 #define NUCLEO_SPIx_SCK_GPIO_CLK_DISABLE()
    __HAL_RCC_GPIOA_CLK_DISABLE()
00156
00157 #define NUCLEO_SPIx_MISO_MOSI_AF
    GPIO_AF0_SPI1
00158 #define NUCLEO_SPIx_MISO_MOSI_GPIO_PORT
    GPIOB
00159 #define NUCLEO_SPIx_MISO_MOSI_GPIO_CLK_ENABL
E()    __HAL_RCC_GPIOB_CLK_ENABLE()
00160 #define NUCLEO_SPIx_MISO_MOSI_GPIO_CLK_DISAB
LE()    __HAL_RCC_GPIOB_CLK_DISABLE()
00161 #define NUCLEO_SPIx_MISO_PIN
    GPIO_PIN_4
00162 #define NUCLEO_SPIx_MOSI_PIN
    GPIO_PIN_5
00163 /* Maximum Timeout values for flags waiting
loops. These timeouts are not based
00164     on accurate values, they just guarantee t
hat the application will not remain
00165     stuck if the SPI communication is corrupt
ed.
00166     You may modify these timeout values depen
ding on CPU frequency and application
00167     conditions (interrupts routines ...). */
00168 #define NUCLEO_SPIx_TIMEOUT_MAX

```

```

1000
00169 #endif /* HAL_SPI_MODULE_ENABLED */
00170 /**
00171  * @}
00172  */
00173
00174 /** @addtogroup STM32L0XX_NUCLEO_32_COMPONENT

00175  * @{
00176  */
00177
00178 /**
00179  * @brief SD Control Lines management
00180  */
00181 #define SD_CS_LOW()      HAL_GPIO_WritePin(
SD_CS_GPIO_PORT, SD_CS_PIN, GPIO_PIN_RESET)
00182 #define SD_CS_HIGH()     HAL_GPIO_WritePin(
SD_CS_GPIO_PORT, SD_CS_PIN, GPIO_PIN_SET)
00183
00184 /**
00185  * @brief LCD Control Lines management
00186  */
00187 #define LCD_CS_LOW()     HAL_GPIO_WritePin(
LCD_CS_GPIO_PORT, LCD_CS_PIN, GPIO_PIN_RESET)
00188 #define LCD_CS_HIGH()    HAL_GPIO_WritePin(
LCD_CS_GPIO_PORT, LCD_CS_PIN, GPIO_PIN_SET)
00189 #define LCD_DC_LOW()     HAL_GPIO_WritePin(
LCD_DC_GPIO_PORT, LCD_DC_PIN, GPIO_PIN_RESET)
00190 #define LCD_DC_HIGH()    HAL_GPIO_WritePin(
LCD_DC_GPIO_PORT, LCD_DC_PIN, GPIO_PIN_SET)
00191
00192 /**
00193  * @brief SD Control Interface pins
00194  */
00195 #define SD_CS_PIN
GPIO_PIN_5
00196 #define SD_CS_GPIO_PORT

```



```

        GPIOB
00197 #define SD_CS_GPIO_CLK_ENABLE()
        __HAL_RCC_GPIOB_CLK_ENABLE()
00198 #define SD_CS_GPIO_CLK_DISABLE()
        __HAL_RCC_GPIOB_CLK_DISABLE()
00199
00200 /**
00201  * @brief LCD Control Interface pins
00202  */
00203 #define LCD_CS_PIN
        GPIO_PIN_6
00204 #define LCD_CS_GPIO_PORT
        GPIOB
00205 #define LCD_CS_GPIO_CLK_ENABLE()
        __HAL_RCC_GPIOB_CLK_ENABLE()
00206 #define LCD_CS_GPIO_CLK_DISABLE()
        __HAL_RCC_GPIOB_CLK_DISABLE()
00207
00208 /**
00209  * @brief LCD Data/Command Interface pins
00210  */
00211 #define LCD_DC_PIN
        GPIO_PIN_9
00212 #define LCD_DC_GPIO_PORT
        GPIOA
00213 #define LCD_DC_GPIO_CLK_ENABLE()
        __HAL_RCC_GPIOA_CLK_ENABLE()
00214 #define LCD_DC_GPIO_CLK_DISABLE()
        __HAL_RCC_GPIOA_CLK_DISABLE()
00215
00216 #if defined(HAL_ADC_MODULE_ENABLED)
00217 /*##### ADC1 #####
00218 #####*/
00218 /**
00219  * @brief ADC Interface pins
00220  *
00221  * used to detect motion of Joystick
00222  * available on Adafruit 1.8" TFT shield

```

```

00221    */
00222 #define NUCLEO_ADCx
        ADC1
00223 #define NUCLEO_ADCx_CLK_ENABLE()
        __HAL_RCC_ADC1_CLK_ENABLE()
00224
00225 #define NUCLEO_ADCx_GPIO_PORT
        GPIOB
00226 #define NUCLEO_ADCx_GPIO_PIN
        GPIO_PIN_0
00227 #define NUCLEO_ADCx_GPIO_CLK_ENABLE()
        __HAL_RCC_GPIOB_CLK_ENABLE()
00228 #define NUCLEO_ADCx_GPIO_CLK_DISABLE()
        __HAL_RCC_GPIOB_CLK_ENABLE()
00229
00230 #endif /* HAL_ADC_MODULE_ENABLED */
00231 /**
00232  * @}
00233  */
00234
00235 /** @defgroup STM32L0XX_NUCLEO_32_Exported_M
acros Exported Macros
00236  * @{
00237  */
00238 /**
00239  * @}
00240  */
00241
00242 /** @defgroup STM32L0XX_NUCLEO_32_Internal_F
unctions Internal Functions
00243  * @{
00244  */
00245 #if defined(HAL_I2C_MODULE_ENABLED)
00246 /* I2C1 bus function */
00247 /* Link function for I2C peripherals */
00248 void                I2C1_Init(void);
00249 void                I2C1_Error (void);

```

