

Alpha Engine

Main Page	Classes	Files	
Class List	Class Members		

Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

 AEGfxTexture	
 AEGfxVertexList	
 AELineSegment2	
 AEMtx33	
 AEVec2	

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[Public Attributes](#) | [List of all members](#)

AEGfxTexture Struct Reference

```
#include <AEGraphics.h>
```

Public Attributes

AEGfxSurface * mpSurface
s8 mpName [256]

Detailed Description

Definition at line **82** of file **AEGraphics.h**.

Member Data Documentation

s8 AEGfxTexture::mpName[256]

Definition at line **85** of file **AEGraphics.h**.

AEGfxSurface* AEGfxTexture::mpSurface

Definition at line **84** of file **AEGraphics.h**.

The documentation for this struct was generated from the following file:

- **AEGraphics.h**

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[Public Attributes](#) | [List of all members](#)

AEGfxVertexList Struct Reference

```
#include <AEGraphics.h>
```

Public Attributes

AEGfxVertexBuffer * mpVtxBuffer
u32 vtxNum

Detailed Description

Definition at line **72** of file **AEGraphics.h**.

Member Data Documentation

AEGfxVertexBuffer* AEGfxVertexList::mpVtxBuffer

Definition at line **74** of file **AEGraphics.h**.

u32 AEGfxVertexList::vtxNum

Definition at line **75** of file **AEGraphics.h**.

The documentation for this struct was generated from the following file:

- **AEGraphics.h**

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[Public Attributes](#) | [List of all members](#)

AELineSegment2 Struct Reference

```
#include <AELineSegment2.h>
```

Public Attributes

AEVec2 **mP0**

Point on the line. [More...](#)

AEVec2 **mP1**

Point on the line. [More...](#)

AEVec2 **mN**

Line's normal. [More...](#)

float **mNdotP0**

To avoid computing it every time it's needed. [More...](#)

Detailed Description

Definition at line **22** of file **AELineSegment2.h**.

Member Data Documentation

[AETVec2](#) AELineSegment2::mN

Line's normal.

Definition at line [26](#) of file [AELineSegment2.h](#).

float AELineSegment2::mNdotP0

To avoid computing it every time it's needed.

Definition at line [27](#) of file [AELineSegment2.h](#).

[AETVec2](#) AELineSegment2::mP0

Point on the line.

Definition at line [24](#) of file [AELineSegment2.h](#).

[AETVec2](#) AELineSegment2::mP1

Point on the line.

Definition at line [25](#) of file [AELineSegment2.h](#).

The documentation for this struct was generated from the following file:

- [AELineSegment2.h](#)
-

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[Public Attributes](#) | [List of all members](#)

AEMtx33 Struct Reference

```
#include <AEMtx33.h>
```

Public Attributes

f32	m	[3][3]
------------	----------	--------

Detailed Description

Matrix is stored in column major format, ie. the translation term is in the right most column.

```
m[0][0] m[0][1] m[0][2]  
m[1][0] m[1][1] m[1][2]  
m[2][0] m[2][1] m[2][2]
```

Definition at line **36** of file **AEMtx33.h**.

Member Data Documentation

f32 AEMtx33::m[3][3]

Definition at line **38** of file **AEMtx33.h**.

The documentation for this struct was generated from the following file:

- **AEMtx33.h**
-

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[Public Attributes](#) | [List of all members](#)

AEVec2 Struct Reference

```
#include <AEVec2.h>
```

Public Attributes

f32 x
f32 y

Detailed Description

Definition at line **26** of file **AEVec2.h**.

Member Data Documentation

f32 AEVec2::x

Definition at line **28** of file **AEVec2.h**.

f32 AEVec2::y

Definition at line **28** of file **AEVec2.h**.

The documentation for this struct was generated from the following file:

- **AEVec2.h**

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Main Page	Classes	Files	
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All	Variables		

Here is a list of all class members with links to the classes they belong to:

- m : [AEMtx33](#)
- mN : [AELineSegment2](#)
- mNdotP0 : [AELineSegment2](#)
- mP0 : [AELineSegment2](#)
- mP1 : [AELineSegment2](#)
- mpName : [AEGfxTexture](#)
- mpSurface : [AEGfxTexture](#)
- mpVtxBuffer : [AEGfxVertexList](#)
- vtxNum : [AEGfxVertexList](#)
- x : [AEVec2](#)
- y : [AEVec2](#)

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All	Variables		

- m : [AEMtx33](#)
- mN : [AELineSegment2](#)
- mNdotP0 : [AELineSegment2](#)
- mP0 : [AELineSegment2](#)
- mP1 : [AELineSegment2](#)
- mpName : [AEGfxTexture](#)
- mpSurface : [AEGfxTexture](#)
- mpVtxBuffer : [AEGfxVertexList](#)
- vtxNum : [AEGfxVertexList](#)
- x : [AEVec2](#)
- y : [AEVec2](#)

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Main Page	Classes	Files
File List	File Members	

File List

Here is a list of all files with brief descriptions:

 AEEngine.h	Header file for the Alpha Engine
 AEExport.h	Header file for the library settings
 AEFrameRateController.h	Header file for the frame rate controller
 AEGameStateMgr.h	Header file for the game state manager
 AEGraphics.h	Header file for the graphics library
 AEInput.h	Header file for the input library
 AELineSegment2.h	Header file for the 2D line segment library
 AEMath.h	Header file for the math library
 AEMtx33.h	Header file for the 3x3 matrix library
 AESystem.h	Header file for the system library
 AETypes.h	Header file for the typedefs
 AEUtil.h	Header file for the utility library
 AEVec2.h	Header file for the 2D vector library

Alpha Engine

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include			

Macros

AEEngine.h File Reference

Header file for the Alpha Engine. [More...](#)

```
#include <stdlib.h> #include <stdio.h>
#include <string.h>
#include <assert.h>
#include <windows.h>
#include "AEExport.h"
#include "AETypes.h"
#include "AEMath.h"
#include "AEUtil.h"
#include "AEFrameRateController.h"
#include "AESystem.h"
#include "AEGraphics.h"
#include "AEInput.h"
#include "AEGameStateMgr.h"
```

[Go to the source code of this file.](#)

Macros

```
#define AE_ASSERT(x)
```

```
#define AE_ASSERT_MESG(x,...)
```

```
#define AE_ASSERT_PARM(x)
```

```
#define AE_ASSERT_ALLOC(x)
```

```
#define AE_WARNING(x)
```

```
#define AE_WARNING_MESG(x,...)
```

```
#define AE_WARNING_PARM(x)
```

```
#define AE_FATAL_ERROR(...)
```

Detailed Description

Header file for the Alpha Engine.

Project: Alpha Engine

Author

Sun Tjen Fam

Date

January 31, 2008

The Alpha Engine consist of the following header files:

- [AEEngine.h](#)
- [AETypes.h](#)
- [AEMath.h](#)
 - [AEVec2.h](#)
 - [AEMtx33.h](#)
 - [AELineSegment2.h](#)
- [AEUtil.h](#)
- [AEFrameRateController.h](#)
- [AESystem.h](#)
- [AEGraphcs.h](#)
- [AEInput.h](#)
- [AEGameStateMgr.h](#)

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Definition in file [AEEngine.h](#).

Macro Definition Documentation

#define AE_ASSERT (x)

Value:

```
{
    \
    if((x) == 0)
    \
    {
        \
        PRINT("AE_ASSERT: %s\nLine:
%d\nFunc: %s\nFile: %s\n",
            \
            #x, __LINE__, __FUNCTION__, __FILE__);
        \
        exit(1);
        \
    }
    \
}
```

Definition at line **52** of file **AEEngine.h**.

#define AE_ASSERT_ALLOC (x)

Value:

```
{
    \
    if((x) == 0)
    \
    {
        \
        PRINT("AE_ASSERT_ALLOC: %s\nLine:
%d\nFunc: %s\nFile: %s\n", \
```

```

        #x, __LINE__, __FUNCTION__, __FILE__);
    \
    exit(1);
    \
}
\
}

```

Definition at line **90** of file **AEEngine.h**.

```

#define AE_ASSERT_MESG ( x,
                        ...
                        )

```

Value:

```

{
    \
    if((x) == 0)
    \
    {
        \
        PRINT("AE_ASSERT_MESG: %s\nLine:
%d\nFunc: %s\nFile: %s\n", \
        #x, __LINE__, __FUNCTION__, __FILE__);
        \
        PRINT("Mesg: "__VA_ARGS__);
        \
        PRINT("\n");
        \
        exit(1);
        \
    }
    \
}

```

Definition at line **64** of file **AEEngine.h**.

#define AE_ASSERT_PARM (x)

Value:

```
{
    \
    if((x) == 0)
    \
    {
    \
        PRINT("AE_ASSERT_PARM: %s\nLine:
%d\nFunc: %s\nFile: %s\n", \
        #x, __LINE__, __FUNCTION__, __FILE__);
    \
        exit(1);
    \
    }
    \
}
```

Definition at line **78** of file **AEEngine.h**.

#define AE_FATAL_ERROR (...)

Value:

```
{
    PRINT("AE_FATAL_ERROR: " __VA_ARGS__); \
    exit(1);
}
```

Definition at line **158** of file **AEEngine.h**.

#define AE_WARNING (x)

Value:

```
{
    \
    if((x) == 0)
```

```

\
{
\
    PRINT("AE_WARNING: %s\nLine:
%d\nFunc: %s\nFile: %s\n", \
        #x, __LINE__, __FUNCTION__, __FILE__);
\
}
\
}

```

Definition at line **103** of file **AEEngine.h**.

```

#define AE_WARNING_MESG ( x,
                        ...
                        )

```

Value:

```

{
\
    if((x) == 0)
\
    {
\
        PRINT("AE_WARNING_MESG: %s\nLine:
%d\nFunc: %s\nFile: %s\n", \
            #x, __LINE__, __FUNCTION__, __FILE__);
\
        PRINT("Mesg: "__VA_ARGS__);
\
        PRINT("\n");
\
    }
\
}

```

Definition at line **114** of file **AEEngine.h**.

#define AE_WARNING_PARM (x)

Value:

```
{
    \
    if((x) == 0)
    \
    {
        \
        PRINT("AE_WARNING_PARM: %s\nLine:
%d\nFunc: %s\nFile: %s\n", \
            #x, __LINE__, __FUNCTION__, __FILE__);
    \
    }
    \
}
```

Definition at line **127** of file **AEEngine.h**.

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include			

Macros

AEEExport.h File Reference

Header file for the library settings. [More...](#)

[Go to the source code of this file.](#)

Macros

```
#define EPSILON 0.00001f
```

```
#define PI 3.1415926f
```

```
#define HALF_PI (PI * 0.5f)
```

```
#define TWO_PI (PI * 2.0f)
```

```
#define EXPORT_WINDOWS 1
```

```
#define EXPORT_ANDROID 0
```

```
#define PRINT(...) printf(__VA_ARGS__)
```

```
#define PRINT_INFO(...)
```

```
#define AE_API __declspec(dllexport)
```

```
#define DECLARE_FUNCTION_FOR_ANDROID(functionName)
```

```
#define IMPLEMENT_FUNCTION_FOR_ANDROID(functionName)
```

```
#define DECLARE_FUNCTION_FOR_ANDROID_2_INT(functionName,  
paramType1, paramType2)
```

```
#define IMPLEMENT_FUNCTION_FOR_ANDROID_2_INT(functionName,  
paramType1, paramType2)
```

Detailed Description

Header file for the library settings.

Project: Alpha Engine

Author

Antoine Abi Chacra

Date

March 21, 2013

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Definition in file [AEEExport.h](#).

Macro Definition Documentation

#define AE_API __declspec(dllexport)

Definition at line [53](#) of file [AEEExport.h](#).

**#define
DECLARE_FUNCTION_FOR_ANDROID (functionName)**

Definition at line [59](#) of file [AEEExport.h](#).

**#define
DECLARE_FUNCTION_FOR_ANDROID_2_INT (functionName,
paramType1,
paramType2
)**

Definition at line [62](#) of file [AEEExport.h](#).

#define EPSILON 0.00001f

Definition at line [21](#) of file [AEEExport.h](#).

#define EXPORT_ANDROID 0

Definition at line [33](#) of file [AEEExport.h](#).

#define EXPORT_WINDOWS 1

Definition at line **32** of file **AEEExport.h**.

```
#define HALF_PI (PI * 0.5f)
```

Definition at line **28** of file **AEEExport.h**.

```
#define  
IMPLEMENT_FUNCTION_FOR_ANDROID      ( functionName )
```

Definition at line **60** of file **AEEExport.h**.

```
#define  
IMPLEMENT_FUNCTION_FOR_ANDROID_2_INT ( functionName,  
                                     paramType1,  
                                     paramType2  
                                     )
```

Definition at line **63** of file **AEEExport.h**.

```
#define PI 3.1415926f
```

Definition at line **25** of file **AEEExport.h**.

```
#define PRINT ( ... )  printf(__VA_ARGS__)
```

Definition at line **40** of file **AEEExport.h**.

```
#define PRINT_INFO ( ... )
```

Value:

```
PRINT("File: %s\nLine: %d\nFunc: %s\n\n",
```

```
\  
  
__FILE__, __LINE__, __FUNCTION__);
```

Definition at line **46** of file **AExport.h**.

```
#define TWO_PI (PI * 2.0f)
```

Definition at line **29** of file **AExport.h**.

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[Functions](#)

AEFrameRateController.h File Reference

Header file for the frame rate controller. [More...](#)

[Go to the source code of this file.](#)

Functions

void **AEFrameRateControllerInit** (u32 FrameRateMax)
Initialize the frame rate controller. [More...](#)

void **AEFrameRateControllerReset** ()
Reset the frame rate controller. [More...](#)

void **AEFrameRateControllerStart** ()
Tell the frame rate controller that a new frame is starting.
[More...](#)

void **AEFrameRateControllerEnd** ()
Tell the frame rate controller that the current frame is ending.
[More...](#)

f64 **AEFrameRateControllerGetFrameTime** ()
Get the time for the previous frame, in seconds. [More...](#)

u32 **AEFrameRateControllerGetFrameCount** ()
Get the total number of frames elapsed. [More...](#)

Detailed Description

Header file for the frame rate controller.

Project: Alpha Engine

Author

Sun Tjen Fam

Date

April 26, 2007

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Definition in file [AEFrameRateController.h](#).

Function Documentation

void AEFramerateControllerEnd ()

Tell the frame rate controller that the current frame is ending.

Warning

This function is already called in AESysFrameEnd.

Return values

void No return

u32 AEFramerateControllerGetFrameCount ()

Get the total number of frames elapsed.

Return values

f64 Return the total number of frames elapsed.

f64 AEFramerateControllerGetFrameTime ()

Get the time for the previous frame, in seconds.

Return values

f64 Return the time for the previous frame, in seconds.

bool AEFramerateControllerInit (u32 FrameRateMax)

Initialize the frame rate controller.

Warning

This function is already called in AESysInit.

Parameters

[in] **FrameRateMax** The maximum number of frames per second.

Return values

bool Returns true

void AEFrameRateControllerReset ()

Reset the frame rate controller.

Warning

This function is already called in AESysReset.

Return values

void No return

void AEFrameRateControllerStart ()

Tell the frame rate controller that a new frame is starting.

Warning

This function is already called in AESysFrameStart.

Return values

void No return

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[Macros](#) | [Functions](#) | [Variables](#)

AEGameStateMgr.h

File Reference

Header file for the game state manager. [More...](#)

[Go to the source code of this file.](#)

Macros

#define **AE_GS_RESTART** 0xFFFFFFFFFE
Special GameState: Restart. [More...](#)

#define **AE_GS_QUIT** 0xFFFFFFFFFF
Special GameState: Quit. [More...](#)

Functions

AEGameStateMgrAdd (**u32** gameStateIdx, void(*pLoad)(), void(*pInit)(), void(*pUpdate)(), void(*pDraw)(), void(*pFree)(), void(*pUnload)())
Create a new GameState and add it to GameStateManager.
[More...](#)

void **AEGameStateMgrInit** (**u32** gameStateInit)
Initialize the GameStateManager. [More...](#)

void **AEGameStateMgrUpdate** ()
Update the GameStateManager. [More...](#)

Variables

u32 gAEGameStateInit
Initial GameState. [More...](#)

u32 gAEGameStateCurr
Current GameState. [More...](#)

u32 gAEGameStatePrev
Previous GameState. [More...](#)

u32 gAEGameStateNext
Next GameState. [More...](#)

void(* AEGameStateLoad)(void)
Function pointer for load. [More...](#)

void(* AEGameStateInit)(void)
Function pointer for init. [More...](#)

void(* AEGameStateUpdate)(void)
Function pointer for update. [More...](#)

void(* AEGameStateDraw)(void)
Function pointer for draw. [More...](#)

void(* AEGameStateFree)(void)
Function pointer for free. [More...](#)

void(* AEGameStateUnload)(void)
Function pointer for unload. [More...](#)

Detailed Description

Header file for the game state manager.