```

00250 void                                I2C1_MspInit(I2C_HandleTy
peDef *hi2c);
00251 void                                I2C1_Write(uint8_t Addr,
uint8_t Reg, uint8_t Value);
00252 uint8_t                             I2C1_Read(uint8_t Addr, u
int8_t Reg);
00253 HAL_StatusTypeDef I2C1_WriteBuffer(uint16_t
Addr, uint8_t Reg, uint16_t RegSize, uint8_t *pBu
ffer, uint16_t Length);
00254 HAL_StatusTypeDef I2C1_ReadBuffer(uint16_t
Addr, uint8_t Reg, uint16_t RegSize, uint8_t *pBuf
fer, uint16_t Length);
00255 HAL_StatusTypeDef I2C1_IsDeviceReady(uint16
_t DevAddress, uint32_t Trials);
00256 #endif /* HAL_I2C_MODULE_ENABLED */
00257 /**
00258  * @}
00259  */
00260
00261 /** @defgroup STM32L0XX_NUCLEO_32_Exported_F
unctions Exported Functions
00262  * @{
00263  */
00264 uint32_t BSP_GetVersion(void);
00265 void BSP_LED_Init(Led_TypeDef Led
d);
00266 void BSP_LED_On(Led_TypeDef Led)
;
00267 void BSP_LED_Off(Led_TypeDef Led
);
00268 void BSP_LED_Toggle(Led_TypeDef
Led);
00269 #if defined(HAL_ADC_MODULE_ENABLED)
00270 uint8_t BSP_JOY_Init(void);
00271 JOYState_TypeDef BSP_JOY_GetState(void);
00272 #endif /* HAL_ADC_MODULE_ENABLED */
00273 /**

```

```
00274      * @}
00275      * /
00276
00277 /*
00278      * @}
00279      * /
00280
00281 /*
00282      * @}
00283      * /
00284
00285 /*
00286      * @}
00287      * /
00288
00289 #ifdef __cplusplus
00290 }
00291 #endif
00292
00293 #endif /* __STM32L0XX_NUCLEO_32_H */
00294
00295 /***** (C) COPYRIGHT STMicroelectronics *****/
00296
```

STM32L0xx_Nucleo_32 BSP User Manual

Main Page	Modules	Files	Directories	
File List	Globals			
Firmware	Drivers	BSP	STM32L0xx_Nucleo_32	

stm32l0xx_nucleo_32.c

[Go to the documentation of this file.](#)

```
00001  /**
00002      ****
00003      ****
00004      * @file      stm32l0xx_nucleo_32.c
00005      * @author    MCD Application Team
00006      * @brief     This file provides set of firmw
are functions to manage:
00007      *           - LEDs and push-button availabl
e on STM32L0XX-Nucleo Kit
00008      *           from STMicroelectronics
00009      ****
00010      ****
00011      * @attention
00012      *
00013      * <h2><center>&copy; COPYRIGHT(c) 2016 STM
icroelectronics</center></h2>
00014      *
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ary forms, with or without modification,
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SE) ARISING IN ANY WAY OUT OF THE USE

00033 * OF THIS SOFTWARE, EVEN IF ADVISED OF THE
POSSIBILITY OF SUCH DAMAGE.

00034 *

00035 *****

```

00036    */
00037
00038 /* Includes -----
-----*/
00039 #include "stm32l0xx_nucleo_32.h"
00040
00041 /** @addtogroup BSP
00042     * @{
00043     */
00044
00045 /** @addtogroup STM32L0XX_NUCLEO_32 NUCLEO 32

00046     * @brief This file provides set of firmwar
e functions to manage Leds and push-button
00047     *         available on STM32L0XX-Nucleo Kit
from STMicroelectronics.
00048     * @{
00049     */
00050
00051 /** @defgroup STM32L0XX_NUCLEO_32_Private_De
fines Private Defines
00052     * @{
00053     */
00054
00055 /**
00056     * @brief STM32L0XX NUCLEO BSP Driver versi
on number
00057     */
00058 #define __STM32L0XX_NUCLEO_32_BSP_VERSION_MA
IN    (0x01) /*!< [31:24] main version */
00059 #define __STM32L0XX_NUCLEO_32_BSP_VERSION_SU
B1    (0x00) /*!< [23:16] sub1 version */
00060 #define __STM32L0XX_NUCLEO_32_BSP_VERSION_SU
B2    (0x03) /*!< [15:8]  sub2 version */
00061 #define __STM32L0XX_NUCLEO_32_BSP_VERSION_RC
(0x00) /*!< [7:0]  release candidate */
00062 #define __STM32L0XX_NUCLEO_32_BSP_VERSION

```

```

        ((__STM32L0XX_NUCLEO_32_BSP_VERSION_MAIN <<
00063 24)\
|((__STM32L0XX_NUCLEO_32_BSP_VERSION_SUB1 << 16)\
00064 |((__STM32L0XX_NUCLEO_32_BSP_VERSION_SUB2 << 8 )\
00065 |((__STM32L0XX_NUCLEO_32_BSP_VERSION_RC))
00066
00067 /**
00068  * @brief LINK SD Card
00069  */
00070 #define SD_DUMMY_BYTE                0xFF
00071 #define SD_NO_RESPONSE_EXPECTED      0x80
00072
00073 /**
00074  * @}
00075  */
00076
00077 /** @defgroup STM32L0XX_NUCLEO_32_Private_Va
riables Private Variables
00078  * @{
00079  */
00080 GPIO_TypeDef* LED_PORT[LEDn] = {LED3_GPIO_PO
RT};
00081 const uint16_t LED_PIN[LEDn] = {LED3_PIN};
00082
00083 /**
00084  * @brief BUS variables
00085  */
00086 #if defined(HAL_I2C_MODULE_ENABLED)
00087 uint32_t I2c1Timeout = BSP_I2C1_TIMEOUT_MAX;
/*<! Value of Timeout when I2C1 communication
fails */
00088 I2C_HandleTypeDef heval_I2c1;
00089 #endif /* HAL_I2C_MODULE_ENABLED */
00090

```



```

00091 #ifdef HAL_SPI_MODULE_ENABLED
00092 uint32_t SpixTimeout = NUCLEO_SPIx_TIMEOUT_M
AX; /*<! Value of Timeout when SPI communication f
ails */
00093 static SPI_HandleTypeDef hnucleo_Spi;
00094 #endif /* HAL_SPI_MODULE_ENABLED */
00095
00096 #ifdef HAL_ADC_MODULE_ENABLED
00097 static ADC_HandleTypeDef hnucleo_Adc;
00098 /* ADC channel configuration structure decla
ration */
00099 static ADC_ChannelConfTypeDef sConfig;
00100 #endif /* HAL_ADC_MODULE_ENABLED */
00101 /**
00102  * @}
00103  */
00104
00105 /** @defgroup STM32L0XX_NUCLEO_32_Private_Fu
nction_Prototypes Private Function Prototypes
00106  * @{
00107  */
00108
00109 #ifdef HAL_SPI_MODULE_ENABLED
00110 static void SPIx_Init(void);
00111 static void SPIx_Write(uint8_t
Value);
00112 static uint32_t SPIx_Read(void);
00113 static void SPIx_Error (void);
00114 static void SPIx_MspInit(SPI_H
andleTypeDef *hspi);
00115
00116 /* SD IO functions */
00117 void SD_IO_Init(void);
00118 HAL_StatusTypeDef SD_IO_WriteCmd(uin
t8_t Cmd, uint32_t Arg, uint8_t Crc, uint8_t Respo
nse);
00119 HAL_StatusTypeDef SD_IO_WaitResponse

```

```

(uint8_t Response);
00120 void SD_IO_WriteDummy(v
oid);
00121 void SD_IO_WriteByte(ui
nt8_t Data);
00122 uint8_t SD_IO_ReadByte(void
);
00123
00124 /* LCD IO functions */
00125 void LCD_IO_Init(void);
00126 void LCD_IO_WriteData(u
int8_t Data);
00127 void LCD_IO_WriteMultip
leData(uint8_t *pData, uint32_t Size);
00128 void LCD_IO_WriteReg(ui
nt8_t LCDReg);
00129 void LCD_Delay(uint32_t
delay);
00130 #endif /* HAL_SPI_MODULE_ENABLED */
00131
00132 #ifdef HAL_ADC_MODULE_ENABLED
00133 static void ADCx_Init(void);
00134 static void ADCx_MspInit(ADC_H
andleTypeDef *hadc);
00135 #endif /* HAL_ADC_MODULE_ENABLED */
00136 /**
00137  * @}
00138  */
00139
00140 /** @defgroup STM32L0XX_NUCLEO_32_Private_Fu
nctions Private Functions
00141  * @{
00142  */
00143
00144 /**
00145  * @brief This method returns the STM32L0X
X NUCLEO BSP Driver revision

```

```

00146     * @retval version : 0xXYZR (8bits for each
    decimal, R for RC)
00147     */
00148 uint32_t BSP_GetVersion(void)
00149 {
00150     return __STM32L0XX_NUCLEO_32_BSP_VERSION;
00151 }
00152
00153 /**
00154     * @brief Configures LED GPIO.
00155     * @param Led: Specifies the Led to be con
    figured.
00156     * This parameter can be one of following
    parameters:
00157     * @arg LED3
00158     * @retval None
00159     */
00160 void BSP_LED_Init(Led_TypeDef Led)
00161 {
00162     GPIO_InitTypeDef GPIO_InitStructure;
00163
00164     /* Enable the GPIO_LED Clock */
00165     LEDx_GPIO_CLK_ENABLE(Led);
00166
00167     /* Configure the GPIO_LED pin */
00168     GPIO_InitStructure.Pin = LED_PIN[Led];
00169     GPIO_InitStructure.Mode = GPIO_MODE_OUTPUT_PP
    ;
00170     GPIO_InitStructure.Pull = GPIO_NOPULL;
00171     GPIO_InitStructure.Speed = GPIO_SPEED_FREQ_VE
    RY_HIGH;
00172
00173     HAL_GPIO_Init(LED_PORT[Led], &GPIO_InitStr
    uct);
00174     HAL_GPIO_WritePin(LED_PORT[Led], LED_PIN[L
    ed], GPIO_PIN_RESET);
00175 }

```

```

00176
00177 /**
00178  * @brief Turns selected LED On.
00179  * @param Led: Specifies the Led to be set
    on.
00180  * This parameter can be one of following
    parameters:
00181  * @arg LED3
00182  * @retval None
00183  */
00184 void BSP_LED_On(Led_TypeDef Led)
00185 {
00186     HAL_GPIO_WritePin(LED_PORT[Led], LED_PIN[L
    ed], GPIO_PIN_SET);
00187 }
00188
00189 /**
00190  * @brief Turns selected LED Off.
00191  * @param Led: Specifies the Led to be set
    off.
00192  * This parameter can be one of following
    parameters:
00193  * @arg LED3
00194  * @retval None
00195  */
00196 void BSP_LED_Off(Led_TypeDef Led)
00197 {
00198     HAL_GPIO_WritePin(LED_PORT[Led], LED_PIN[L
    ed], GPIO_PIN_RESET);
00199 }
00200
00201 /**
00202  * @brief Toggles the selected LED.
00203  * @param Led: Specifies the Led to be tog
    gled.
00204  * This parameter can be one of following
    parameters:

```

```

00205      *          @arg LED3
00206      * @retval None
00207      */
00208 void BSP_LED_Toggle(Led_TypeDef Led)
00209 {
00210     HAL_GPIO_TogglePin(LED_PORT[Led], LED_PIN[
Led]);
00211 }
00212
00213 /*****
*****
00214                                     BUS OPERATIONS
00215 *****/
00216 #if defined(HAL_I2C_MODULE_ENABLED)
00217 /***** I2C Routine
S *****/
00218
00219 /**
00220  * @brief I2C Bus initialization
00221  * @retval None
00222  */
00223 void I2C1_Init(void)
00224 {
00225     if(HAL_I2C_GetState(&heval_I2c1) == HAL_I2
C_STATE_RESET)
00226     {
00227         heval_I2c1.Instance          = BSP_I
2C1;
00228         heval_I2c1.Init.Timing       = I2C1_
TIMING;
00229         heval_I2c1.Init.OwnAddress1  = 0;
00230         heval_I2c1.Init.AddressingMode = I2C_A
DDRESSINGMODE_7BIT;
00231         heval_I2c1.Init.DualAddressMode = I2C_D
UALADDRESS_DISABLE;
00232         heval_I2c1.Init.OwnAddress2  = 0;