Project: Alpha Engine

Author

Sun Tjen Fam

Date

October 10, 2007

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Definition in file [AEGameStateMgr.h](#).

Macro Definition Documentation

#define AE_GS_QUIT 0xFFFFFFFF

Special GameState: Quit.

Definition at line **24** of file **AEGameStateMgr.h**.

#define AE_GS_RESTART 0xFFFFFFFFE

Special GameState: Restart.

Definition at line **23** of file **AEGameStateMgr.h**.

Function Documentation

```
void AEGameStateMgrAdd ( u32      gameStateIdx,  
                        void(*)() pLoad,  
                        void(*)() pInit,  
                        void(*)() pUpdate,  
                        void(*)() pDraw,  
                        void(*)() pFree,  
                        void(*)() pUnload  
                        )
```

Create a new GameState and add it to GameStateManager.

The new GameState is identified as **gameStateIdx** and will contain the 6 function pointers passed in.

Parameters

[in] gameStateIdx	ID of the newly created GameState.
[in] pLoad	Function pointer to the load function of the new GameState.
[in] pInit	Function pointer to the init function of the new GameState.
[in] pUpdate	Function pointer to the update function of the new GameState.
[in] pDraw	Function pointer to the draw function of the new GameState.
[in] pFree	Function pointer to the free function of the new GameState.
[in] pUnload	Function pointer to the unload function of the new GameState.

Return values

void No return.

void AEGameStateMgrInit (u32 gameStateInit)

Initialize the GameStateManager.

Set the initial GameState and start the GameStateManager with that GameState.

Warning

This function should be called AFTER all the GameStates have been added to the GameStateManager.

Parameters

[in] **gameStateInit** ID of the initial GameState.

Return values

void No return.

void AEGameStateMgrUpdate ()

Update the GameStateManager.

Call this function when the GameState changes to set the function pointers for the new state.

Return values

void No return.

Variable Documentation

void(* AEGameStateDraw)(void)

Function pointer for draw.

void(* AEGameStateFree)(void)

Function pointer for free.

void(* AEGameStateInit)(void)

Function pointer for init.

void(* AEGameStateLoad)(void)

Function pointer for load.

void(* AEGameStateUnload)(void)

Function pointer for unload.

void(* AEGameStateUpdate)(void)

Function pointer for update.

u32 gAEGameStateCurr

Current GameState.

u32 gAEGameStateInit

Initial GameState.

u32 gAEGameStateNext

Next GameState.

u32 gAEGameStatePrev

Previous GameState.

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AEGraphics.h File Reference

Header file for the graphics library. [More...](#)

[Go to the source code of this file.](#)

Classes

struct **AEGfxVertexList**

struct **AEGfxTexture**

Typedefs

```
typedef struct AEGfxVertexBuffer AEGfxVertexBuffer
```

```
typedef struct AEGfxVertexList AEGfxVertexList
```

```
typedef struct AEGfxSurface AEGfxSurface
```

```
typedef struct AEGfxTexture AEGfxTexture
```

Enumerations

enum	AEGfxRenderMode { AE_GFX_RM_NONE, AE_GFX_RM_COLOR, AE_GFX_RM_TEXTURE, AE_GFX_RM_NUM }
------	--

enum	AEGfxBlendMode { AE_GFX_BM_NONE = 0, AE_GFX_BM_BLEND, AE_GFX_BM_ADD, AE_GFX_BM_NUM }
------	---

enum	AEGfxTextureMode { AE_GFX_TM_PRECISE = 0, AE_GFX_TM_AVERAGE }
------	--

enum	AEGfxMeshDrawMode { AE_GFX_MDM_POINTS = 0, AE_GFX_MDM_LINES, AE_GFX_MDM_LINES_STRIP, AE_GFX_MDM_TRIANGLES, AE_GFX_MDM_NUM }
------	--

Functions

s32 AEGfxInit (s32 Width, s32 Height)

Initialize AEGraphics. [More...](#)

**DECLARE_FUNCTION_FOR_ANDROID_2_INT
(AEGfxInit, s32 Width, s32 Height)**

void AEGfxReset ()

Reset AEGraphics. [More...](#)

void AEGfxExit ()

Free AEGraphics. [More...](#)

void AEGfxStart ()

Tell AEGraphics that a new frame is starting.
[More...](#)

**DECLARE_FUNCTION_FOR_ANDROID
(AEGfxStart)**

void AEGfxEnd ()

Tell AEGraphics that the current frame is ending.
[More...](#)

**DECLARE_FUNCTION_FOR_ANDROID
(AEGfxEnd)**

**void AEGfxSetBackgroundColor (f32 Red, f32
Green, f32 Blue)**

Set the background colour to selected RGB
values. [More...](#)

**void AEGfxSetRenderMode (AEGfxRenderMode
RenderMode)**

Set the render mode. [More...](#)

void **AEGfxSetBlendMode** (**AEGfxBlendMode** BlendMode)
Set the blend mode. [More...](#)

f32 **AEGfxGetWinMinX** (void)
Get the minimum X world coordinate. [More...](#)

f32 **AEGfxGetWinMaxX** (void)
Get the maximum X world coordinate. [More...](#)

f32 **AEGfxGetWinMinY** (void)
Get the minimum Y world coordinate. [More...](#)

f32 **AEGfxGetWinMaxY** (void)
Get the maximum Y world coordinate. [More...](#)

void **AEGfxSetCamPosition** (**f32** X, **f32** Y)
Set the camera's X and Y position. [More...](#)

void **AEGfxGetCamPosition** (**f32** *pX, **f32** *pY)
Get the camera's X and Y position. [More...](#)

void **AEGfxSetPosition** (**f32** X, **f32** Y)
Set the position (translation) to render from. [More...](#)

void **AEGfxSetTransform** (**f32** pTransform[3][3])
Set the new global transformation matrix. [More...](#)

void **AEGfxSetTransform3D** (**f32** pTransform[4][4])
Set the new global transformation matrix. [More...](#)

void **AEGfxSetTransparency** (**f32** Alpha)
Set the new global transparency value. [More...](#)

void **AEGfxSetBlendColor** (f32 Red, f32 Green, f32 Blue, f32 Alpha)
Sets a color (RGBA) that will be used to blend with the original material. [More...](#)

void **AEGfxSetTintColor** (float Red, float Green, float Blue, float Alpha)
Sets a color (RGBA) that will be used to tint the original material. [More...](#)

void **AEGfxMeshStart** ()
Instruct AEGraphics to start creating a new mesh. [More...](#)

void **AEGfxTriAdd** (f32 x0, f32 y0, u32 c0, f32 tu0, f32 tv0, f32 x1, f32 y1, u32 c1, f32 tu1, f32 tv1, f32 x2, f32 y2, u32 c2, f32 tu2, f32 tv2)
Add a new triangle to the mesh. [More...](#)

void **AEGfxVertexAdd** (f32 x0, f32 y0, u32 c0, f32 tu0, f32 tv0)
Add a new point to the mesh. [More...](#)

AEGfxVertexList * **AEGfxMeshEnd** ()
Instruct AEGraphics to end creating of new mesh. [More...](#)

void **AEGfxMeshDraw** (AEGfxVertexList *pVertexList, AEGfxMeshDrawMode MeshDrawMode)
Draw the mesh on screen. [More...](#)

void **AEGfxMeshFree** (AEGfxVertexList *pVertexList)
Free the mesh. [More...](#)

AEGfxTexture * **AEGfxTextureLoad** (const **s8** *pFileName)
Load a texture file into memory. [More...](#)

void **AEGfxTextureSet** (**AEGfxTexture** *pTexture, **f32** offset_x, **f32** offset_y)
Set a texture to be used for rendering. [More...](#)

void **AEGfxTextureUnload** (**AEGfxTexture** *pTexture)
Unload a texture file from memory. [More...](#)

AEGfxTexture * **AEGfxTextureLoadFromMemory** (**u8** *pColors, **u32** Width, **u32** Height)
Load a texture from data in memory. [More...](#)

void **AEGfxSaveTextureToFile** (**AEGfxTexture** *pTexture, **s8** *pFileName)
Save a texture from memory to file. [More...](#)

void **AEGfxSetTextureMode** (**AEGfxTextureMode** TextureMode)
Set the texture mode. [More...](#)

void **AEGfxPoint** (**f32** x0, **f32** y0, **f32** z0, **u32** c0)
Draw a point on screen. [More...](#)

void **AEGfxLine** (**f32** x0, **f32** y0, **f32** z0, **f32** r0, **f32** g0, **f32** b0, **f32** a0, **f32** x1, **f32** y1, **f32** z1, **f32** r1, **f32** g1, **f32** b1, **f32** a1)
Draw a line on screen. [More...](#)

void **AEGfxTri** (**f32** x0, **f32** y0, **f32** z0, **u32** c0, **f32** x1, **f32** y1, **f32** z1, **u32** c1, **f32** x2, **f32** y2, **f32** z2, **u32** c2)
Draw a triangle on screen. [More...](#)

AEGfxQuad (**f32** x0, **f32** y0, **f32** z0, **u32** c0, **f32**

void **x1, f32 y1, f32 z1, u32 c1, f32 x2, f32 y2, f32 z2, u32 c2, f32 x3, f32 y3, f32 z3, u32 c3)**

Draw a rectangle on screen. [More...](#)

void **AEGfxBox (f32 x0, f32 y0, f32 z0, f32 sizeX, f32 sizeY, f32 sizeZ, u32 c0, u32 c1)**

Draw a 3D box on screen. [More...](#)

void **AEGfxSphere (f32 x0, f32 y0, f32 z0, f32 radius, u32 c0, u32 c1, u32 division)**

Draw a 3D sphere on screen. [More...](#)

void **AEGfxCone (f32 x0, f32 y0, f32 z0, f32 x1, f32 y1, f32 z1, f32 radius, u32 c0, u32 c1, u32 division)**

Draw a 3D cone on screen. [More...](#)

void **AEGfxAxis (f32 scale)**

Draw a 3D axis on screen. [More...](#)

u32 AEGfxColInterp (u32 c0, u32 c1, f32 t)

Get the interpolation between two colours (c0 and c1) at time interval t. [More...](#)

void **AEGfxPrint (s32 x, s32 y, u32 color, s8 *pStr)**

Render text onto the screen. [More...](#)

Detailed Description

Header file for the graphics library.

Project: Alpha Engine

Author

Sun Tjen Fam

Date

January 30, 2008

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Definition in file [AEGraphics.h](#).

Typedef Documentation

typedef struct [AEGfxSurface](#) AEGfxSurface

Definition at line **80** of file [AEGraphics.h](#).

typedef struct [AEGfxTexture](#) AEGfxTexture

typedef struct [AEGfxVertexBuffer](#) AEGfxVertexBuffer

Definition at line **70** of file [AEGraphics.h](#).

typedef struct [AEGfxVertexList](#) AEGfxVertexList

Enumeration Type Documentation

enum AEGfxBlendMode

AEEngine blend option

Enumerator	
<i>AE_GFX_BM_NONE</i>	No blending.
<i>AE_GFX_BM_BLEND</i>	Color blending.
<i>AE_GFX_BM_ADD</i>	Additive blending.
<i>AE_GFX_BM_NUM</i>	

Definition at line **37** of file **AEGraphics.h**.

enum AEGfxMeshDrawMode

Enumerator	
<i>AE_GFX_MDM_POINTS</i>	
<i>AE_GFX_MDM_LINES</i>	
<i>AE_GFX_MDM_LINES_STRIP</i>	
<i>AE_GFX_MDM_TRIANGLES</i>	
<i>AE_GFX_MDM_NUM</i>	

Definition at line **56** of file **AEGraphics.h**.

enum AEGfxRenderMode

AEEngine render option

Enumerator	

<i>AE_GFX_RM_NONE</i>	No render.
<i>AE_GFX_RM_COLOR</i>	Color rendering.
<i>AE_GFX_RM_TEXTURE</i>	Texture rendering.
<i>AE_GFX_RM_NUM</i>	

Definition at line **24** of file **AEGraphics.h**.

enum **AEGfxTextureMode**

Enumerator	
<i>AE_GFX_TM_PRECISE</i>	
<i>AE_GFX_TM_AVERAGE</i>	

Definition at line **48** of file **AEGraphics.h**.

Function Documentation

void AEGfxAxis (f32 scale)

Draw a 3D axis on screen.

The axis is rendered on the center of the screen with size scale.

Warning

Do not call this function when AEGraphics is building mesh.

Function may be slow. Use with caution.

Parameters

[in] **scale** Size of the axis

Return values

void No return.

```
void AEGfxBox ( f32 x0,  
                f32 y0,  
                f32 z0,  
                f32 sizeX,  
                f32 sizeY,  
                f32 sizeZ,  
                u32 c0,  
                u32 c1  
                )
```

Draw a 3D box on screen.

The box is centered around the point (x0, y0, z0) and sizeX, sizeY and sizeZ are the width, height and depth. c0 and c1 are the box color. Default values are white and grey.

Warning

Do not call this function when AEGraphics is building mesh.
Function may be slow. Use with caution.

Parameters

[in] **x0** X coordinate of the center of the box
[in] **y0** Y coordinate of the center of the box
[in] **z0** Z coordinate of the center of the box
[in] **sizeX** Width of the box
[in] **sizeY** Height of the box
[in] **sizeZ** Depth of the box
[in] **c0** First color of the box.
[in] **c1** Second color of the box.

Return values

void No return.

```
u32 AEGfxColInterp ( u32 c0,  
                     u32 c1,  
                     f32 t  
                     )
```

Get the interpolation between two colours (c0 and c1) at time interval t.

Warning

t should be between 0.0f to 1.0f.

Parameters

[in] **c0** The first colour.
[in] **c1** The second colour.
[in] **t** The time interval to calculate the interpolation at. At t = 0.0f, the result will be c0. At t = 1.0f, the result will be c1.

Return values

void No return.

```
void AEGfxCone ( f32 x0,  
                 f32 y0,  
                 f32 z0,  
                 f32 x1,  
                 f32 y1,  
                 f32 z1,  
                 f32 radius,  
                 u32 c0,  
                 u32 c1,  
                 u32 division  
                )
```

Draw a 3D cone on screen.

The base of the cone is centered around the point (x0, y0, z0) with size radius. The tip of the cone is at point(x1, y1, z1). c0 and c1 are the sphere color. Default colors are white and grey. Division is the resolution of the cone, or how many parts the cone consists of. Default value is 8.

Warning

This function is not implemented.

Do not call this function when AEGraphics is building mesh.

Function may be slow. Use with caution.

Parameters

[in] x0	X coordinate of the center of the base of cone
[in] y0	Y coordinate of the center of the base of cone
[in] z0	Z coordinate of the tip of cone
[in] x1	X coordinate of the tip of cone
[in] y1	Y coordinate of the tip of cone
[in] z1	Z coordinate of the tip of cone
[in] radius	Radius of the cone

[in] **c0** First color of the cone.
[in] **c1** Second color of the cone.
[in] **division** Number of parts to divide the cone by.

Return values

void No return.

void AEGfxEnd ()

Tell AEGraphics that the current frame is ending.

Warning

This function is already called in AESysFrameEnd.

Return values

void No return.

void AEGfxExit ()

Free AEGraphics.

Warning

This function is already called in AESysExit.

Return values

void No return.

void AEGfxGetCamPosition (f32 * pX, f32 * pY)

Get the camera's X and Y position.

Parameters

[out] **pX** Pointer to f32 to store the X position in.
[out] **pY** Pointer to f32 to store the Y position in.

Return values

void No return.

f32 AEGfxGetWinMaxX (void)

Get the maximum X world coordinate.

Return values

f32 Returns the maximum X world coordinate.

f32 AEGfxGetWinMaxY (void)

Get the maximum Y world coordinate.

Return values

f32 Returns the maximum Y world coordinate.

f32 AEGfxGetWinMinX (void)

Get the minimum X world coordinate.

Return values

f32 Returns the minimum X world coordinate.

f32 AEGfxGetWinMinY (void)

Get the minimum Y world coordinate.

Return values

f32 Returns the minimum Y world coordinate.

```
s32 AEGfxInit ( s32 Width,  
                s32 Height  
                )
```

Initialize AEGraphics.

Warning

This function is already called in AESysInit.

Parameters

[in] **Width** Set the width of the window.

[in] **Height** Set the height of the window.