```

```

00233     heval_I2c1.Init.OwnAddress2Masks = I2C_O
A2_NOMASK;
00234     heval_I2c1.Init.GeneralCallMode   = I2C_G
ENERALCALL_DISABLE;
00235     heval_I2c1.Init.NoStretchMode      = I2C_N
OSTRETCH_DISABLE;
00236
00237     /* Init the I2C */
00238     I2C1_MspInit(&heval_I2c1);
00239     HAL_I2C_Init(&heval_I2c1);
00240 }
00241 }
00242
00243 /**
00244  * @brief Writes a single data.
00245  * @param Addr: I2C address
00246  * @param Reg: Register address
00247  * @param Value: Data to be written
00248  * @retval None
00249  */
00250 void I2C1_Write(uint8_t Addr, uint8_t Reg, u
int8_t Value)
00251 {
00252     HAL_StatusTypeDef status = HAL_OK;
00253
00254     status = HAL_I2C_Mem_Write(&heval_I2c1, Ad
dr, (uint16_t)Reg, I2C_MEMADD_SIZE_8BIT, &Value, 1
, 100);
00255
00256     /* Check the communication status */
00257     if(status != HAL_OK)
00258     {
00259         /* Execute user timeout callback */
00260         I2C1_Error();
00261     }
00262 }
00263

```

```

00264 /**
00265  * @brief Reads a single data.
00266  * @param Addr: I2C address
00267  * @param Reg: Register address
00268  * @retval Read data
00269  */
00270 uint8_t I2C1_Read(uint8_t Addr, uint8_t Reg)
00271 {
00272     HAL_StatusTypeDef status = HAL_OK;
00273     uint8_t Value = 0;
00274
00275     status = HAL_I2C_Mem_Read(&hval_I2c1, Addr,
00276                               Reg, I2C_MEMADD_SIZE_8BIT, &Value, 1, 1000);
00277     /* Check the communication status */
00278     if(status != HAL_OK)
00279     {
00280         /* Execute user timeout callback */
00281         I2C1_Error();
00282     }
00283     return Value;
00284 }
00285
00286
00287
00288 /**
00289  * @brief Reads multiple data on the BUS.
00290  * @param Addr : I2C Address
00291  * @param Reg : Reg Address
00292  * @param RegSize : The target register size (can be 8BIT or 16BIT)
00293  * @param pBuffer : pointer to read data buffer
00294  * @param Length : length of the data
00295  * @retval 0 if no problems to read multiple data
00296  */

```

```

00297 HAL_StatusTypeDef I2C1_ReadBuffer(uint16_t A
ddr, uint8_t Reg, uint16_t RegSize, uint8_t *pBuff
er, uint16_t Length)
00298 {
00299     HAL_StatusTypeDef status = HAL_OK;
00300
00301     status = HAL_I2C_Mem_Read(&heval_I2c1, Add
r, Reg, RegSize, pBuffer, Length, I2c1Timeout);
00302
00303     /* Check the communication status */
00304     if(status != HAL_OK)
00305     {
00306         /* Re-Initiaize the BUS */
00307         I2C1_Error();
00308     }
00309     return status;
00310 }
00311
00312 /**
00313  * @brief Checks if target device is ready
    for communication.
00314  * @note This function is used with Memor
y devices
00315  * @param DevAddress: Target device address

00316  * @param Trials: Number of trials
00317  * @retval HAL status
00318  */
00319 HAL_StatusTypeDef I2C1_IsDeviceReady(uint16_
t DevAddress, uint32_t Trials)
00320 {
00321     return (HAL_I2C_IsDeviceReady(&heval_I2c1,
DevAddress, Trials, I2c1Timeout));
00322 }
00323
00324 /**
00325  * @brief Write a value in a register of t

```


he device through BUS.

00326 * @param Addr: Device address on BUS Bus.

00327 * @param Reg: The target register address
to write

00328 * @param RegSize: The target register siz
e (can be 8BIT or 16BIT)

00329 * @param pBuffer: The target register val
ue to be written

00330 * @param Length: buffer size to be written

00331 * @retval None

00332 */

00333 HAL_StatusTypeDef I2C1_WriteBuffer(uint16_t
Addr, uint8_t Reg, uint16_t RegSize, uint8_t *pBuf
fer, uint16_t Length)

00334 {

00335 HAL_StatusTypeDef status = HAL_OK;

00336

00337 status = HAL_I2C_Mem_Write(&heval_I2c1, Ad
dr, Reg, RegSize, pBuffer, Length, I2c1Timeout);

00338

00339 /* Check the communication status */

00340 if(status != HAL_OK)

00341 {

00342 /* Re-Initiaize the BUS */

00343 I2C1_Error();

00344 }

00345 return status;

00346 }

00347

00348 /**

00349 * @brief Manages error callback by re-ini
tializing I2C.

00350 * @retval None

00351 */

00352 void I2C1_Error(void)

```

00353 {
00354     /* De-initialize the I2C communication BUS
        */
00355     HAL_I2C_DeInit(&heval_I2c1);
00356
00357     /* Re-Initiaize the I2C communication BUS
        */
00358     I2C1_Init();
00359 }
00360
00361 /**
00362  * @brief I2C MSP Initialization
00363  * @param hi2c: I2C handle
00364  * @retval None
00365  */
00366 void I2C1_MspInit(I2C_HandleTypeDef *hi2c)
00367 {
00368     GPIO_InitTypeDef GPIO_InitStruct;
00369     RCC_PeriphCLKInitTypeDef RCC_PeriphCLKInit
Struct;
00370
00371     /*##-1- Set source clock to SYSCLK for I2C
1 #####
        */
00372     RCC_PeriphCLKInitStruct.PeriphClockSelecti
on = RCC_PERIPHCLK_I2C1;
00373     RCC_PeriphCLKInitStruct.I2c1ClockSelection
= RCC_I2C1CLKSOURCE_SYSCLK;
00374     HAL_RCCEx_PeriphCLKConfig(&RCC_PeriphCLKIn
itStruct);
00375
00376     /*##-2- Configure the GPIOs #####
        #####*/
00377
00378     /* Enable GPIO clock */
00379     BSP_I2C1_GPIO_CLK_ENABLE();
00380

```

```

00381  /* Configure I2C SCL & SDA as alternate fu
nction */
00382  GPIO_InitStruct.Pin          = (BSP_I2C1_SCL_
PIN| BSP_I2C1_SDA_PIN);
00383  GPIO_InitStruct.Mode        = GPIO_MODE_AF_O
D;
00384  GPIO_InitStruct.Pull        = GPIO_NOPULL;
00385  GPIO_InitStruct.Speed       = GPIO_SPEED_FRE
Q_VERY_HIGH;
00386  GPIO_InitStruct.Alternate = BSP_I2C1_SCL_S
DA_AF;
00387  HAL_GPIO_Init(BSP_I2C1_GPIO_PORT, &GPIO_In
itStruct);
00388
00389  /*##-3- Configure the Eval I2C peripheral
#####*/
00390  /* Enable I2C clock */
00391  BSP_I2C1_CLK_ENABLE();
00392
00393  /* Force the I2C peripheral clock reset */
00394  BSP_I2C1_FORCE_RESET();
00395
00396  /* Release the I2C peripheral clock reset
*/
00397  BSP_I2C1_RELEASE_RESET();
00398 }
00399
00400 #endif /*HAL_I2C_MODULE_ENABLED*/
00401
00402 #ifdef HAL_SPI_MODULE_ENABLED
00403 /**
00404  * @brief Initializes SPI MSP.
00405  * @param hspi: SPI handle
00406  * @retval None
00407  */
00408 static void SPIx_MspInit(SPI_HandleTypeDef *
hspi)

```

```

00409 {
00410     GPIO_InitTypeDef  GPIO_InitStructure;
00411
00412     /*** Configure the GPIOs ***/
00413     /* Enable GPIO clock */
00414     NUCLEO_SPIx_SCK_GPIO_CLK_ENABLE();
00415     NUCLEO_SPIx_MISO_MOSI_GPIO_CLK_ENABLE();
00416
00417     /* Configure SPI SCK */
00418     GPIO_InitStructure.Pin = NUCLEO_SPIx_SCK_PIN;
00419     GPIO_InitStructure.Mode = GPIO_MODE_AF_PP;
00420     GPIO_InitStructure.Pull  = GPIO_PULLUP;
00421     GPIO_InitStructure.Speed = GPIO_SPEED_FREQ_VE
RY_HIGH;
00422     GPIO_InitStructure.Alternate = NUCLEO_SPIx_SC
K_AF;
00423     HAL_GPIO_Init(NUCLEO_SPIx_SCK_GPIO_PORT, &
GPIO_InitStructure);
00424
00425     /* Configure SPI MISO and MOSI */
00426     GPIO_InitStructure.Pin = NUCLEO_SPIx_MOSI_PIN
;
00427     GPIO_InitStructure.Alternate = NUCLEO_SPIx_MI
SO_MOSI_AF;
00428     GPIO_InitStructure.Pull  = GPIO_PULLDOWN;
00429     HAL_GPIO_Init(NUCLEO_SPIx_MISO_MOSI_GPIO_P
ORT, &GPIO_InitStructure);
00430
00431     GPIO_InitStructure.Pin = NUCLEO_SPIx_MISO_PIN
;
00432     HAL_GPIO_Init(NUCLEO_SPIx_MISO_MOSI_GPIO_P
ORT, &GPIO_InitStructure);
00433
00434     /*** Configure the SPI peripheral ***/
00435     /* Enable SPI clock */
00436     NUCLEO_SPIx_CLK_ENABLE();
00437 }

```

```

00438
00439 /**
00440  * @brief Initializes SPI HAL.
00441  * @retval None
00442  */
00443 static void SPIx_Init(void)
00444 {
00445     if(HAL_SPI_GetState(&hnucleo_Spi) == HAL_S
PI_STATE_RESET)
00446     {
00447         /* SPI Config */
00448         hnucleo_Spi.Instance = NUCLEO_SPIx;
00449         /* SPI baudrate is set to 8 MHz maximum (PCLK2/SPI_BaudRatePrescaler = 32/4 = 8 MHz)
00450         to verify these constraints:
00451         - ST7735 LCD SPI interface max baudrate is 15MHz for write and 6.66MHz for read
00452         Since the provided driver doesn't use read capability from LCD, only constraint
00453         on write baudrate is considered.
00454         - SD card SPI interface max baudrate is 25MHz for write/read
00455         - PCLK2 max frequency is 32 MHz
00456         */
00457         hnucleo_Spi.Init.BaudRatePrescaler = SPI
_BAUDRATEPRESCALER_4;
00458         hnucleo_Spi.Init.Direction = SPI_DIRECTI
ON_2LINES;
00459         hnucleo_Spi.Init.CLKPhase = SPI_PHASE_2E
DGE;
00460         hnucleo_Spi.Init.CLKPolarity = SPI_POLAR
ITY_HIGH;
00461         hnucleo_Spi.Init.CRCCalculation = SPI_CR
CCALCULATION_DISABLE;
00462         hnucleo_Spi.Init.CRCPolynomial = 7;
00463         hnucleo_Spi.Init.DataSize = SPI_DATASIZE
_8BIT;

```

```

00464     hnucleo_Spi.Init.FirstBit = SPI_FIRSTBIT
_MSB;
00465     hnucleo_Spi.Init.NSS = SPI_NSS_SOFT;
00466     hnucleo_Spi.Init.TIMode = SPI_TIMODE_DISABLE;
00467     hnucleo_Spi.Init.Mode = SPI_MODE_MASTER;
00468
00469     SPIx_MspInit(&hnucleo_Spi);
00470     HAL_SPI_Init(&hnucleo_Spi);
00471 }
00472 }
00473
00474 /**
00475  * @brief SPI Read 4 bytes from device
00476  * @retval Read data
00477  */
00478 static uint32_t SPIx_Read(void)
00479 {
00480     HAL_StatusTypeDef status = HAL_OK;
00481     uint32_t readvalue = 0;
00482     uint32_t writevalue = 0xFFFFFFFF;
00483
00484     status = HAL_SPI_TransmitReceive(&hnucleo_Spi, (uint8_t*) &writevalue, (uint8_t*) &readvalue, 1, SpixTimeout);
00485
00486     /* Check the communication status */
00487     if(status != HAL_OK)
00488     {
00489         /* Execute user timeout callback */
00490         SPIx_Error();
00491     }
00492
00493     return readvalue;
00494 }
00495
00496 /**