Return values

s32 Return 1 if initialization is successful. Else return 0.

```
void AEGfxLine ( f32 x0,  
                 f32 y0,  
                 f32 z0,  
                 f32 r0,  
                 f32 g0,  
                 f32 b0,  
                 f32 a0,  
                 f32 x1,  
                 f32 y1,  
                 f32 z1,  
                 f32 r1,  
                 f32 g1,  
                 f32 b1,  
                 f32 a1  
                 )
```

Draw a line on screen.

The line is defined by 2 points: pt0 and pt1.

Warning

Do not call this function when AEGraphics is building mesh.
Function may be slow. Use with caution.

Parameters

- [in] **x0** X coordinate of pt0
- [in] **y0** Y coordinate of pt0
- [in] **z0** Z coordinate of pt0
- [in] **r0** Percentage of red of pt0. Range from 0.0f to 1.0f.
- [in] **g0** Percentage of green of pt0. Range from 0.0f to 1.0f.
- [in] **b0** Percentage of blue of pt0. Range from 0.0f to 1.0f.
- [in] **a0** Percentage of alpha (transparency) of pt0. Range from 0.0f (clear) to 1.0f (opaque).
- [in] **x1** X coordinate of pt1
- [in] **y1** Y coordinate of pt1
- [in] **z1** Z coordinate of pt1
- [in] **r1** Percentage of red of pt1. Range from 0.0f to 1.0f.
- [in] **g1** Percentage of green of pt1. Range from 0.0f to 1.0f.
- [in] **b1** Percentage of blue of pt1. Range from 0.0f to 1.0f.
- [in] **a1** Percentage of alpha (transparency) of pt1. Range from 0.0f (clear) to 1.0f (opaque).

Return values

void No return.

```
void AEGfxMeshDraw ( AEGfxVertexList *      pVertexList,  
                    AEGfxMeshDrawMode MeshDrawMode  
                    )
```

Draw the mesh on screen.

Render the mesh onto the screen using the MeshDrawMode stated.

Parameters

- [in] **pVertexList** Pointer to the **AEGfxVertexList** to be rendered.
- [in] **MeshDrawMode** The AEGfxMeshDrawMode to use for rendering the mesh.

Return values

void No return.

AEGfxVertexList * AEGfxMeshEnd ()

Instruct AEGraphics to end creating of new mesh.

Call this function once after all the points have been added to the mesh.

Return values

AEGfxVertexList* Returns a **AEGfxVertexList** pointer to the new mesh.

void AEGfxMeshFree (AEGfxVertexList * pVertexList)

Free the mesh.

Release the mesh from AEGraphics memory. The mesh is destroyed and can no longer be used.

Parameters

- [in] **pVertexList** Pointer to the **AEGfxVertexList** to be free.

Return values

void No return.

void AEGfxMeshStart ()

Instruct AEGraphics to start creating a new mesh.

Call this function once before adding any points to the mesh.

Return values

void No return.

```
void AEGfxPoint ( f32 x0,  
                  f32 y0,  
                  f32 z0,  
                  u32 c0  
                  )
```

Draw a point on screen.

The point is defined by x0, y0, z0 with color c0.

Warning

Do not call this function when AEGraphics is building mesh.
Function may be slow. Use with caution.

Parameters

[in] **x0** X coordinate of point
[in] **y0** Y coordinate of point
[in] **z0** Z coordinate of point
[in] **c0** Color value of point

Return values

void No return.

```
void AEGfxPrint ( s32 x,  
                  s32 y,  
                  u32 color,  
                  s8 * pStr  
                  )
```

Render text onto the screen.

Render a null-terminated string of text (pStr) onto the screen starting at the point(x, y) using the color set.

Parameters

- [in] **x** X coordinate to start rendering the text from. This is given in terms of actual windows coordinates.
- [in] **y** X coordinate to start rendering the text from. This is given in terms of actual windows coordinates.
- [in] **color** The color to render the text with.
- [in] **pStr** Pointer to a NULL-terminated string containing the text to be rendered onto the screen.

Return values

void No return.

```
void AEGfxQuad ( f32 x0,  
                 f32 y0,  
                 f32 z0,  
                 u32 c0,  
                 f32 x1,  
                 f32 y1,  
                 f32 z1,  
                 u32 c1,  
                 f32 x2,  
                 f32 y2,  
                 f32 z2,  
                 u32 c2,  
                 f32 x3,  
                 f32 y3,  
                 f32 z3,  
                 u32 c3  
                 )
```

Draw a rectangle on screen.

The rectangle is defined by 4 points: pt0, pt1, pt2 and pt3. The points are listed in a counter-clockwise order.

Warning

Do not call this function when AEGraphics is building mesh.
Function may be slow. Use with caution.

Parameters

[in] **x0** X coordinate of pt0
[in] **y0** Y coordinate of pt0
[in] **z0** Z coordinate of pt0
[in] **c0** Color value of pt0
[in] **x1** X coordinate of pt1
[in] **y1** Y coordinate of pt1
[in] **z1** Z coordinate of pt1
[in] **c1** Color value of pt1
[in] **x2** X coordinate of pt2
[in] **y2** Y coordinate of pt2
[in] **z2** Z coordinate of pt2
[in] **c2** Color value of pt2
[in] **x3** X coordinate of pt3
[in] **y3** Y coordinate of pt3
[in] **z3** Z coordinate of pt3
[in] **c3** Color value of pt3

Return values

void No return.

void AEGfxReset ()

Reset AEGraphics.

Warning

This function is already called in AESysReset.

Return values

void No return.

```
void AEGfxSaveTextureToFile ( AEGfxTexture * pTexture,  
                             s8 * pFileName  
                             )
```

Save a texture from memory to file.

Parameters

- [in] **pTexture** Pointer to **AEGfxTexture** to be saved.
- [in] **pFileName** Pointer to a null-terminated string containing the relative path of the file.

Return values

void No return.

```
void AEGfxSetBackgroundColor ( f32 Red,  
                              f32 Green,  
                              f32 Blue  
                              )
```

Set the background colour to selected RGB values.

Parameters

- [in] **Red** Percentage of red. Range from 0.0f to 1.0f.
- [in] **Green** Percentage of green. Range from 0.0f to 1.0f.
- [in] **Blue** Percentage of blue. Range from 0.0f to 1.0f.

Return values

void No return.

```
void AEGfxSetBlendColor ( f32 Red,  
                          f32 Green,  
                          f32 Blue,
```

f32 Alpha
)

Sets a color (RGBA) that will be used to blend with the original material.

Parameters

- [in] **Red** Percentage of red. Range from 0.0f to 1.0f.
- [in] **Green** Percentage of green. Range from 0.0f to 1.0f.
- [in] **Blue** Percentage of blue. Range from 0.0f to 1.0f.
- [in] **Alpha** Percentage of alpha (transparency). Range from 0.0f (clear) to 1.0f (opaque).

Return values

void No return.

void AEGfxSetBlendMode (AEGfxBlendMode BlendMode)

Set the blend mode.

Parameters

- [in] **BlendMode** The AEGfxBlendMode to set.

Return values

void No return.

**void AEGfxSetCamPosition (f32 X,
f32 Y
)**

Set the camera's X and Y position.

Parameters

- [in] **X** X position to set camera to.
- [in] **Y** Y position to set camera to.

Return values

void No return.

```
void AEGfxSetPosition ( f32 X,  
                        f32 Y  
                        )
```

Set the position (translation) to render from.

Parameters

[in] **X** X position to render from.

[out] **Y** Y position to render from.

Return values

void No return.

```
void AEGfxSetRenderMode ( AEGfxRenderMode RenderMode )
```

Set the render mode.

Warning

This function should be called at least once per frame, before any rendering is done.

Parameters

[in] **RenderMode** The AEGfxRenderMode to set.

Return values

void No return.

```
void AEGfxSetTextureMode ( AEGfxTextureMode TextureMode )
```

Set the texture mode.

Parameters

[in] **TextureMode** The AEGfxTextureMode to set.

Return values

void No return.

```
void AEGfxSetTintColor ( float Red,  
                        float Green,  
                        float Blue,  
                        float Alpha  
                        )
```

Sets a color (RGBA) that will be used to tint the original material.

Parameters

[in] **Red** Percentage of red. Range from 0.0f to 1.0f.

[in] **Green** Percentage of green. Range from 0.0f to 1.0f.

[in] **Blue** Percentage of blue. Range from 0.0f to 1.0f.

[in] **Alpha** Percentage of alpha (transparency). Range from 0.0f (clear) to 1.0f (opaque).

Return values

void No return.

```
void AEGfxSetTransform ( f32 pTransform[3][3] )
```

Set the new global transformation matrix.

The new matrix will be applied to all object drawn after this function was called.

Parameters

[in] **pTransform** Pointer to a 3x3 matrix to set with. User may pass in a **AEMtx33.m**.

Return values

void No return.

void AEGfxSetTransform3D (f32 pTransform[4][4])

Set the new global transformation matrix.

The new matrix will be applied to all object drawn after this function was called.

Parameters

[in] **pTransform** Pointer to a 4x4 matrix to set with.

Return values

void No return.

void AEGfxSetTransparency (f32 Alpha)

Set the new global transparency value.

The new transparency value will be applied to all object drawn after this function was called.

Parameters

[in] **Alpha** Percentage of alpha (transparency). Range from 0.0f (clear) to 1.0f (opaque).

Return values

void No return.

**void AEGfxSphere (f32 x0,
f32 y0,
f32 z0,
f32 radius,
u32 c0,**

```
    u32 c1,  
    u32 division  
)
```

Draw a 3D sphere on screen.

The sphere is centered around the point (x0, y0, z0) with size radius. c0 and c1 are the sphere color. Default colors are white and grey. Division is the resolution, or how many parts the sphere consists of. Default value is 8.

Warning

Do not call this function when AEGraphics is building mesh.
Function may be slow. Use with caution.

Parameters

[in] x0	X coordinate of the center of the sphere
[in] y0	Y coordinate of the center of the sphere
[in] z0	Z coordinate of the center of the sphere
[in] radius	Radius of the sphere
[in] c0	First color of the sphere.
[in] c1	Second color of the sphere.
[in] division	Number of parts to divide the sphere by.

Return values

void No return.

void AEGfxStart ()

Tell AEGraphics that a new frame is starting.

Warning

This function is already called in AESysFrameStart.

Return values

void No return.

AEGfxTexture * AEGfxTextureLoad (const s8 * pFileName)

Load a texture file into memory.

Parameters

[in] **pFileName** Pointer to a null-terminated string containing the relative path of the file to be loaded.

Return values

AEGfxTexture* Returns a **AEGfxTexture** pointer to the loaded texture.

**AEGfxTexture * AEGfxTextureLoadFromMemory (u8 * pColors,
u32 Width,
u32 Height
)**

Load a texture from data in memory.

Parameters

[in] **pColors** Pointer to an array containing the data.

[in] **Width** The width of the texture.

[in] **Height** The height of the texture.

Return values

AEGfxTexture* Returns a **AEGfxTexture** pointer to the loaded texture.

**void AEGfxTextureSet (AEGfxTexture * pTexture,
f32 offset_x,
f32 offset_y
)**

Set a texture to be used for rendering.

Parameters

- [in] **pTexture** Pointer to the **AEGfxTexture** to be used. Set to null if not using texture.
- [in] **offset_x** X offset for the texture. Range from 0.0f to 1.0f.
- [in] **offset_y** Y offset for the texture. Range from 0.0f to 1.0f.

Return values

void No return.

void AEGfxTextureUnload (AEGfxTexture * pTexture)

Unload a texture file from memory.

Parameters

- [in] **pTexture** Pointer to **AEGfxTexture** to be unloaded.

Return values

void No return.

```
void AEGfxTri ( f32 x0,  
               f32 y0,  
               f32 z0,  
               u32 c0,  
               f32 x1,  
               f32 y1,  
               f32 z1,  
               u32 c1,  
               f32 x2,  
               f32 y2,  
               f32 z2,  
               u32 c2
```

Draw a triangle on screen.

The triangle is defined by 3 points: pt0, pt1 and pt2. The points are listed in a counter-clockwise order.

Warning

Do not call this function when AEGraphics is building mesh.

Function may be slow. Use with caution.

Parameters

```
[in] x0 X coordinate of pt0
```

```
[in] y0 Y coordinate of pt0
```

```
[in] z0 Z coordinate of pt0
```

```
[in] c0 Color value of pt0
```

```
[in] x1 X coordinate of pt1
```

```
[in] y1 Y coordinate of pt1
```

```
[in] z1 Z coordinate of pt1
```

```
[in] c1 Color value of pt1
```

```
[in] x2 X coordinate of pt2
```

```
[in] y2 Y coordinate of pt2
```

```
[in] z2 Z coordinate of pt2
```

```
[in] c2 Color value of pt2
```

Return values

void No return.

```
void AEGfxTriAdd ( f32 x0,
                   f32 y0,
                   u32 c0,
                   f32 tu0,
                   f32 tv0,
                   f32 x1,
                   f32 y1,
```

```
    u32 c1,  
    f32 tu1,  
    f32 tv1,  
    f32 x2,  
    f32 y2,  
    u32 c2,  
    f32 tu2,  
    f32 tv2  
)
```

Add a new triangle to the mesh.

The triangle is defined by 3 points: pt0, pt1 and pt2. The points are listed in a counter-clockwise order. The Z-value of the points are set to default 0.

Parameters

- [in] **x0** X coordinate of pt0.
- [in] **y0** Y coordinate of pt0.
- [in] **c0** Color value of pt0.
- [in] **tu0** Texture translation of pt0.
- [in] **tv0** Texture translation of pt0.
- [in] **x1** X coordinate of pt1.
- [in] **y1** Y coordinate of pt1.
- [in] **c1** Color value of pt1.
- [in] **tu1** Texture translation of pt1.
- [in] **tv1** Texture translation of pt1.
- [in] **x2** X coordinate of pt2.
- [in] **y2** Y coordinate of pt2.
- [in] **c2** Color value of pt2.
- [in] **tu2** Texture translation of pt2.
- [in] **tv2** Texture translation of pt2.

Return values

void No return.

```
void AEGfxVertexAdd ( f32 x0,
                      f32 y0,
                      u32 c0,
                      f32 tu0,
                      f32 tv0
                      )
```

Add a new point to the mesh.

The Z-value of the point are set to default 0.

Parameters

- [in] **x0** X coordinate of the point.
- [in] **y0** Y coordinate of the point.
- [in] **c0** Color value of the point.
- [in] **tu0** Texture translation of the point.
- [in] **tv0** Texture translation of the point.

Return values

void No return.

```
DECLARE_FUNCTION_FOR_ANDROID ( AEGfxStart )
```

```
DECLARE_FUNCTION_FOR_ANDROID ( AEGfxEnd )
```

```
DECLARE_FUNCTION_FOR_ANDROID_2_INT ( AEGfxInit ,
                                     s32      Width,
                                     s32      Height
                                     )
```

Alpha Engine

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AEInput.h File Reference

Header file for the input library. [More...](#)

[Go to the source code of this file.](#)

Macros

```
#define AEVK_LBUTTON VK_LBUTTON  
Left mouse button. More...
```

```
#define AEVK_RBUTTON VK_RBUTTON  
Right mouse button. More...
```

```
#define AEVK_MBUTTON VK_MBUTTON  
Middle mouse button. More...
```

```
#define AEVK_BACK VK_BACK  
Backspace. More...
```

```
#define AEVK_TAB VK_TAB
```

```
#define AEVK_RETURN VK_RETURN
```

```
#define AEVK_LSHIFT VK_LSHIFT
```

```
#define AEVK_RSHIFT VK_RSHIFT
```

```
#define AEVK_LCTRL VK_LCONTROL
```

```
#define AEVK_RCTRL VK_RCONTROL
```

```
#define AEVK_LALT VK_LMENU
```

```
#define AEVK_RALT VK_RMENU
```

```
#define AEVK_PRINTSCREEN VK_SNAPSHOT
```

```
#define AEVK_SCROLLLOCK VK_SCROLL
```

```
#define AEVK_PAUSE VK_PAUSE
```

```
#define AEVK_CAPSLOCK VK_CAPITAL
```

```
#define AEVK_ESCAPE VK_ESCAPE
```

```
#define AEVK_SPACE VK_SPACE
```

```
#define AEVK_PAGEUP VK_PRIOR
```

```
#define AEVK_PAGEDOWN VK_NEXT
```

```
#define AEVK_END VK_END
```

```
#define AEVK_HOME VK_HOME
```

```
#define AEVK_LEFT VK_LEFT
```

```
#define AEVK_UP VK_UP
```

```
#define AEVK_RIGHT VK_RIGHT
```

```
#define AEVK_DOWN VK_DOWN
```

```
#define AEVK_INSERT VK_INSERT
```

```
#define AEVK_DELETE VK_DELETE
```

```
#define AEVK_0 0x30
```

```
#define AEVK_1 0x31
```

```
#define AEVK_2 0x32
```

```
#define AEVK_3 0x33
```

```
#define AEVK_4 0x34
```

```
#define AEVK_5 0x35
```



```
#define AEVK_6 0x36
```

```
#define AEVK_7 0x37
```

```
#define AEVK_8 0x38
```

```
#define AEVK_9 0x39
```

```
#define AEVK_A 0x41
```

```
#define AEVK_B 0x42
```

```
#define AEVK_C 0x43
```

```
#define AEVK_D 0x44
```

```
#define AEVK_E 0x45
```

```
#define AEVK_F 0x46
```

```
#define AEVK_G 0x47
```

```
#define AEVK_H 0x48
```

```
#define AEVK_I 0x49
```

```
#define AEVK_J 0x4A
```

```
#define AEVK_K 0x4B
```

```
#define AEVK_L 0x4C
```

```
#define AEVK_M 0x4D
```

```
#define AEVK_N 0x4E
```

```
#define AEVK_O 0x4F
```

```
#define AEVK_P 0x50
```

```
#define AEVK_Q 0x51
```

```
#define AEVK_R 0x52
```

```
#define AEVK_S 0x53
```

```
#define AEVK_T 0x54
```

```
#define AEVK_U 0x55
```

```
#define AEVK_V 0x56
```

```
#define AEVK_W 0x57
```

```
#define AEVK_X 0x58
```

```
#define AEVK_Y 0x59
```

```
#define AEVK_Z 0x5A
```

```
#define AEVK_NUMPAD0 VK_NUMPAD0
```

```
#define AEVK_NUMPAD1 VK_NUMPAD1
```

```
#define AEVK_NUMPAD2 VK_NUMPAD2
```

```
#define AEVK_NUMPAD3 VK_NUMPAD3
```

```
#define AEVK_NUMPAD4 VK_NUMPAD4
```

```
#define AEVK_NUMPAD5 VK_NUMPAD5
```

```
#define AEVK_NUMPAD6 VK_NUMPAD6
```

```
#define AEVK_NUMPAD7 VK_NUMPAD7
```

```
#define AEVK_NUMPAD8 VK_NUMPAD8
```

```
#define AEVK_NUMPAD9 VK_NUMPAD9
```

```
#define AEVK_NUM_MULTIPLY VK_MULTIPLY
```

```
#define AEVK_NUM_PLUS VK_ADD
```

```
#define AEVK_NUM_MINUS VK_SUBTRACT
```

```
#define AEVK_NUM_PERIOD VK_DECIMAL
```

```
#define AEVK_NUM_DIVIDE VK_DIVIDE
```

```
#define AEVK_NUMLOCK VK_NUMLOCK
```

```
#define AEVK_F1 VK_F1
```

```
#define AEVK_F2 VK_F2
```

```
#define AEVK_F3 VK_F3
```

```
#define AEVK_F4 VK_F4
```

```
#define AEVK_F5 VK_F5
```

```
#define AEVK_F6 VK_F6
```

```
#define AEVK_F7 VK_F7
```

```
#define AEVK_F8 VK_F8
```

```
#define AEVK_F9 VK_F9
```

```
#define AEVK_F10 VK_F10
```

```
#define AEVK_F11 VK_F11
```

```
#define AEVK_F12 VK_F12
```

```
#define AEVK_SEMICOLON VK_OEM_1  
; : More...
```

```
#define AEVK_SLASH VK_OEM_2  
/ ? More...
```

```
#define AEVK_BACKQUOTE VK_OEM_3  
` ~ More...
```

```
#define AEVK_LBRACKET VK_OEM_4  
[ { More...
```

```
#define AEVK_BACKSLASH VK_OEM_5  
\ | More...
```

```
#define AEVK_RBRACKET VK_OEM_6  
] } More...
```

```
#define AEVK_QUOTE VK_OEM_7  
' " More...
```

```
#define AEVK_EQUAL VK_OEM_PLUS  
= + More...
```

```
#define AEVK_MINUS VK_OEM_MINUS
```

```
#define AEVK_PERIOD VK_OEM_PERIOD  
. > More...
```

```
#define AEVK_COMMA VK_OEM_COMMA  
    , < More...
```

Functions

s32 AEInputInit ()
Initialize AEInput. [More...](#)

void AEInputReset ()
Reset AEInput. [More...](#)

void AEInputUpdate ()
Update AEInput. [More...](#)

void AEInputExit ()
Free AEInput. [More...](#)

u8 AEInputCheckCurr (u8 key)
Check if a keyboard button is being pressed. [More...](#)

u8 AEInputCheckPrev (u8 key)
Check if a keyboard button was pressed recently. [More...](#)

u8 AEInputCheckTriggered (u8 key)
Check if a keyboard button was triggered. [More...](#)

u8 AEInputCheckReleased (u8 key)
Check if a keyboard button was released. [More...](#)

void AEInputGetCursorPosition (s32 *pX, s32 *pY)
Get the current position of the cursor, in screen coordinates.
[More...](#)

void AEInputGetCursorPositionDelta (s32 *pDeltaX, s32 *pDeltaY)
Get the change in position of the cursor since the last update, in screen coordinates. [More...](#)

void AEInputShowCursor (s32 Show)

Set if mouse cursor is showned. [More...](#)

Detailed Description

Header file for the input library.

Project: Alpha Engine

Author

Sun Tjen Fam

Date

January 31, 2008

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Definition in file [AEInput.h](#).

Macro Definition Documentation

#define AEVK_0 0x30

Definition at line **59** of file [AEInput.h](#).

#define AEVK_1 0x31

Definition at line **60** of file [AEInput.h](#).

#define AEVK_2 0x32

Definition at line **61** of file [AEInput.h](#).

#define AEVK_3 0x33

Definition at line **62** of file [AEInput.h](#).

#define AEVK_4 0x34

Definition at line **63** of file [AEInput.h](#).

#define AEVK_5 0x35

Definition at line **64** of file [AEInput.h](#).

#define AEVK_6 0x36

Definition at line **65** of file **AEInput.h**.

```
#define AEVK_7 0x37
```

Definition at line **66** of file **AEInput.h**.

```
#define AEVK_8 0x38
```

Definition at line **67** of file **AEInput.h**.

```
#define AEVK_9 0x39
```

Definition at line **68** of file **AEInput.h**.

```
#define AEVK_A 0x41
```

Definition at line **70** of file **AEInput.h**.

```
#define AEVK_B 0x42
```

Definition at line **71** of file **AEInput.h**.

```
#define AEVK_BACK VK_BACK
```

Backspace.

Definition at line **31** of file **AEInput.h**.

```
#define AEVK_BACKQUOTE VK_OEM_3
```

`~

Definition at line **130** of file **AEInput.h**.

```
#define AEVK_BACKSLASH VK_OEM_5
```

\\

Definition at line **132** of file **AEInput.h**.

```
#define AEVK_C 0x43
```

Definition at line **72** of file **AEInput.h**.

```
#define AEVK_CAPSLOCK VK_CAPITAL
```

Definition at line **43** of file **AEInput.h**.

```
#define AEVK_COMMA VK_OEM_COMMA
```

, <

Definition at line **139** of file **AEInput.h**.

```
#define AEVK_D 0x44
```

Definition at line **73** of file **AEInput.h**.

```
#define AEVK_DELETE VK_DELETE
```

Definition at line [57](#) of file [AEInput.h](#).

```
#define AEVK_DOWN VK_DOWN
```

Definition at line [55](#) of file [AEInput.h](#).

```
#define AEVK_E 0x45
```

Definition at line [74](#) of file [AEInput.h](#).

```
#define AEVK_END VK_END
```

Definition at line [50](#) of file [AEInput.h](#).

```
#define AEVK_EQUAL VK_OEM_PLUS
```

= +

Definition at line [136](#) of file [AEInput.h](#).

```
#define AEVK_ESCAPE VK_ESCAPE
```

Definition at line [45](#) of file [AEInput.h](#).

```
#define AEVK_F 0x46
```

Definition at line [75](#) of file [AEInput.h](#).

```
#define AEVK_F1 VK_F1
```

Definition at line [115](#) of file [AEInput.h](#).

```
#define AEVK_F10 VK_F10
```

Definition at line [124](#) of file [AEInput.h](#).

```
#define AEVK_F11 VK_F11
```

Definition at line [125](#) of file [AEInput.h](#).

```
#define AEVK_F12 VK_F12
```

Definition at line [126](#) of file [AEInput.h](#).

```
#define AEVK_F2 VK_F2
```

Definition at line [116](#) of file [AEInput.h](#).

```
#define AEVK_F3 VK_F3
```

Definition at line [117](#) of file [AEInput.h](#).

```
#define AEVK_F4 VK_F4
```

Definition at line [118](#) of file [AEInput.h](#).

```
#define AEVK_F5 VK_F5
```

Definition at line [119](#) of file [AEInput.h](#).

#define AEVK_F6 VK_F6

Definition at line **120** of file **AEInput.h**.

#define AEVK_F7 VK_F7

Definition at line **121** of file **AEInput.h**.

#define AEVK_F8 VK_F8

Definition at line **122** of file **AEInput.h**.

#define AEVK_F9 VK_F9

Definition at line **123** of file **AEInput.h**.

#define AEVK_G 0x47

Definition at line **76** of file **AEInput.h**.

#define AEVK_H 0x48

Definition at line **77** of file **AEInput.h**.

#define AEVK_HOME VK_HOME

Definition at line **51** of file **AEInput.h**.

#define AEVK_I 0x49

Definition at line **78** of file [AEInput.h](#).

#define AEVK_INSERT VK_INSERT

Definition at line **56** of file [AEInput.h](#).

#define AEVK_J 0x4A

Definition at line **79** of file [AEInput.h](#).

#define AEVK_K 0x4B

Definition at line **80** of file [AEInput.h](#).

#define AEVK_L 0x4C

Definition at line **81** of file [AEInput.h](#).

#define AEVK_LALT VK_LMENU

Definition at line **38** of file [AEInput.h](#).

#define AEVK_LBRACKET VK_OEM_4

[{

Definition at line **131** of file [AEInput.h](#).

#define AEVK_LBUTTON VK_LBUTTON

Left mouse button.

Definition at line [27](#) of file [AEInput.h](#).

#define AEVK_LCTRL VK_LCONTROL

Definition at line [36](#) of file [AEInput.h](#).

#define AEVK_LEFT VK_LEFT

Definition at line [52](#) of file [AEInput.h](#).

#define AEVK_LSHIFT VK_LSHIFT

Definition at line [34](#) of file [AEInput.h](#).

#define AEVK_M 0x4D

Definition at line [82](#) of file [AEInput.h](#).

#define AEVK_MBUTTON VK_MBUTTON

Middle mouse button.

Definition at line [29](#) of file [AEInput.h](#).

#define AEVK_MINUS VK_OEM_MINUS

- —

Definition at line [137](#) of file [AEInput.h](#).

```
#define AEVK_N 0x4E
```

Definition at line [83](#) of file [AEInput.h](#).

```
#define AEVK_NUM_DIVIDE VK_DIVIDE
```

Definition at line [112](#) of file [AEInput.h](#).

```
#define AEVK_NUM_MINUS VK_SUBTRACT
```

Definition at line [110](#) of file [AEInput.h](#).

```
#define AEVK_NUM_MULTIPLY VK_MULTIPLY
```

Definition at line [108](#) of file [AEInput.h](#).

```
#define AEVK_NUM_PERIOD VK_DECIMAL
```

Definition at line [111](#) of file [AEInput.h](#).

```
#define AEVK_NUM_PLUS VK_ADD
```

Definition at line [109](#) of file [AEInput.h](#).

```
#define AEVK_NUMLOCK VK_NUMLOCK
```

Definition at line [113](#) of file [AEInput.h](#).

```
#define AEVK_NUMPAD0 VK_NUMPAD0
```

Definition at line [97](#) of file [AEInput.h](#).

```
#define AEVK_NUMPAD1 VK_NUMPAD1
```

Definition at line [98](#) of file [AEInput.h](#).

```
#define AEVK_NUMPAD2 VK_NUMPAD2
```

Definition at line [99](#) of file [AEInput.h](#).

```
#define AEVK_NUMPAD3 VK_NUMPAD3
```

Definition at line [100](#) of file [AEInput.h](#).

```
#define AEVK_NUMPAD4 VK_NUMPAD4
```

Definition at line [101](#) of file [AEInput.h](#).

```
#define AEVK_NUMPAD5 VK_NUMPAD5
```

Definition at line [102](#) of file [AEInput.h](#).

```
#define AEVK_NUMPAD6 VK_NUMPAD6
```

Definition at line [103](#) of file [AEInput.h](#).

```
#define AEVK_NUMPAD7 VK_NUMPAD7
```

Definition at line [104](#) of file [AEInput.h](#).

```
#define AEVK_NUMPAD8 VK_NUMPAD8
```

Definition at line [105](#) of file [AEInput.h](#).

```
#define AEVK_NUMPAD9 VK_NUMPAD9
```

Definition at line [106](#) of file [AEInput.h](#).

```
#define AEVK_O 0x4F
```

Definition at line [84](#) of file [AEInput.h](#).

```
#define AEVK_P 0x50
```

Definition at line [85](#) of file [AEInput.h](#).

```
#define AEVK_PAGEDOWN VK_NEXT
```

Definition at line [49](#) of file [AEInput.h](#).

```
#define AEVK_PAGEUP VK_PRIOR
```

Definition at line [48](#) of file [AEInput.h](#).

```
#define AEVK_PAUSE VK_PAUSE
```

Definition at line [42](#) of file [AEInput.h](#).

```
#define AEVK_PERIOD VK_OEM_PERIOD
```

. >

Definition at line [138](#) of file [AEInput.h](#).

```
#define AEVK_PRINTSCREEN VK_SNAPSHOT
```

Definition at line [40](#) of file [AEInput.h](#).

```
#define AEVK_Q 0x51
```

Definition at line [86](#) of file [AEInput.h](#).

```
#define AEVK_QUOTE VK_OEM_7
```

' "

Definition at line [134](#) of file [AEInput.h](#).

```
#define AEVK_R 0x52
```

Definition at line [87](#) of file [AEInput.h](#).

```
#define AEVK_RALT VK_RMENU
```

Definition at line [39](#) of file [AEInput.h](#).

```
#define AEVK_RBRACKET VK_OEM_6
```

```
}}
```

Definition at line [133](#) of file [AEInput.h](#).

```
#define AEVK_RBUTTON VK_RBUTTON
```

Right mouse button.

Definition at line [28](#) of file [AEInput.h](#).

```
#define AEVK_RCTRL VK_RCONTROL
```

Definition at line [37](#) of file [AEInput.h](#).

```
#define AEVK_RETURN VK_RETURN
```

Definition at line [33](#) of file [AEInput.h](#).

```
#define AEVK_RIGHT VK_RIGHT
```

Definition at line [54](#) of file [AEInput.h](#).

```
#define AEVK_RSHIFT VK_RSHIFT
```

Definition at line [35](#) of file [AEInput.h](#).

```
#define AEVK_S 0x53
```

Definition at line [88](#) of file [AEInput.h](#).

```
#define AEVK_SCROLLLOCK VK_SCROLL
```

Definition at line [41](#) of file [AEInput.h](#).

```
#define AEVK_SEMICOLON VK_OEM_1
```

```
;;
```

Definition at line [128](#) of file [AEInput.h](#).

```
#define AEVK_SLASH VK_OEM_2
```

```
/ ?
```

Definition at line [129](#) of file [AEInput.h](#).

```
#define AEVK_SPACE VK_SPACE
```

Definition at line [47](#) of file [AEInput.h](#).

```
#define AEVK_T 0x54
```

Definition at line [89](#) of file [AEInput.h](#).

```
#define AEVK_TAB VK_TAB
```

Definition at line [32](#) of file [AEInput.h](#).

```
#define AEVK_U 0x55
```

Definition at line [90](#) of file [AEInput.h](#).

#define AEVK_UP VK_UP

Definition at line **53** of file [AEInput.h](#).

#define AEVK_V 0x56

Definition at line **91** of file [AEInput.h](#).

#define AEVK_W 0x57

Definition at line **92** of file [AEInput.h](#).

#define AEVK_X 0x58

Definition at line **93** of file [AEInput.h](#).

#define AEVK_Y 0x59

Definition at line **94** of file [AEInput.h](#).

#define AEVK_Z 0x5A

Definition at line **95** of file [AEInput.h](#).

Function Documentation

u8 AEInputCheckCurr (u8 key)

Check if a keyboard button is being pressed.

Check if keyboard button given by key is currently being pressed.

Parameters

[in] **key** Value corresponding to the keyboard button that is being checked for.

Return values

u8 Return true if keyboard button is being pressed. Else return false.

u8 AEInputCheckPrev (u8 key)

Check if a keyboard button was pressed recently.