```

```

00497     * @brief SPI Write a byte to device
00498     * @param Value: value to be written
00499     * @retval None
00500     */
00501 static void SPIx_Write(uint8_t Value)
00502 {
00503     HAL_StatusTypeDef status = HAL_OK;
00504
00505     status = HAL_SPI_Transmit(&hnucleo_Spi, (uint8_t*) &Value, 1, SpixTimeout);
00506
00507     /* Check the communication status */
00508     if(status != HAL_OK)
00509     {
00510         /* Execute user timeout callback */
00511         SPIx_Error();
00512     }
00513 }
00514
00515 /**
00516     * @brief SPI error treatment function
00517     * @retval None
00518     */
00519 static void SPIx_Error (void)
00520 {
00521     /* De-initialize the SPI communication BUS
    */
00522     HAL_SPI_DeInit(&hnucleo_Spi);
00523
00524     /* Re-Initiaize the SPI communication BUS
    */
00525     SPIx_Init();
00526 }
00527
00528 /*****
    *****/
00529
    LINK OPERATIONS

```

```

00530 *****
00531 *****/
00532 /***** LINK SD *
00533 ****/
00534  * @brief  Initializes the SD Card and put
it into StandBy State (Ready for
00535  *          data transfer).
00536  * @retval None
00537  */
00538 void SD_IO_Init(void)
00539 {
00540     GPIO_InitTypeDef  GPIO_InitStructure;
00541     uint8_t counter;
00542
00543     /* SD_CS_GPIO Periph clock enable */
00544     SD_CS_GPIO_CLK_ENABLE();
00545
00546     /* Configure SD_CS_PIN pin: SD Card CS pin
    */
00547     GPIO_InitStructure.Pin = SD_CS_PIN;
00548     GPIO_InitStructure.Mode = GPIO_MODE_OUTPUT_PP
;
00549     GPIO_InitStructure.Pull = GPIO_PULLUP;
00550     GPIO_InitStructure.Speed = GPIO_SPEED_FREQ_VE
RY_HIGH;
00551     HAL_GPIO_Init(SD_CS_GPIO_PORT, &GPIO_InitS
truct);
00552
00553     /*-----Put SD in SPI mode-----
    */
00554     /* SD SPI Config */
00555     SPIx_Init();
00556
00557     /* SD chip select high */
00558     SD_CS_HIGH();

```



```

00559
00560  /* Send dummy byte 0xFF, 10 times with CS
high */
00561  /* Rise CS and MOSI for 80 clocks cycles */

00562  for (counter = 0; counter <= 9; counter++)
00563  {
00564      /* Send dummy byte 0xFF */
00565      SD_IO_WriteByte(SD_DUMMY_BYTE);
00566  }
00567 }
00568
00569 /**
00570  * @brief Writes a byte on the SD.
00571  * @param Data: byte to send.
00572  * @retval None
00573  */
00574 void SD_IO_WriteByte(uint8_t Data)
00575 {
00576     /* Send the byte */
00577     SPIx_Write(Data);
00578 }
00579
00580 /**
00581  * @brief Reads a byte from the SD.
00582  * @retval The received byte.
00583  */
00584 uint8_t SD_IO_ReadByte(void)
00585 {
00586     uint8_t data = 0;
00587
00588     /* Get the received data */
00589     data = SPIx_Read();
00590
00591     /* Return the shifted data */
00592     return data;
00593 }

```

```

00594
00595 /**
00596  * @brief Sends 5 bytes command to the SD
card and get response
00597  * @param Cmd: The user expected command t
o send to SD card.
00598  * @param Arg: The command argument.
00599  * @param Crc: The CRC.
00600  * @param Response: Expected response from
the SD card
00601  * @retval HAL_StatusTypeDef HAL Status
00602  */
00603 HAL_StatusTypeDef SD_IO_WriteCmd(uint8_t Cmd
, uint32_t Arg, uint8_t Crc, uint8_t Response)
00604 {
00605     uint32_t counter = 0x00;
00606     uint8_t frame[6];
00607
00608     /* Prepare Frame to send */
00609     frame[0] = (Cmd | 0x40);          /* Constr
uct byte 1 */
00610     frame[1] = (uint8_t)(Arg >> 24); /* Constr
uct byte 2 */
00611     frame[2] = (uint8_t)(Arg >> 16); /* Constr
uct byte 3 */
00612     frame[3] = (uint8_t)(Arg >> 8);  /* Constr
uct byte 4 */
00613     frame[4] = (uint8_t)(Arg);        /* Constr
uct byte 5 */
00614     frame[5] = (Crc);                 /* Constr
uct byte 6 */
00615
00616     /* SD chip select low */
00617     SD_CS_LOW();
00618
00619     /* Send Frame */
00620     for (counter = 0; counter < 6; counter++)

```

```

00621     {
00622         SD_IO_WriteByte(frame[counter]); /* Send
the Cmd bytes */
00623     }
00624
00625     if(Response != SD_NO_RESPONSE_EXPECTED)
00626     {
00627         return SD_IO_WaitResponse(Response);
00628     }
00629
00630     return HAL_OK;
00631 }
00632
00633 /**
00634  * @brief Waits response from the SD card
00635  * @param Response: Expected response from
the SD card
00636  * @retval HAL_StatusTypeDef HAL Status
00637  */
00638 HAL_StatusTypeDef SD_IO_WaitResponse(uint8_t
Response)
00639 {
00640     uint32_t timeout = 0xFFFF;
00641
00642     /* Check if response is got or a timeout i
s happen */
00643     while ((SD_IO_ReadByte() != Response) && t
imeout)
00644     {
00645         timeout--;
00646     }
00647
00648     if (timeout == 0)
00649     {
00650         /* After time out */
00651         return HAL_TIMEOUT;
00652     }