Check if keyboard button given by key was pressed in the previous update.

Parameters

[in] **key** Value corresponding to the keyboard button that is being checked for.

Return values

u8 Return true if keyboard button was pressed. Else return false.

u8 AEInputCheckReleased (u8 key)

Check if a keyboard button was released.

Check if the keyboard button given by key was recently released.

Parameters

[in] **key** Value corresponding to the keyboard button that is being checked for.

Return values

u8 Return true if keyboard button was pressed. Else return false.

u8 AEInputCheckTriggered (u8 key)

Check if a keyboard button was triggered.

Check if the keyboard button given by key was recently triggered (pressed and then quickly released).

Parameters

[in] **key** Value corresponding to the keyboard button that is being checked for.

Return values

u8 Return true if keyboard button was pressed. Else return false.

void AEInputExit ()

Free AEInput.

Warning

This function is already called in AESysExit.

Return values

void No return.

```
void AEInputGetCursorPosition ( s32 * pX,  
                               s32 * pY  
                               )
```

Get the current position of the cursor, in screen coordinates.

Parameters

[out] **pX** Pointer to s32 where the X value will be stored.

[out] **pY** Pointer to s32 where the Y value will be stored.

Return values

void No return.

```
void AEInputGetCursorPositionDelta ( s32 * pDeltaX,  
                                     s32 * pDeltaY  
                                     )
```

Get the change in position of the cursor since the last update, in screen coordinates.

Parameters

[out] **pDeltaX** Pointer to s32 where the X value will be stored.

[out] **pDeltaY** Pointer to s32 where the Y value will be stored.

Return values

void No return.

```
s32 AEInputInit ( )
```

Initialize AEInput.

Warning

This function is already called in AESysInit.

Return values

s32 Return 1 if initialization is successful. Else return 0.

void AEInputReset ()

Reset AEInput.

Warning

This function is already called in AESysReset.

Return values

void No return.

void AEInputShowCursor (**s32 Show)**

Set if mouse cursor is showned.

Setting true will allow mouse cursor to be rendered on screen.
Setting false will hide the mouse cursor.

Parameters

[in] **Show** Set if mouse cursor is showned or not.

Return values

void No return.

void AEInputUpdate ()

Update AEInput.

Warning

This function is already called in AESysUpdate.

Return values

void No return.

Alpha Engine

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[Classes](#) | [Typedefs](#) | [Functions](#)

AELineSegment2.h

File Reference

Header file for the 2D line segment library. [More...](#)

[Go to the source code of this file.](#)

Classes

struct **AELineSegment2**

Typedefs

```
typedef struct AELineSegment2 AELineSegment2
```

Functions

s32 AEBuildLineSegment2 (AELineSegment2 *pLS, AEVec2 *pPt0, AEVec2 *pPt1)
Initialize pLS using pPt0 and pPt1. Also computes the normal (unit vector) and the dot product of the normal with one of the points. [More...](#)

Detailed Description

Header file for the 2D line segment library.

Project: Alpha Engine

Author

Antoine Abi Chacra

Date

March 19, 2012

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Definition in file [AELineSegment2.h](#).

Typedef Documentation

typedef struct [AELineSegment2](#) AELineSegment2

Function Documentation

```
s32 AEBuildLineSegment2 ( AELineSegment2 * pLS,  
                           AEVec2 * pPt0,  
                           AEVec2 * pPt1  
                           )
```

Initialize pLS using pPt0 and pPt1. Also computes the normal (unit vector) and the dot product of the normal with one of the points.

Warning

The distance between pPt0 and pPt1 should be greater than EPSILON.

Parameters

- [out] **pLS** Pointer to **AELineSegment2** to be set.
- [in] **pPt0** Pointer to **AEVec2** for input.
- [in] **pPt1** Pointer to **AEVec2** for input.

Return values

s32 Returns 1 if pLS is successfully initialized. Else returns 0.

Alpha Engine

Main Page	Classes	Files	
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[Functions](#)

AEMath.h File Reference

Header file for the math library. [More...](#)

```
#include "AEVec2.h" #include "AEMtx33.h"
#include "AELineSegment2.h"
#include <float.h>
#include "math.h"
```

[Go to the source code of this file.](#)

Macros

#define AESinDeg(x) AESin(AEDegToRad(x))
Macros for the trigo functions that take input in degree.
[More...](#)

#define AECosDeg(x) AECos(AEDegToRad(x))
Macros for the trigo functions that take input in degree.
[More...](#)

#define AETanDeg(x) AETan(AEDegToRad(x))
Macros for the trigo functions that take input in degree.
[More...](#)

#define AEASinDeg(x) AERadToDeg(AEASin(x))
Macros for the trigo functions that take input in degree.
[More...](#)

#define AEACosDeg(x) AERadToDeg(AEACos(x))
Macros for the trigo functions that take input in degree.
[More...](#)

#define AEATanDeg(x) AERadToDeg(AEATan(x))
Macros for the trigo functions that take input in degree.
[More...](#)

Functions

f32 AEDegToRad (f32 x)

Convert an angle from Degree to Radians. [More...](#)

f32 AERadToDeg (f32 x)

Convert an angle from Radians to Degree. [More...](#)

f32 AESin (f32 x)

Calculate the Sine value of an angle. [More...](#)

f32 AECos (f32 x)

Calculate the Cosine value of an angle. [More...](#)

f32 AETan (f32 x)

Calculate the Tangent value of an angle. [More...](#)

f32 AEASin (f32 x)

Calculate the ArcSine value of an angle. [More...](#)

f32 AEACos (f32 x)

Calculate the ArcCosine value of an angle. [More...](#)

f32 AEATan (f32 x)

Calculate the ArcTangent value of an angle. [More...](#)

u32 AEIsPowOf2 (u32 x)

Check if x is a power of 2. [More...](#)

u32 AENextPowOf2 (u32 x)

Calculate the next power of 2 that is greater than x. [More...](#)

u32 AELogBase2 (u32 x)

Calculate the log2 of x. [More...](#)

f32 AEClamp (**f32** X, **f32** Min, **f32** Max)
Clamp x to between x0 and x1. [More...](#)

f32 AEWrap (**f32** x, **f32** x0, **f32** x1)
Wraparound for x with respect to range (x0 to x1). [More...](#)

f32 AEMin (**f32** x, **f32** y)
Find which of the 2 value is lower. [More...](#)

f32 AEMax (**f32** x, **f32** y)
Find which of the 2 value is higher. [More...](#)

s32 AEInRange (**f32** x, **f32** x0, **f32** x1)
Find if x is in the range (x0 to x1), inclusive. [More...](#)

f32 AECalcDistPointToCircle (**AVec2** *pPos, **AVec2** *pCtr, **f32** radius)
Calculate the shortest distance from a point to the edge of a circle. [More...](#)

f32 AECalcDistPointToRect (**AVec2** *pPos, **AVec2** *pRect, **f32** sizeX, **f32** sizeY)
Calculate the shortest distance from a point to the edge of a rectangle. [More...](#)

f32 AECalcDistPointToLineSeg (**AVec2** *pPos, **AVec2** *pLine0, **AVec2** *pLine1)
Calculate the shortest distance from a point to a line segment. [More...](#)

f32 AECalcDistPointToConvexPoly (**AVec2** *pPos, **AVec2** *pVtx, **u32** vtxNum)
Calculate the shortest distance from a point to the edge of a convex polygon. [More...](#)

f32 AECalcDistCircleToCircle (**AVec2** *pCtr0, **f32** radius0, **AVec2** *pCtr1, **f32** radius1)

Calculate the shortest distance between the edges of two circles. [More...](#)

f32 **AECalcDistCircleToRect** (**AVec2** *pCtr, **f32** radius, **AVec2** *pRect, **f32** sizeX, **f32** sizeY)
Calculate the shortest distance between the edges of a circle and a rectangle. [More...](#)

f32 **AECalcDistRectToRect** (**AVec2** *pRect0, **f32** sizeX0, **f32** sizeY0, **AVec2** *pRect1, **f32** sizeX1, **f32** sizeY1, **AVec2** *pNormal)
Calculate the shortest distance between the edges of two rectangles. [More...](#)

s32 **AETestPointToCircle** (**AVec2** *pPos, **AVec2** *pCtr, **f32** radius)
Test if a point is inside a circle. [More...](#)

s32 **AETestPointToRect** (**AVec2** *pPos, **AVec2** *pRect, **f32** sizeX, **f32** sizeY)
Test if a point is inside a rectangle. [More...](#)

s32 **AETestCircleToCircle** (**AVec2** *pCtr0, **f32** radius0, **AVec2** *pCtr1, **f32** radius1)
Test for collision between two circles. [More...](#)

s32 **AETestCircleToRect** (**AVec2** *pCtr, **f32** radius, **AVec2** *pRect, **f32** sizeX, **f32** sizeY)
Test for collision between a circle and a rectangle. [More...](#)

s32 **AETestRectToRect** (**AVec2** *pRect0, **f32** sizeX0, **f32** sizeY0, **AVec2** *pRect1, **f32** sizeX1, **f32** sizeY1)
Test for collision between two rectangles. [More...](#)

f32 **AESStaticPointToStaticLineSegment** (**AVec2** *pPos, **AVec2** *pLine)
Calculate the shortest distance from a point to a line. [More...](#)

f32 AAnimatedPointToStaticLineSegment (**AVec2** *pStart, **AVec2** *pEnd, **ALineSegment2** *pLine, **AVec2** *pInter)

Calculate the collision between a moving point with a line.
[More...](#)

f32 AAnimatedCircleToStaticLineSegment (**AVec2** *pStart, **AVec2** *pEnd, **f32** radius, **ALineSegment2** *pLine, **AVec2** *pInter)

Calculate the collision between a moving circle with a line.
[More...](#)

f32 AReflectAnimatedPointOnStaticLineSegment (**AVec2** *pStart, **AVec2** *pEnd, **ALineSegment2** *pLine, **AVec2** *pInter, **AVec2** *pReflect)

Calculate the collision between a moving point with a line and the reflected path of the point. [More...](#)

f32 AReflectAnimatedCircleOnStaticLineSegment (**AVec2** *pStart, **AVec2** *pEnd, **f32** radius, **ALineSegment2** *pLine, **AVec2** *pInter, **AVec2** *pReflect)

Calculate the collision between a moving circle with a line and the reflected path of the circle. [More...](#)

f32 AAnimatedPointToStaticCircle (**AVec2** *pStart, **AVec2** *pEnd, **AVec2** *pCtr, **f32** radius, **AVec2** *pInter)

Calculate the collision between a moving point with a circle.
[More...](#)

f32 AReflectAnimatedPointOnStaticCircle (**AVec2** *pStart, **AVec2** *pEnd, **AVec2** *pCtr, **f32** radius, **AVec2** *pInter, **AVec2** *pReflect)

Calculate the collision between a moving point with a circle and the reflected path of the point. [More...](#)

f32 AAnimatedCircleToStaticCircle (**AVec2** *pCtr0s, **AVec2** *pCtr0e, **f32** radius0, **AVec2** *pCtr1, **f32** radius1, **AVec2**

***pInter)**

Calculate the collision between a moving circle with a static circle. [More...](#)

AEReflectAnimatedCircleOnStaticCircle (**AVec2** *pCtr0s,
f32 **AVec2** *pCtr0e, **f32** radius0, **AVec2** *pCtr1, **f32** radius1,
AVec2 *pInter, **AVec2** *pReflect)

Calculate the collision between a moving circle with a static circle and the reflected path of moving circle. [More...](#)

Detailed Description

Header file for the math library.

Project: Alpha Engine

Author

Sun Tjen Fam

Date

January 31, 2008

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Definition in file [AEMath.h](#).

Macro Definition Documentation

#define AEACosDeg (x) AERadToDeg(AEACos(x))

Macros for the trigo functions that take input in degree.

Definition at line **169** of file **AEMath.h**.

#define AEASinDeg (x) AERadToDeg(AEASin(x))

Macros for the trigo functions that take input in degree.

Definition at line **168** of file **AEMath.h**.

#define AEATanDeg (x) AERadToDeg(AEATan(x))

Macros for the trigo functions that take input in degree.

Definition at line **170** of file **AEMath.h**.

#define AECosDeg (x) AECos(AEDegToRad(x))

Macros for the trigo functions that take input in degree.

Definition at line **166** of file **AEMath.h**.

#define AESinDeg (x) AESin(AEDegToRad(x))

Macros for the trigo functions that take input in degree.

Definition at line **165** of file **AEMath.h**.

```
#define AETanDeg ( x ) AETan(AEDegToRad(x))
```

Macros for the trigo functions that take input in degree.

Definition at line **167** of file **AEMath.h**.

Function Documentation

f32 AEACos (f32 x)

Calculate the ArcCosine value of an angle.

Parameters

[in] **x** The angle in Radians.

Return values

f32 The value of $\text{acos}(x)$.

```
f32 AEAnimatedCircleToStaticCircle ( AEVec2 * pCtr0s,  
                                     AEVec2 * pCtr0e,  
                                     f32      radius0,  
                                     AEVec2 * pCtr1,  
                                     f32      radius1,  
                                     AEVec2 * pInter  
                                     )
```

Calculate the collision between a moving circle with a static circle.

Given the start position (pCtr0s) and end position (pCtr0e) of moving circle0 of size (radius0) and the center of static circle1 (pCtr1) of size (radius1), calculate the time and point of intersection.

Warning

Radius of circles should be a non-negative value.

Parameters

[in] **pCtr0s** Pointer to **AEVec2** containing start pos of circle0.

[in] **pCtr0e** Pointer to **AEVec2** containing end pos of the

circle0.

[in] **radius0** The radius of circle0.

[in] **pCtr1** Pointer to **AEVec2** containing the center of circle1.

[in] **radius1** The radius of the circle1.

[out] **pInter** Pointer to **AEVec2** for storing the point of intersection. Will not be used if there is no collision.

Return values

f32 Returns the time of collision, if there is one. Else return -1.0f.

f32

```
AEAnimatedCircleToStaticLineSegment ( AEVec2 *      pStart
                                       AEVec2 *      pEnd
                                       f32           radius
                                       AELineSegment2 * pLine
                                       AEVec2 *      pInter
                                       )
```

Calculate the collision between a moving circle with a line.

Given the start position (pStart) and end position (pEnd) of a moving circle of size (radius) and a line (pLine), calculate the time and point of intersection.

Warning

Line is assumed to stretch to infinity.

Radius of circle should be a non-negative value.

Parameters

[in] **pStart** Pointer to **AEVec2** containing start pos of the circle.

[in] **pEnd** Pointer to **AEVec2** containing end pos of the circle.

[in] **radius** The radius of the circle.

[in] **pLine** Pointer to **AELineSegment2** containing the line.

[out] **pInter** Pointer to **AEVec2** for storing the point of intersection. Will not be used if there is no collision.

Return values

f32 Returns the time of collision, if there is one. Else return -1.0f.

```
f32 AEAnimatedPointToStaticCircle ( AEVec2 * pStart,  
                                     AEVec2 * pEnd,  
                                     AEVec2 * pCtr,  
                                     f32      radius,  
                                     AEVec2 * pInter  
                                     )
```

Calculate the collision between a moving point with a circle.

Given the start position (pStart) and end position (pEnd) of a moving point and the center of a circle (pCtr) of size (radius), calculate the time and point of intersection.

Warning

Radius of circle should be a non-negative value.

Parameters

- [in] **pStart** Pointer to **AEVec2** containing start pos of the point.
- [in] **pEnd** Pointer to **AEVec2** containing end pos of the point.
- [in] **pCtr** Pointer to **AEVec2** containing the center of the circle.
- [in] **radius** The radius of the circle.
- [out] **pInter** Pointer to **AEVec2** for storing the point of intersection. Will not be used if there is no collision.

Return values

f32 Returns the time of collision, if there is one. Else return -1.0f.

f32

```
AEAnimatedPointToStaticLineSegment ( AEVec2 * pStart,  
                                         AEVec2 * pEnd,  
                                         AELineSegment2 * pLine,  
                                         AEVec2 * pInter  
                                         )
```

Calculate the collision between a moving point with a line.

Given the start position (pStart) and end position (pEnd) of a moving point and a line (pLine), calculate the time and point of intersection.

Warning

Line is assumed to stretch to infinity.

Parameters

- [in] **pStart** Pointer to **AEVec2** containing start pos of the point.
- [in] **pEnd** Pointer to **AEVec2** containing end pos of the point.
- [in] **pLine** Pointer to **AELineSegment2** containing the line.
- [out] **pInter** Pointer to **AEVec2** for storing the point of intersection. Will not be used if there is no collision.

Return values

f32 Returns the time of collision, if there is one. Else return -1.0f.

f32 AEASin (f32 x)

Calculate the ArcSine value of an angle.

Parameters

- [in] **x** The angle in Radians.

Return values

f32 The value of asin(x).

f32 AEATan (**f32** x)

Calculate the ArcTangent value of an angle.

Parameters

[in] **x** The angle in Radians.

Return values

f32 The value of atan(x).

```
f32 AECalcDistCircleToCircle ( AEVec2 * pCtr0,  
                                f32      radius0,  
                                AEVec2 * pCtr1,  
                                f32      radius1  
                                )
```

Calculate the shortest distance between the edges of two circles.

Given the center of circle0 (pCtr0) of size (radius0) and the center of circle1 (pCtr1) of size (radius1), calculate the shortest distance between their edges.

Warning

radius of circles should be a non-negative value.

Parameters

[in] **pCtr0** Pointer to **AEVec2** containing the center of circle0.

[in] **radius0** The radius of circle0.

[in] **pCtr1** Pointer to **AEVec2** containing the center of circle1.

[in] **radius1** The radius of circle1.

Return values

f32 Returns the shortest distance between the edge of both circles. This value will be negative if the circles are

overlapping.

```
f32 AECalcDistCircleToRect ( AEVec2 * pCtr,  
                             f32      radius,  
                             AEVec2 * pRect,  
                             f32      sizeX,  
                             f32      sizeY  
                             )
```

Calculate the shortest distance between the edges of a circle and a rectangle.

Given the center of a circle (pCtr) of size (radius) and the center of a rect (pRect) of width (sizeX) and height (sizeY), calculate the shortest distance between their edges.

Warning

radius of circles should be a non-negative value.

The width and height of the rect should be non-negative values.

Function will only work if the rect is not rotated, i.e. the sides of the rect are parallel to the axis.

Parameters

[in] **pCtr** Pointer to **AEVec2** containing the center of the circle.

[in] **radius** The radius of circle.

[in] **pRect** Pointer to **AEVec2** containing the center of the rect.

[in] **sizeX** The width of the rect.

[in] **sizeY** The height of the rect.

Return values

f32 Returns the shortest distance between the edges of the circle and the rect. This value will be negative if the circle and rect are overlapping.

```
f32 AECalcDistPointToCircle ( AEVec2 * pPos,  
                                AEVec2 * pCtr,  
                                f32      radius  
                                )
```

Calculate the shortest distance from a point to the edge of a circle.

Given a point (pPos) and the center of a circle (pCtr) of size (radius), calculate the shortest distance from the point to the circumference of the circle.

Warning

Radius of circle should be a non-negative value.

Parameters

- [in] **pPos** Pointer to **AEVec2** containing the position of the point.
- [in] **pCtr** Pointer to **AEVec2** containing the position of the center of the circle
- [in] **radius** The radius of the circle.

Return values

f32 Returns the shortest distance from the point to the edge of the circle. This value will be negative if the point is inside the circle.

```
f32 AECalcDistPointToConvexPoly ( AEVec2 * pPos,  
                                    AEVec2 * pVtx,  
                                    u32      vtxNum  
                                    )
```

Calculate the shortest distance from a point to the edge of a convex polygon.

Given a point (pPos) and an array of vertices (pVtx) of size (vtxNum) making up a convex polygon, calculate the shortest distance from the point to the edge of the polygon.

Warning

Function not implemented. Do not use. Currently returns -1.0f.

Parameters

- [in] **pPos** Pointer to **AEVec2** containing the position of the point.
- [in] **pVtx** Pointer to an array of **AEVec2** containing the vertices of the polygon.
- [in] **vtxNum** The number of vertices in the polygon

Return values

f32 Returns the shortest distance from the point to the edge of the polygon. This value will be negative if the point is inside the polygon.

```
f32 AECalcDistPointToLineSeg ( AEVec2 * pPos,  
                                AEVec2 * pLine0,  
                                AEVec2 * pLine1  
                                )
```

Calculate the shortest distance from a point to a line segment.

Given a point (pPos) and start (pLine0) and end (pLine1) of a line segment, calculate the shortest distance from the point to the line segment.

Parameters

- [in] **pPos** Pointer to **AEVec2** containing the position of the point.
- [in] **pLine0** Pointer to **AEVec2** containing the start of the line segment.
- [in] **pLine1** Pointer to **AEVec2** containing the end of the line segment.

Return values

f32 Returns the shortest distance from the point to the line segment.

```
f32 AECalcDistPointToRect ( AEVec2 * pPos,  
                             AEVec2 * pRect,  
                             f32      sizeX,  
                             f32      sizeY  
                             )
```

Calculate the shortest distance from a point to the edge of a rectangle.

Given a point (pPos) and the center of a rect (pRect) of width (sizeX) and height (sizeY), calculate the shortest distance from the point to the perimeter of the rect.

Warning

The width and height of the rect should be non-negative values.
Function will only work if the rect is not rotated, i.e. the sides of the rect are parallel to the axis.

Parameters

- [in] **pPos** Pointer to **AEVec2** containing the position of the point.
- [in] **pRect** Pointer to **AEVec2** containing the position of the center of the rect.
- [in] **sizeX** Width of the rect, i.e. the size of the rect along the x-axis.
- [in] **sizeY** Height of the rect, i.e. the size of the rect along the y-axis.

Return values

f32 Returns the shortest distance from the point to the edge of the rect. This value will be negative if the point is inside the rect.

```
f32 AECalcDistRectToRect ( AEVec2 * pRect0,  
                           f32      sizeX0,
```

```

    f32      sizeY0,
    AVec2 * pRect1,
    f32      sizeX1,
    f32      sizeY1,
    AVec2 * pNormal
)

```

Calculate the shortest distance between the edges of two rectangles.

Given the center of rect0 (pRect0) of width (sizeX0) and height (sizeY0) and the center of rect1 (pRect1) of width (sizeX1) and height (sizeY1), calculate the shortest distance between their edges.

Warning

The width and height of the rect should be non-negative values.
Function will only work if the rect is not rotated, i.e. the sides of the rect are parallel to the axis.

Parameters

[in]	pRect0	Pointer to AVec2 containing the center of rect0.
[in]	sizeX0	The width of rect0.
[in]	sizeY0	The height of rect0.
[in]	pRect1	Pointer to AVec2 containing the center of rect1.
[in]	sizeX1	The width of rect1.
[in]	sizeY1	The height of rect1.
[out]	pNormal	Pointer to AVec2 where the direction from rect1 to rect0 is stored. May be left null if not needed.

Return values

f32 Returns the shortest distance between the edges of both rects. This value will be negative if they are overlapping.

```
f32 AEClamp ( f32 x,  
               f32 x0,  
               f32 x1  
             )
```

Clamp x to between x0 and x1.

If x is lower than the minimum value (x0), return x0. If x is higher than the maximum value (x1), return x1. Else return x.

Parameters

- [in] **x** The input value.
- [in] **x0** The minimum value.
- [in] **x1** The maximum value.

Return values

f32 The clamped value of x.

```
f32 AECos ( f32 x )
```

Calculate the Cosine value of an angle.

Parameters

- [in] **x** The angle in Radians.

Return values

f32 The value of cos(x).

```
f32 AEDegToRad ( f32 x )
```

Convert an angle from Degree to Radians.

Parameters

- [in] **x** The angle in Degree to be converted.

Return values

f32 The angle in Radians after conversion.

```
s32 AEInRange ( f32 x,  
                f32 x0,  
                f32 x1  
                )
```

Find if x is in the range (x0 to x1), inclusive.

If x is more than or equal to x0 OR If x is less than or equal to x1, return true. Else return false.

Parameters

- [in] **x** The input value.
- [in] **x0** The lower bound of range.
- [in] **x1** The upper bound of range.

Return values

s32 Returns true if x is between x0 and x1, inclusive. Else return false.

```
u32 AEIsPowOf2 ( u32 x )
```

Check if x is a power of 2.

Powers of 2 are values which can be presented as 2^N , where N is any non-negative integer. Examples of powers of 2 are:

- 1 (2^0)
- 2 (2^1)
- 4 (2^2)
- 256 (2^8)
- 1024 (2^{10})

Parameters

[in] **x** The value to be checked.

Return values

u32 Returns true (non-zero value) if x is a power of 2. Else return false (zero).

u32 AELogBase2 (u32 x)

Calculate the log2 of x.

Calculate the log2 of x, rounded to the lower integer.

Parameters

[in] **x** The input value.

Return values

u32 The log2 of x, rounded to lower integer.

f32 AEMax (f32 x, f32 y)

Find which of the 2 value is higher.

If x is higher than y, return x. If y is higher than x, return y.

Parameters

[in] **x** The first input value.

[in] **y** The second input value.

Return values

f32 The higher of the 2 value.

f32 AEMin (f32 x, f32 y)

)

Find which of the 2 value is lower.

If x is lower than y, return x. If y is lower than x, return y.

Parameters

[in] **x** The first input value.

[in] **y** The second input value.

Return values

f32 The lower of the 2 value.

u32 AENextPowOf2 (**u32** x)

Calculate the next power of 2 that is greater than x.

Powers of 2 are values which can be presented as 2^N , where N is any non-negative integer. Examples of powers of 2 are:

- 1 (2^0)
- 2 (2^1)
- 4 (2^2)
- 256 (2^8)
- 1024 (2^{10})

Parameters

[in] **x** The input value.

Return values

u32 Returns the next power of 2 greater than x.

f32 AERadToDeg (**f32** x)

Convert an angle from Radians to Degree.

Parameters

[in] **x** The angle in Radians to be converted.

Return values

f32 The angle in Degree after conversion.

```
f32 AEReflectAnimatedCircleOnStaticCircle ( AEVec2 * pCtr0s,  
                                              AEVec2 * pCtr0e,  
                                              f32      radius0,  
                                              AEVec2 * pCtr1,  
                                              f32      radius1,  
                                              AEVec2 * pInter,  
                                              AEVec2 * pReflect  
                                              )
```

Calculate the collision between a moving circle with a static circle and the reflected path of moving circle.

Given the start position (**pCtr0s**) and end position (**pCtr0e**) of moving circle0 of size (**radius0**) and the center of static circle1 (**pCtr1**) of size (**radius1**), calculate the time, point of intersection and reflected path of circle0.

Warning

Radius of circles should be a non-negative value.

Parameters

[in] **pCtr0s** Pointer to **AEVec2** containing start pos of circle0.

[in] **pCtr0e** Pointer to **AEVec2** containing end pos of the circle0.

[in] **radius0** The radius of circle0.

[in] **pCtr1** Pointer to **AEVec2** containing the center of circle1.

[in] **radius1** The radius of the circle1.

[out] **pInter** Pointer to **AEVec2** for storing the point of

intersection. Will not be used if there is no collision.

[out] **pReflect** Pointer to **AEVec2** for storing the reflected path. Will not be used if there is no collision.

Return values

f32 Returns the time of collision, if there is one. Else return -1.0f.

f32

```
AEReflectAnimatedCircleOnStaticLineSegment ( AEVec2 *  
                                              AEVec2 *  
                                              f32  
                                              AELineSegment2  
                                              AEVec2 *  
                                              AEVec2 *  
                                              )
```

Calculate the collision between a moving circle with a line and the reflected circle.

Given the start position (pStart) and end position (pEnd) of a moving circle (radius) and a line (pLine), calculate the time, point of intersection and reflected path.

Warning

Line is assumed to stretch to infinity.

Radius of circle should be a non-negative value.

Parameters

[in]	pStart	Pointer to AEVec2 containing start pos of the circle.
[in]	pEnd	Pointer to AEVec2 containing end pos of the circle.
[in]	radius	The radius of the circle.
[in]	pLine	Pointer to AELineSegment2 containing the line.
[out]	pInter	Pointer to AEVec2 for storing the point of intersection. Will not be used if there is no collision.

[out] **pReflect** Pointer to **AVec2** for storing the reflected path. V used if there is no collision.

Return values

f32 Returns the time of collision, if there is one. Else return -1.0f.

```
f32 AEReflectAnimatedPointOnStaticCircle ( AVec2 * pStart,  
                                             AVec2 * pEnd,  
                                             AVec2 * pCtr,  
                                             f32      radius,  
                                             AVec2 * pInter,  
                                             AVec2 * pReflect  
                                             )
```

Calculate the collision between a moving point with a circle and the reflected path of the point.

Given the start position (pStart) and end position (pEnd) of a moving point and the center of a circle (pCtr) of size (radius), calculate the time, point of intersection and reflected path.

Warning

Radius of circle should be a non-negative value.

Parameters

[in] pStart	Pointer to AVec2 containing start pos of the point.
[in] pEnd	Pointer to AVec2 containing end pos of the point.
[in] pCtr	Pointer to AVec2 containing the center of the circle.
[in] radius	The radius of the circle.
[out] pInter	Pointer to AVec2 for storing the point of intersection. Will not be used if there is no collision.
[out] pReflect	Pointer to AVec2 for storing the reflected path. Will not be used if there is no collision.

Return values

f32 Returns the time of collision, if there is one. Else return -1.0f.

f32

```
AEReflectAnimatedPointOnStaticLineSegment ( AEVec2 *  
                                                AEVec2 *  
                                                AELineSegment2 *  
                                                AEVec2 *  
                                                AEVec2 *  
                                                )
```

Calculate the collision between a moving point with a line and the reflection of the point.

Given the start position (pStart) and end position (pEnd) of a moving point (pLine), calculate the time, point of intersection and reflected path.

Warning

Line is assumed to stretch to infinity.

Parameters

- [in] **pStart** Pointer to **AEVec2** containing start pos of the point
- [in] **pEnd** Pointer to **AEVec2** containing end pos of the point
- [in] **pLine** Pointer to **AELineSegment2** containing the line.
- [out] **pInter** Pointer to **AEVec2** for storing the point of intersection. Not to be used if there is no collision.
- [out] **pReflect** Pointer to **AEVec2** for storing the reflected path. Not to be used if there is no collision.

Return values

f32 Returns the time of collision, if there is one. Else return -1.0f.

f32 **AESin** (**f32** x)

Calculate the Sine value of an angle.

Parameters

[in] **x** The angle in Radians.

Return values

f32 The value of sin(x).

f32

AESStaticPointToStaticLineSegment (**AEVec2** * **pPos**,
 AELineSegment2 * **pLine**
)

Calculate the shortest distance from a point to a line.

Given a point (pPos) and a line (pLine), calculate the shortest distance from the point to the line.

Warning

Line is assumed to stretch to infinity.

Parameters

[in] **pPos** Pointer to **AEVec2** containing the point.

[in] **pLine** Pointer to **AELineSegment2** containing the line.

Return values

f32 Returns the distance from the point to the line. Negative if the point is in the line's inside half plane. Positive if the point is in the line's outside half plane. Otherwise zero if the point is on the line.

f32 **AETan** (**f32** **x**)

Calculate the Tangent value of an angle.

Parameters

[in] **x** The angle in Radians.

Return values

f32 The value of tan(x).

```
s32 AETestCircleToCircle ( AEVec2 * pCtr0,  
                           f32      radius0,  
                           AEVec2 * pCtr1,  
                           f32      radius1  
                           )
```

Test for collision between two circles.

Given the center of circle0 (**pCtr0**) of size (**radius0**) and the center of circle1 (**pCtr1**) of size (**radius1**), check if they are colliding.

Warning

Radius of circle should be a non-negative value.

Parameters

[in] **pCtr0** Pointer to **AEVec2** containing the center of circle0.

[in] **radius0** The radius of circle0.

[in] **pCtr1** Pointer to **AEVec2** containing the center of circle1.

[in] **radius1** The radius of circle1.

Return values

s32 Returns true if the circles are colliding. Else return false.

```
s32 AETestCircleToRect ( AEVec2 * pCtr,  
                          f32      radius,  
                          AEVec2 * pRect,  
                          f32      sizeX,  
                          f32      sizeY
```

)

Test for collision between a circle and a rectangle.

Given the center of a circle (pCtr) of size (radius) and the center of a rect (pRect) of width (sizeX) and height (sizeY), check if they are colliding.

Warning

radius of circles should be a non-negative value.

The width and height of the rect should be non-negative values.

Function will only work if the rect is not rotated, i.e. the sides of the rect are parallel to the axis.

Parameters

[in] **pCtr** Pointer to **AEVec2** containing the center of the circle.

[in] **radius** The radius of circle.

[in] **pRect** Pointer to **AEVec2** containing the center of the rect.

[in] **sizeX** The width of the rect.

[in] **sizeY** The height of the rect.

Return values

s32 Returns true if the circle and the rect are colliding. Else return false.

```
s32 AETestPointToCircle ( AEVec2 * pPos,  
                           AEVec2 * pCtr,  
                           f32      radius  
                           )
```

Test if a point is inside a circle.

Given a point (pPos) and the center of a circle (pCtr) of size (radius), check if the point is in the circle.