```

```

00653     else
00654     {
00655         /* Right response got */
00656         return HAL_OK;
00657     }
00658 }
00659
00660 /**
00661  * @brief Sends dummy byte with CS High
00662  * @retval None
00663  */
00664 void SD_IO_WriteDummy(void)
00665 {
00666     /* SD chip select high */
00667     SD_CS_HIGH();
00668
00669     /* Send Dummy byte 0xFF */
00670     SD_IO_WriteByte(SD_DUMMY_BYTE);
00671 }
00672
00673 /***** LINK LCD
***** */
00674 /**
00675  * @brief Initializes the LCD
00676  * @retval None
00677  */
00678 void LCD_IO_Init(void)
00679 {
00680     GPIO_InitTypeDef  GPIO_InitStructure;
00681
00682     /* LCD_CS_GPIO and LCD_DC_GPIO Periph clock enable */
00683     LCD_CS_GPIO_CLK_ENABLE();
00684     LCD_DC_GPIO_CLK_ENABLE();
00685
00686     /* Configure LCD_CS_PIN pin: LCD Card CS pin */

```

```

00687     GPIO_InitStruct.Pin = LCD_CS_PIN;
00688     GPIO_InitStruct.Mode = GPIO_MODE_OUTPUT_PP
;
00689     GPIO_InitStruct.Pull = GPIO_NOPULL;
00690     GPIO_InitStruct.Speed = GPIO_SPEED_FREQ_VE
RY_HIGH;
00691     HAL_GPIO_Init(LCD_CS_GPIO_PORT, &GPIO_Init
Struct);
00692
00693     /* Configure LCD_DC_PIN pin: LCD Card DC p
in */
00694     GPIO_InitStruct.Pin = LCD_DC_PIN;
00695     HAL_GPIO_Init(LCD_DC_GPIO_PORT, &GPIO_Init
Struct);
00696
00697     /* LCD chip select high */
00698     LCD_CS_HIGH();
00699
00700     /* LCD SPI Config */
00701     SPIx_Init();
00702 }
00703
00704 /**
00705  * @brief Writes command to select the LCD
    register.
00706  * @param LCDReg: Address of the selected
    register.
00707  * @retval None
00708  */
00709 void LCD_IO_WriteReg(uint8_t LCDReg)
00710 {
00711     /* Reset LCD control line CS */
00712     LCD_CS_LOW();
00713
00714     /* Set LCD data/command line DC to Low */
00715     LCD_DC_LOW();
00716

```

```

00717     /* Send Command */
00718     SPIx_Write(LCDReg);
00719
00720     /* Deselect : Chip Select high */
00721     LCD_CS_HIGH();
00722 }
00723
00724 /**
00725  * @brief Writes data to select the LCD re
gister.
00726  *          This function must be used after
st7735_WriteReg() function
00727  * @param Data: data to write to the selec
ted register.
00728  * @retval None
00729  */
00730 void LCD_IO_WriteData(uint8_t Data)
00731 {
00732     /* Reset LCD control line CS */
00733     LCD_CS_LOW();
00734
00735     /* Set LCD data/command line DC to High */
00736     LCD_DC_HIGH();
00737
00738     /* Send Data */
00739     SPIx_Write(Data);
00740
00741     /* Deselect : Chip Select high */
00742     LCD_CS_HIGH();
00743 }
00744
00745 /**
00746  * @brief Write register value.
00747  * @param pData Pointer on the register value
00748  * @param Size Size of byte to transmit to t
he register

```

```

00749 * @retval None
00750 */
00751 void LCD_IO_WriteMultipleData(uint8_t *pData
, uint32_t Size)
00752 {
00753     uint32_t counter = 0;
00754
00755     /* Reset LCD control line CS */
00756     LCD_CS_LOW();
00757
00758     /* Set LCD data/command line DC to High */
00759     LCD_DC_HIGH();
00760
00761     if (Size == 1)
00762     {
00763         /* Only 1 byte to be sent to LCD - gener
al interface can be used */
00764         /* Send Data */
00765         SPIx_Write(*pData);
00766     }
00767     else
00768     {
00769         /* Several data should be sent in a raw
*/
00770         /* Direct SPI accesses for optimization
*/
00771         for (counter = Size; counter != 0; count
er--)
00772         {
00773             while(((hnucleo_Spi.Instance->SR) & SP
I_FLAG_TXE) != SPI_FLAG_TXE)
00774             {
00775             }
00776             /* Need to invert bytes for LCD*/
00777             *((__IO uint8_t*)&hnucleo_Spi.Instance
->DR) = *(pData+1);
00778

```

```

00779         while(((hnucleo_Spi.Instance->SR) & SPI_
I_FLAG_TXE) != SPI_FLAG_TXE)
00780         {
00781         }
00782         *((__IO uint8_t*)&hnucleo_Spi.Instance
->DR) = *pData;
00783         counter--;
00784         pData += 2;
00785     }
00786
00787     /* Wait until the bus is ready before re
leasing Chip select */
00788     while(((hnucleo_Spi.Instance->SR) & SPI_
FLAG_BSY) != RESET)
00789     {
00790     }
00791 }
00792 /* Deselect : Chip Select high */
00793 LCD_CS_HIGH();
00794 }
00795
00796 /**
00797  * @brief Wait for loop in ms.
00798  * @param Delay in ms.
00799  * @retval None
00800  */
00801 void LCD_Delay(uint32_t Delay)
00802 {
00803     HAL_Delay(Delay);
00804 }
00805 #endif /* HAL_SPI_MODULE_ENABLED */
00806
00807 /***** LINK JOYSTI
CK *****/
00808 #ifdef HAL_ADC_MODULE_ENABLED
00809 /**
00810  * @brief Initializes ADC MSP.