Warning

Radius of circle should be a non-negative value.

Parameters

- [in] **pPos** Pointer to **AEVec2** containing the position of the point.
- [in] **pCtr** Pointer to **AEVec2** containing the center of the circle.
- [in] **radius** The radius of circle0.

Return values

s32 Returns true if the point is inside the circle. Else return false.

```
s32 AETestPointToRect ( AEVec2 * pPos,  
                        AEVec2 * pRect,  
                        f32      sizeX,  
                        f32      sizeY  
                        )
```

Test if a point is inside a rectangle.

Given a point (pPos) and the center of a rect (pRect) of width (sizeX) and height (sizeY), check if the point is in the rect.

Warning

The width and height of the rect should be non-negative values.
Function will only work if the rect is not rotated, i.e. the sides of the rect are parallel to the axis.

Parameters

- [in] **pPos** Pointer to **AEVec2** containing the position of the point.
- [in] **pRect** Pointer to **AEVec2** containing the center of the rect.
- [in] **sizeX** The width of the rect.
- [in] **sizeY** The height of the rect.

Return values

s32 Returns true if the point is inside the rect. Else return false.

```
s32 AETestRectToRect ( AEVec2 * pRect0,  
                        f32      sizeX0,  
                        f32      sizeY0,  
                        AEVec2 * pRect1,  
                        f32      sizeX1,  
                        f32      sizeY1  
                      )
```

Test for collision between two rectangles.

Given the center of rect0 (**pRect0**) of width (**sizeX0**) and height (**sizeY0**) and the center of rect1 (**pRect1**) of width (**sizeX1**) and height (**sizeY1**), check if they are colliding.

Warning

The width and height of the rect should be non-negative values.
Function will only work if the rect is not rotated, i.e. the sides of the rect are parallel to the axis.

Parameters

- [in] **pRect0** Pointer to **AEVec2** containing the center of rect0.
- [in] **sizeX0** The width of rect0.
- [in] **sizeY0** The height of rect0.
- [in] **pRect1** Pointer to **AEVec2** containing the center of rect1.
- [in] **sizeX1** The width of rect1.
- [in] **sizeY1** The height of rect1.

Return values

s32 Returns true if the rects are colliding. Else return false.

```
f32 AEWrap ( f32 x,  
             f32 x0,
```

f32 x1
)

Wraparound for x with respect to range (x0 to x1).

If x is lesser than x0, return (x + range). If x is higher than x1, return (x - range).

Warning

Wraparound does not work if x is lesser than (x0 - range) or if x is greater than (x1 + range).

Parameters

[in] **x** The input value.

[in] **x0** The lower bound of range

[in] **x1** The upper bound of range.

Return values

f32 The wraparound value of x with respect to range.

Alpha Engine

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AEMtx33.h File Reference

Header file for the 3x3 matrix library. [More...](#)

[Go to the source code of this file.](#)

Classes

struct **AEMtx33**

Macros

```
#define AEMtx33RowCol(pMtx, row, col) (pMtx)->m[(row)][(col)]
```

Typedefs

```
typedef struct AEMtx33 AEMtx33
```

Functions

void **AEMtx33Identity** (**AEMtx33** *pResult)
Set pResult to identity matrix. [More...](#)

void **AEMtx33Transpose** (**AEMtx33** *pResult, **AEMtx33** *pMtx)
Set pResult to the transpose of pMtx. [More...](#)

f32 **AEMtx33Inverse** (**AEMtx33** *pResult, **AEMtx33** *pMtx)
Set pResult to the inverse of pMtx. [More...](#)

void **AEMtx33InvTranspose** (**AEMtx33** *pResult, **AEMtx33** *pMtx)
Set pResult to the transpose of the inverse of pMtx. [More...](#)

void **AEMtx33Concat** (**AEMtx33** *pResult, **AEMtx33** *pMtx0, **AEMtx33** *pMtx1)
Set pResult to the multiplication of pMtx0 with pMtx1. [More...](#)

void **AEMtx33Orthogonalize** (**AEMtx33** *pResult, **AEMtx33** *pMtx)
Set pResult to the orthogonalization of pMtx. [More...](#)

f32 **AEMtx33Determinant** (**AEMtx33** *pMtx)
Calculate the determinant of pMtx. [More...](#)

void **AEMtx33SetCol** (**AEMtx33** *pResult, **u32** col, **AEVec2** *pVec)
Set the first and second element of the selected column of pResult to the x and y values of pVec respectively. The last element of the column will be set automatically. [More...](#)

void **AEMtx33SetRow** (**AEMtx33** *pResult, **u32** row, **AEVec2** *pVec)
Set the first and second element of the selected row of pResult to the x and y values of pVec respectively. The last element of the row will be set automatically. [More...](#)

void **AEMtx33GetCol** (**AEVec2** *pResult, **AEMtx33** *pMtx, **u32** col)
Set the x and y values of pResult with the first and second

element of the selected column of pMtx respectively. [More...](#)

void **AEMtx33GetRow** (**AEVec2** *pResult, **AEMtx33** *pMtx, **u32** row)

void **AEMtx33Trans** (**AEMtx33** *pResult, **f32** x, **f32** y)
Set pResult to the translation matrix of x and y. [More...](#)

void **AEMtx33TransApply** (**AEMtx33** *pResult, **AEMtx33** *pMtx, **f32** x, **f32** y)
Set pResult to the multiplication of translation matrix of x and y with pMtx. [More...](#)

void **AEMtx33Scale** (**AEMtx33** *pResult, **f32** x, **f32** y)
Set pResult to the scaling matrix of x and y. [More...](#)

void **AEMtx33ScaleApply** (**AEMtx33** *pResult, **AEMtx33** *pMtx, **f32** x, **f32** y)
Set pResult to the multiplication of scaling matrix of x and y with pMtx. [More...](#)

void **AEMtx33Rot** (**AEMtx33** *pResult, **f32** angle)
Set pResult to the rotation matrix of angle in radians rotating counter-clockwise. [More...](#)

void **AEMtx33RotDeg** (**AEMtx33** *pResult, **f32** angle)
Set pResult to the rotation matrix of angle in degrees rotating counter-clockwise. [More...](#)

void **AEMtx33MultVec** (**AEVec2** *pResult, **AEMtx33** *pMtx, **AEVec2** *pVec)
Set pResult to the multiplication of pMtx with pVec. [More...](#)

void **AEMtx33MultVecArray** (**AEVec2** *pResult, **AEMtx33** *pMtx, **AEVec2** *pVec, **u32** count)
Set an array of vectors (pResult) to the multiplication of pMtx with an array of vectors (pVec) of size (count). [More...](#)

```
void AEMtx33MultVecSR (AEVec2 *pResult, AEMtx33 *pMtx,  
AEVec2 *pVec)
```

```
void AEMtx33MultVecArraySR (AEVec2 *pResult, AEMtx33 *pMtx,  
AEVec2 *pVec, u32 count)
```

Detailed Description

Header file for the 3x3 matrix library.

Project: Alpha Engine

Author

Sun Tjen Fam

Date

January 31, 2008

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Definition in file [AEMtx33.h](#).

Macro Definition Documentation

```
#define AEMtx33RowCol ( pMtx,  
                        row,  
                        col  
                        )    (pMtx)->m[(row)][(col)]
```

Definition at line [23](#) of file [AEMtx33.h](#).

Typedef Documentation

typedef struct [AEMtx33](#) AEMtx33

Matrix is stored in column major format, ie. the translation term is in the right most column.

```
m[0][0] m[0][1] m[0][2]  
m[1][0] m[1][1] m[1][2]  
m[2][0] m[2][1] m[2][2]
```

Function Documentation

```
void AEMtx33Concat ( AEMtx33 * pResult,  
                    AEMtx33 * pMtx0,  
                    AEMtx33 * pMtx1  
                    )
```

Set pResult to the multiplication of pMtx0 with pMtx1.

Parameters

[out] **pResult** Pointer to **AEMtx33** to be set.
[in] **pMtx0** Pointer to **AEMtx33** for input.
[in] **pMtx1** Pointer to **AEMtx33** for input.

Return values

void No return.

```
f32 AEMtx33Determinant ( AEMtx33 * pMtx )
```

Calculate the determinant of pMtx.

Parameters

[in] **pMtx** Pointer to **AEMtx33** for input.

Return values

f32 Returns the determinant of pMtx.

```
void AEMtx33GetCol ( AEVec2 * pResult,  
                    AEMtx33 * pMtx,  
                    u32      col  
                    )
```

Set the x and y values of pResult with the first and second element of the selected column of pMtx respectively.

Parameters

- [out] **pResult** Pointer to **AEVec2** to be set.
- [in] **pMtx** Pointer to **AEMtx33** for input.
- [in] **col** The selected column of pResult.

Return values

void No return.

```
void AEMtx33GetRow ( AEVec2 * pResult,  
                    AEMtx33 * pMtx,  
                    u32      row  
                    )
```

```
void AEMtx33Identity ( AEMtx33 * pResult )
```

Set pResult to identity matrix.

Parameters

- [out] **pResult** Pointer to **AEMtx33** to be set.

Return values

void No return.

```
f32 AEMtx33Inverse ( AEMtx33 * pResult,  
                    AEMtx33 * pMtx  
                    )
```

Set pResult to the inverse of pMtx.

Parameters

- [out] **pResult** Pointer to **AEMtx33** to be set.

[in] **pMtx** Pointer to **AEMtx33** for input.

Return values

f32 Returns the determinant of pMtx.

```
void AEMtx33InvTranspose ( AEMtx33 * pResult,  
                           AEMtx33 * pMtx  
                           )
```

Set pResult to the transpose of the inverse of pMtx.

Parameters

[out] **pResult** Pointer to **AEMtx33** to be set.

[in] **pMtx** Pointer to **AEMtx33** for input.

Return values

void No return.

```
void AEMtx33MultVec ( AEVec2 * pResult,  
                     AEMtx33 * pMtx,  
                     AEVec2 * pVec  
                     )
```

Set pResult to the multiplication of pMtx with pVec.

Parameters

[out] **pResult** Pointer to **AEMtx33** to be set.

[in] **pMtx** Pointer to **AEMtx33** for input.

[in] **pVec** Pointer to **AEVec2** for input.

Return values

void No return.

```
void AEMtx33MultVecArray ( AEVec2 * pResult,
```

```
    AEMtx33 * pMtx,  
    AVec2 * pVec,  
    u32      count  
)
```

Set an array of vectors (pResult) to the multiplication of pMtx with an array of vectors (pVec) of size (count).

Warning

Size of pResult should be not less than count.

Parameters

[out] **pResult** Pointer to an array of **AEMtx33** to be set.
[in] **pMtx** Pointer to **AEMtx33** for input.
[in] **pVec** Pointer to an array of **AVec2** for input.
[in] **count** Number of elements in pVec to be multiplied.

Return values

void No return.

```
void AEMtx33MultVecArraySR ( AVec2 * pResult,  
                             AEMtx33 * pMtx,  
                             AVec2 * pVec,  
                             u32      count  
)
```

```
void AEMtx33MultVecSR ( AVec2 * pResult,  
                        AEMtx33 * pMtx,  
                        AVec2 * pVec  
)
```

```
void AEMtx33Orthogonalize ( AEMtx33 * pResult,  
                            AEMtx33 * pMtx  
)
```

Set pResult to the orthogonalization of pMtx.

Warning

Function not implemented.

Parameters

[out] **pResult** Pointer to **AEMtx33** to be set.
[in] **pMtx** Pointer to **AEMtx33** for input.

Return values

void No return.

```
void AEMtx33Rot ( AEMtx33 * pResult,  
                  f32          angle  
                  )
```

Set pResult to the rotation matrix of angle in radians rotating counter-clockwise.

Parameters

[out] **pResult** Pointer to **AEMtx33** to be set.
[in] **angle** Angle in radians rotating counter-clockwise.

Return values

void No return.

```
void AEMtx33RotDeg ( AEMtx33 * pResult,  
                     f32          angle  
                     )
```

Set pResult to the rotation matrix of angle in degrees rotating counter-clockwise.

Parameters

[out] **pResult** Pointer to **AEMtx33** to be set.

[in] **angle** Angle in degrees rotating counter-clockwise.

Return values

void No return.

```
void AEMtx33Scale ( AEMtx33 * pResult,  
                   f32      x,  
                   f32      y  
                   )
```

Set pResult to the scaling matrix of x and y.

Parameters

[out] **pResult** Pointer to **AEMtx33** to be set.
[in] **x** Scaling along the x-axis.
[in] **y** Scaling along the y-axis.

Return values

void No return.

```
void AEMtx33ScaleApply ( AEMtx33 * pResult,  
                        AEMtx33 * pMtx,  
                        f32      x,  
                        f32      y  
                        )
```

Set pResult to the multiplication of scaling matrix of x and y with pMtx.

Parameters

[out] **pResult** Pointer to **AEMtx33** to be set.
[in] **pMtx** Pointer to **AEMtx33** for input.
[in] **x** Scaling along the x-axis.
[in] **y** Scaling along the y-axis.

Return values

void No return.

```
void AEMtx33SetCol ( AEMtx33 * pResult,  
                    u32      col,  
                    AVec2 *  pVec  
                    )
```

Set the first and second element of the selected column of pResult to the x and y values of pVec respectively. The last element of the column will be set automatically.

Parameters

[in, out]	pResult	Pointer to AEMtx33 to be set.
[in]	col	The selected column of pResult.
[in]	pVec	Pointer to AVec2 for input.

Return values

void No return.

```
void AEMtx33SetRow ( AEMtx33 * pResult,  
                    u32      row,  
                    AVec2 *  pVec  
                    )
```

Set the first and second element of the selected row of pResult to the x and y values of pVec respectively. The last element of the row will be set automatically.

Parameters

[in, out]	pResult	Pointer to AEMtx33 to be set.
[in]	row	The selected row of pResult.
[in]	pVec	Pointer to AVec2 for input.

Return values

void No return.

```
void AEMtx33Trans ( AEMtx33 * pResult,  
                   f32      x,  
                   f32      y  
                   )
```

Set pResult to the translation matrix of x and y.

Parameters

[out] **pResult** Pointer to **AEMtx33** to be set.
[in] **x** Translation along the x-axis.
[in] **y** Translation along the y-axis.

Return values

void No return.

```
void AEMtx33TransApply ( AEMtx33 * pResult,  
                        AEMtx33 * pMtx,  
                        f32      x,  
                        f32      y  
                        )
```

Set pResult to the multiplication of translation matrix of x and y with pMtx.

Parameters

[out] **pResult** Pointer to **AEMtx33** to be set.
[in] **pMtx** Pointer to **AEMtx33** for input.
[in] **x** Translation along the x-axis.
[in] **y** Translation along the y-axis.

Return values

void No return.

```
void AEMtx33Transpose ( AEMtx33 * pResult,  
                        AEMtx33 * pMtx  
                        )
```

Set pResult to the transpose of pMtx.

Parameters

[out] **pResult** Pointer to **AEMtx33** to be set.
[in] **pMtx** Pointer to **AEMtx33** for input.

Return values

void No return.

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[Functions](#) | [Variables](#)

AESystem.h File Reference

Header file for the system library. [More...](#)

[Go to the source code of this file.](#)

Functions

s32 **AESysInit** (HINSTANCE hAppInstance, **s32** show, **s32** WinWidth, **s32** WinHeight, **s32** CreateConsole, **u32** FrameRateMax, LRESULT(*pWinCallBack)(HWND hWnd, UINT msg, WPARAM wp, LPARAM lp))
Initialize the Alpha Engine. [More...](#)

void **AESysReset** ()
Reset the Alpha Engine. [More...](#)

void **AESysExit** ()
Free the Alpha Engine. [More...](#)

void **AESysFrameStart** ()
Start of frame. [More...](#)

void **AESysFrameEnd** ()
End of frame. [More...](#)

HWND **AESysGetWindowHandle** ()
Get the handle to the window. [More...](#)

void **AESysSetWindowTitle** (const **s8** *pTitle)
Set the title of the window. [More...](#)

s32 **AESysDoesWindowExist** ()
Check if the window has been closed. [More...](#)

Variables

HINSTANCE	ghAESysAppInstance
-----------	---------------------------

HWND	gAESysWindowHandle
------	---------------------------

WNDCLASS	winClass
----------	-----------------

const s8 *	gpAESysWinTitle
------------	------------------------

const s8 *	gpAESysWinClassName
------------	----------------------------

s32	gAESysAppActive
-----	------------------------

Detailed Description

Header file for the system library.

Project: Alpha Engine

Author

Sun Tjen Fam

Date

January 31, 2007

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Definition in file [AESystem.h](#).

Function Documentation

s32 AESysDoesWindowExist ()

Check if the window has been closed.