```



```

00811     * @param hadc: ADC peripheral
00812     * @retval None
00813     */
00814 static void ADCx_MspInit(ADC_HandleTypeDef *
hadc)
00815 {
00816     GPIO_InitTypeDef  GPIO_InitStruct;
00817
00818     /*** Configure the GPIOs ***/
00819     /* Enable GPIO clock */
00820     NUCLEO_ADCx_GPIO_CLK_ENABLE();
00821
00822     /* Configure ADC1 Channel8 as analog input
    */
00823     GPIO_InitStruct.Pin = NUCLEO_ADCx_GPIO_PIN
;
00824     GPIO_InitStruct.Mode = GPIO_MODE_ANALOG;
00825     HAL_GPIO_Init(NUCLEO_ADCx_GPIO_PORT, &GPIO
_InitStruct);
00826
00827     /*** Configure the ADC peripheral ***/
00828     /* Enable ADC clock */
00829     NUCLEO_ADCx_CLK_ENABLE();
00830 }
00831
00832 /**
00833  * @brief Initializes ADC HAL.
00834  * @retval None
00835  */
00836 static void ADCx_Init(void)
00837 {
00838     if(HAL_ADC_GetState(&hnucleo_Adc) == HAL_A
DC_STATE_RESET)
00839     {
00840         /* ADC Config */
00841         hnucleo_Adc.Instance = NUCLEO_ADCx;
00842         hnucleo_Adc.Init.OversamplingMode      =

```

```

DISABLE;
00843     hnucleo_Adc.Init.ClockPrescaler      =
        ADC_CLOCK_SYNC_PCLK_DIV2; /* (must not exceed 16M
Hz) */
00844     hnucleo_Adc.Init.LowPowerAutoPowerOff  =
        DISABLE;
00845     hnucleo_Adc.Init.LowPowerFrequencyMode =
        ENABLE;
00846     hnucleo_Adc.Init.LowPowerAutoWait      =
        ENABLE;
00847     hnucleo_Adc.Init.Resolution            =
        ADC_RESOLUTION_12B;
00848     hnucleo_Adc.Init.SamplingTime          =
        ADC_SAMPLETIME_1CYCLE_5;
00849     hnucleo_Adc.Init.ScanConvMode          =
        ADC_SCAN_DIRECTION_FORWARD;
00850     hnucleo_Adc.Init.DataAlign              =
        ADC_DATAALIGN_RIGHT;
00851     hnucleo_Adc.Init.ContinuousConvMode      =
        DISABLE;
00852     hnucleo_Adc.Init.DiscontinuousConvMode  =
        DISABLE;
00853     hnucleo_Adc.Init.ExternalTrigConvEdge   =
        ADC_EXTERNALTRIGCONVEDGE_NONE;
00854     hnucleo_Adc.Init.EOCSelection           =
        ADC_EOC_SINGLE_CONV;
00855     hnucleo_Adc.Init.DMAContinuousRequests  =
        DISABLE;
00856
00857     ADCx_MspInit(&hnucleo_Adc);
00858     HAL_ADC_Init(&hnucleo_Adc);
00859 }
00860 }
00861
00862 /**
00863  * @brief Configures joystick available on
        adafruit 1.8" TFT shield

```

```

00864      *          managed through ADC to detect mo
tion.
00865      * @retval Joystickstatus (0=> success, 1=>
fail)
00866      */
00867 uint8_t BSP_JOY_Init(void)
00868 {
00869     uint8_t status = 1;
00870
00871     ADCx_Init();
00872
00873     /* Start ADC calibration */
00874     HAL_ADCEx_Calibration_Start(&hnucleo_Adc,
ADC_SINGLE_ENDED);
00875
00876     /* Select Channel 0 to be converted */
00877     sConfig.Channel = ADC_CHANNEL_8;
00878     status = HAL_ADC_ConfigChannel(&hnucleo_Adc
, &sConfig);
00879
00880     /* Return Joystick initialization status */

00881     return status;
00882 }
00883
00884 /**
00885      * @brief Returns the Joystick key pressed.

00886      * @note To know which Joystick key is pr
essed we need to detect the voltage
00887      * level on each key output
00888      * - None : 3.3 V / 4095
00889      * - SEL : 1.055 V / 1308
00890      * - DOWN : 0.71 V / 88
00891      * - LEFT : 3.0 V / 3720
00892      * - RIGHT : 0.595 V / 737
00893      * - UP : 1.65 V / 2046

```

```

00894     * @retval JOYState_TypeDef: Code of the Joystick key pressed.
00895     */
00896 JOYState_TypeDef BSP_JOY_GetState(void)
00897 {
00898     JOYState_TypeDef state;
00899     uint16_t KeyConvertedValue = 0;
00900
00901     /* Start the conversion process */
00902     HAL_ADC_Start(&hnucleo_Adc);
00903
00904     /* Wait for the end of conversion */
00905     if (HAL_ADC_PollForConversion(&hnucleo_Adc, 10) != HAL_TIMEOUT)
00906     {
00907         /* Get the converted value of regular channel */
00908         KeyConvertedValue = HAL_ADC_GetValue(&hnucleo_Adc);
00909     }
00910
00911     if((KeyConvertedValue > 2010) && (KeyConvertedValue < 2090))
00912     {
00913         state = JOY_UP;
00914     }
00915     else if((KeyConvertedValue > 680) && (KeyConvertedValue < 780))
00916     {
00917         state = JOY_RIGHT;
00918     }
00919     else if((KeyConvertedValue > 1270) && (KeyConvertedValue < 1350))
00920     {
00921         state = JOY_SEL;
00922     }
00923     else if((KeyConvertedValue > 50) && (KeyCo

```

```

nvertedValue < 130))
00924     {
00925         state = JOY_DOWN;
00926     }
00927     else if((KeyConvertedValue > 3570) && (Key
ConvertedValue < 3800))
00928     {
00929         state = JOY_LEFT;
00930     }
00931     else
00932     {
00933         state = JOY_NONE;
00934     }
00935
00936     /* Loop while a key is pressed */
00937     if(state != JOY_NONE)
00938     {
00939         KeyConvertedValue = HAL_ADC_GetValue(&h
ucleo_Adc);
00940     }
00941     /* Return the code of the Joystick key pre
ssed */
00942     return state;
00943 }
00944 #endif /* HAL_ADC_MODULE_ENABLED */
00945
00946 /**
00947  * @}
00948  */
00949
00950 /**
00951  * @}
00952  */
00953
00954 /**
00955  * @}
00956  */

```

00957

00958 /***** (C) COPYRIGHT STMicroelectronics *****/

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STM32L0xx_Nucleo_32 BSP User Manual

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BSP

Modules

NUCLEO 32

This file provides set of firmware functions to manage Leds and push-button available on STM32L0XX-Nucleo Kit from STMicroelectronics.

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