Return values

s32 Return 1 if the window exist. Else return 0.

void AESysExit ()

Free the Alpha Engine.

Call this function once at the end of the program to free the system.

Return values

void No return.

void AESysFrameEnd ()

End of frame.

Call this function once at the end of the frame to inform the system the current frame is ending.

Return values

void No return.

void AESysFrameStart ()

Start of frame.

Call this function once at the start of the frame to inform the system a new frame is starting.

Return values

void No return.

HWND AESysGetWindowHandle ()

Get the handle to the window.

Return values

HWND Returns the handle to the window.

s32

AESysInit (HINSTANCE

s32

s32

s32

s32

u32

LRESULT(*)(HWND hWnd, UINT msg, WPARAM wp, LP

Initialize the Alpha Engine.

Call this function once at the start of the program to initialize the system

Parameters

- [in] **hAppInstance** Handle to the current instance of the application.
- [in] **show** Set how the window is to be shown.
- [in] **WinWidth** Set the width of the window.
- [in] **WinHeight** Set the height of the window.
- [in] **CreateConsole** Input 1 if a console window should be created.
- [in] **FrameRateMax** Set the maximum frames per second.
- [in] **pWinCallback** Pointer to a callback function. May be left null.

Return values

s32 Return 1 if initialization is successful. Else return 0.

void AESysReset ()

Reset the Alpha Engine.

Call this function when changing gamestates to reset the system.

Return values

void No return.

void AESysSetWindowTitle (const s8 * pTitle)

Set the title of the window.

Parameters

[in] **pTitle** Pointer to a null-terminated string to set as the title of the window.

Return values

void No return.

Variable Documentation

s32 gAESysAppActive

HWND gAESysWindowHandle

HINSTANCE ghAESysAppInstance

const s8* gpAESysWinClassName

const s8* gpAESysWinTitle

WNDCLASS winClass

Alpha Engine

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AETypes.h File Reference

Header file for the typedefs. [More...](#)

[Go to the source code of this file.](#)

Typedefs

typedef char	s8
typedef unsigned char	u8
typedef signed short	s16
typedef unsigned short	u16
typedef signed int	s32
typedef unsigned int	u32
typedef signed long long	s64
typedef unsigned long long	u64
typedef float	f32
typedef double	f64

Detailed Description

Header file for the typedefs.

Project: Alpha Engine

Author

Antoine Abi Chacra

Date

March 21, 2013

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Definition in file [AETypes.h](#).

Typedef Documentation

typedef float f32

Definition at line [31](#) of file [AETypes.h](#).

typedef double f64

Definition at line [32](#) of file [AETypes.h](#).

typedef signed short s16

Definition at line [25](#) of file [AETypes.h](#).

typedef signed int s32

Definition at line [27](#) of file [AETypes.h](#).

typedef signed long long s64

Definition at line [29](#) of file [AETypes.h](#).

typedef char s8

Definition at line [23](#) of file [AETypes.h](#).

typedef unsigned short u16

Definition at line **26** of file **AETypes.h**.

typedef unsigned int u32

Definition at line **28** of file **AETypes.h**.

typedef unsigned long long u64

Definition at line **30** of file **AETypes.h**.

typedef unsigned char u8

Definition at line **24** of file **AETypes.h**.

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AEUtil.h File Reference

Header file for the utility library. [More...](#)

[Go to the source code of this file.](#)

Macros

```
#define isZero(x) ((x < EPSILON) && (x > -EPSILON))
```

```
#define isEqual(x, y) (((x >= y) ? (x-y) : (y-x)) < EPSILON)
```

Functions

f64 AEGetTime (f64 *pTime)

Get the current time in seconds. [More...](#)

f32 AERandFloat ()

Get a random real number between 0.0f to 1.0f. [More...](#)

s8 * ReadFromFile (const s8 *fileName)

Read file into memory. [More...](#)

Detailed Description

Header file for the utility library.

Project: Alpha Engine

Author

Sun Tjen Fam

Date

February 02, 2008

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Definition in file [AEUtil.h](#).

Macro Definition Documentation

```
#define isEqual ( x,  
                y  
                )    (((x >= y) ? (x-y) : (y-x)) < EPSILON)
```

Definition at line **56** of file **AEUtil.h**.

```
#define isZero ( x )    ((x < EPSILON) && (x > -EPSILON))
```

Definition at line **54** of file **AEUtil.h**.

Function Documentation

f64 AEGetTime (f64 * pTime)

Get the current time in seconds.

Parameters

[out] **pTime** Pointer to f64 to store the current time. May be left null if not needed.

Return values

f64 Returns the current time in seconds.

f32 AERandFloat ()

Get a random real number between 0.0f to 1.0f.

Return values

f32 Returns a random real number between 0.0f to 1.0f.

s8 * ReadFromFile (const s8 * fileName)

Read file into memory.

Open a file named filename, allocate sufficient storage and read the file into memory.

Warning

User must delete the memory allocated on their own.

Parameters

[in] **fileName** Pointer to the name of the file.

Return values

s8* Pointer to the start of the memory containing the file.

Alpha Engine

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File List	File Members		
include			

[Classes](#) | [Typedefs](#) | [Functions](#)

AEVec2.h File Reference

Header file for the 2D vector library. [More...](#)

```
#include "AExport.h" #include "ATypes.h"
```

[Go to the source code of this file.](#)

Classes

struct **AEVec2**

Typedefs

```
typedef struct AEVec2 AEVec2
```

Functions

s32 AEVec2Test (s32 i1, s32 i2)

void **AEVec2Zero** (**AEVec2** *pResult)
Set pResult to zero. [More...](#)

void **AEVec2Set** (**AEVec2** *pResult, **f32** x, **f32** y)
Set pResult to (x, y). [More...](#)

void **AEVec2Neg** (**AEVec2** *pResult, **AEVec2** *pVec0)
Set pResult to the negative of pVec0. [More...](#)

void **AEVec2Add** (**AEVec2** *pResult, **AEVec2** *pVec0, **AEVec2** *pVec1)
Set pResult to (pVec0 + pVec1). [More...](#)

void **AEVec2Sub** (**AEVec2** *pResult, **AEVec2** *pVec0, **AEVec2** *pVec1)
Set pResult to (pVec0 - pVec1). [More...](#)

void **AEVec2Normalize** (**AEVec2** *pResult, **AEVec2** *pVec0)
Set pResult to the normalized of pVec0. [More...](#)

void **AEVec2Scale** (**AEVec2** *pResult, **AEVec2** *pVec0, **f32** s)
Set pResult to (pVec0 * s). [More...](#)

void **AEVec2ScaleAdd** (**AEVec2** *pResult, **AEVec2** *pVec0, **AEVec2** *pVec1, **f32** s)
Set pResult to ((pVec0 + pVec1) * s). [More...](#)

void **AEVec2ScaleSub** (**AEVec2** *pResult, **AEVec2** *pVec0, **AEVec2** *pVec1, **f32** s)
Set pResult to ((pVec0 - pVec1) * s). [More...](#)

AEVec2Project (**AEVec2** *pResult, **AEVec2** *pVec0, **AEVec2**

void ***pVec1)**
Set pResult to the projection of pVec1 onto pVec0. [More...](#)

void **AEVec2ProjectPerp (AEVec2 *pResult, AEVec2 *pVec0, AEVec2 *pVec1)**
Set pResult to the perpendicular projection (rejection) of pVec0 onto pVec1. [More...](#)

void **AEVec2Lerp (AEVec2 *pResult, AEVec2 *pVec0, AEVec2 *pVec1, f32 t)**
Set pResult to the linear interpolation between pVec0 and pVec1 at time interval t. [More...](#)

f32 AEVec2Length (AEVec2 *pVec0)
Calculate the length of pVec0. [More...](#)

f32 AEVec2SquareLength (AEVec2 *pVec0)
Calculate the squared length of pVec0. [More...](#)

f32 AEVec2Distance (AEVec2 *pVec0, AEVec2 *pVec1)
Calculate the distance between 2 points. [More...](#)

f32 AEVec2SquareDistance (AEVec2 *pVec0, AEVec2 *pVec1)
Calculate the squared distance between 2 points. [More...](#)

f32 AEVec2DotProduct (AEVec2 *pVec0, AEVec2 *pVec1)
Calculate the dot product of 2 vectors. [More...](#)

f32 AEVec2CrossProductMag (AEVec2 *pVec0, AEVec2 *pVec1)
Calculate the magnitude of the cross product of 2 vectors.
[More...](#)

void **AEVec2FromAngle (AEVec2 *pResult, f32 angle)**
Set pResult to unit vector of angle. [More...](#)

Detailed Description

Header file for the 2D vector library.

Project: Alpha Engine

Author

Sun Tjen Fam

Date

January 31, 2008

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Definition in file [AEVec2.h](#).

Typedef Documentation

typedef struct [AEVec2](#) AEVec2

Function Documentation

```
void AEVec2Add ( AEVec2 * pResult,  
                AEVec2 * pVec0,  
                AEVec2 * pVec1  
                )
```

Set pResult to (pVec0 + pVec1).

Parameters

- [out] **pResult** Pointer to **AEVec2** to be set.
- [in] **pVec0** Pointer to **AEVec2** for input.
- [in] **pVec1** Pointer to **AEVec2** for input.

Return values

void No return.

```
f32 AEVec2CrossProductMag ( AEVec2 * pVec0,  
                           AEVec2 * pVec1  
                           )
```

Calculate the magnitude of the cross product of 2 vectors.

Parameters

- [in] **pVec0** Pointer to **AEVec2** of first vector.
- [in] **pVec1** Pointer to **AEVec2** of second vector.

Return values

f32 Returns the magnitude of the cross product of pVec0 and pVec1.

```
f32 AEVec2Distance ( AEVec2 * pVec0,  
                     AEVec2 * pVec1  
                     )
```

Calculate the distance between 2 points.

Parameters

[in] **pVec0** Pointer to **AEVec2** of first point.

[in] **pVec1** Pointer to **AEVec2** of second point.

Return values

f32 Returns the distance between pVec0 and pVec1.

```
f32 AEVec2DotProduct ( AEVec2 * pVec0,  
                      AEVec2 * pVec1  
                      )
```

Calculate the dot product of 2 vectors.

Parameters

[in] **pVec0** Pointer to **AEVec2** of first vector.

[in] **pVec1** Pointer to **AEVec2** of second vector.

Return values

f32 Returns the dot product of pVec0 and pVec1.

```
void AEVec2FromAngle ( AEVec2 * pResult,  
                      f32      angle  
                      )
```

Set pResult to unit vector of angle.

Parameters

[out] **pResult** Pointer to **AEVec2** to be set.

[in] **angle** Angle of the unit vector.

Return values

void No return.

f32 AEVec2Length (AEVec2 * pVec0)

Calculate the length of pVec0.

Parameters

[in] **pVec0** Pointer to **AEVec2** for input

Return values

f32 Returns the length of pVec0.

```
void AEVec2Lerp ( AEVec2 * pResult,  
                  AEVec2 * pVec0,  
                  AEVec2 * pVec1,  
                  f32      t  
                )
```

Set pResult to the linear interpolation between pVec0 and pVec1 at time interval t.

Warning

t should be between 0.0f to 1.0f.

Parameters

[out] **pResult** Pointer to **AEVec2** to be set.

[in] **pVec0** Pointer to **AEVec2** for input.

[in] **pVec1** Pointer to **AEVec2** for input.

[in] **t** The time interval to calculate the linear interpolation at. At t = 0.0f, the result will be pVec0. At t = 1.0f, the result will be pVec1.

Return values

void No return.

```
void AEVec2Neg ( AEVec2 * pResult,  
                AEVec2 * pVec0  
                )
```

Set pResult to the negative of pVec0.

Parameters

[out] **pResult** Pointer to **AEVec2** to be set.

[in] **pVec0** Pointer to **AEVec2** for input.

Return values

void No return.

```
void AEVec2Normalize ( AEVec2 * pResult,  
                      AEVec2 * pVec0  
                      )
```

Set pResult to the normalized of pVec0.

Parameters

[out] **pResult** Pointer to **AEVec2** to be set.

[in] **pVec0** Pointer to **AEVec2** for input.

Return values

void No return.

```
void AEVec2Project ( AEVec2 * pResult,  
                   AEVec2 * pVec0,  
                   AEVec2 * pVec1  
                   )
```

Set pResult to the projection of pVec1 onto pVec0.

Parameters

- [out] **pResult** Pointer to **AEVec2** to be set.
- [in] **pVec0** Pointer to **AEVec2** for input.
- [in] **pVec1** Pointer to **AEVec2** for input.

Return values

void No return.

```
void AEVec2ProjectPerp ( AEVec2 * pResult,  
                        AEVec2 * pVec0,  
                        AEVec2 * pVec1  
                        )
```

Set pResult to the perpendicular projection (rejection) of pVec0 onto pVec1.

Parameters

- [out] **pResult** Pointer to **AEVec2** to be set.
- [in] **pVec0** Pointer to **AEVec2** for input.
- [in] **pVec1** Pointer to **AEVec2** for input.

Return values

void No return.

```
void AEVec2Scale ( AEVec2 * pResult,  
                  AEVec2 * pVec0,  
                  f32      s  
                  )
```

Set pResult to (pVec0 * s).

Parameters

- [out] **pResult** Pointer to **AEVec2** to be set.

[in] **pVec0** Pointer to **AEVec2** for input.
[in] **s** Value to scale with.

Return values

void No return.

```
void AEVec2ScaleAdd ( AEVec2 * pResult,  
                     AEVec2 * pVec0,  
                     AEVec2 * pVec1,  
                     f32      s  
                     )
```

Set pResult to ((pVec0 + pVec1) * s).

Warning

Purpose unclear or error in implementation.

Parameters

[out] **pResult** Pointer to **AEVec2** to be set.
[in] **pVec0** Pointer to **AEVec2** for input.
[in] **pVec1** Pointer to **AEVec2** for input.
[in] **s** Value to scale with.

Return values

void No return.

```
void AEVec2ScaleSub ( AEVec2 * pResult,  
                     AEVec2 * pVec0,  
                     AEVec2 * pVec1,  
                     f32      s  
                     )
```

Set pResult to ((pVec0 - pVec1) * s).

Warning

Purpose unclear or error in implementation.

Parameters

- [out] **pResult** Pointer to **AEVec2** to be set.
- [in] **pVec0** Pointer to **AEVec2** for input.
- [in] **pVec1** Pointer to **AEVec2** for input.
- [in] **s** Value to scale with.

Return values

void No return.

```
void AEVec2Set ( AEVec2 * pResult,  
                 f32      x,  
                 f32      y  
                )
```

Set pResult to (x, y).

Parameters

- [out] **pResult** Pointer to **AEVec2** to be set.
- [in] **x** X value to set with.
- [in] **y** Y value to set with.

Return values

void No return.

```
f32 AEVec2SquareDistance ( AEVec2 * pVec0,  
                           AEVec2 * pVec1  
                          )
```

Calculate the squared distance between 2 points.

Parameters

- [in] **pVec0** Pointer to **AEVec2** of first point.
- [in] **pVec1** Pointer to **AEVec2** of second point.

Return values

f32 Returns the squared distance between pVec0 and pVec1.

f32 AEVec2SquareLength (**AEVec2** * **pVec0**)

Calculate the squared length of pVec0.

Parameters

[in] **pVec0** Pointer to **AEVec2** for input

Return values

f32 Returns the squared length of pVec0.

```
void AEVec2Sub ( AEVec2 * pResult,  
                AEVec2 * pVec0,  
                AEVec2 * pVec1  
                )
```

Set pResult to (pVec0 - pVec1).

Parameters

[out] **pResult** Pointer to **AEVec2** to be set.

[in] **pVec0** Pointer to **AEVec2** for input.

[in] **pVec1** Pointer to **AEVec2** for input.

Return values

void No return.

```
s32 AEVec2Test ( s32 i1,  
                 s32 i2  
                 )
```

void AEVec2Zero (AEVec2 * pResult)

Set pResult to zero.

Parameters

[out] **pResult** Pointer to **AEVec2** to be set.

Return values

void No return.

Alpha Engine

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a	d	e	f	g	h
i	p	r	s	t	u
w					

Here is a list of all file members with links to the files they belong to:

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- AE_ASSERT_ALLOC : [AEEngine.h](#)
- AE_ASSERT_MESG : [AEEngine.h](#)
- AE_ASSERT_PARM : [AEEngine.h](#)
- AE_FATAL_ERROR : [AEEngine.h](#)
- AE_GFX_BM_ADD : [AEGraphics.h](#)
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- AE_GFX_MDM_LINES_STRIP : [AEGraphics.h](#)
- AE_GFX_MDM_NUM : [AEGraphics.h](#)
- AE_GFX_MDM_POINTS : [AEGraphics.h](#)
- AE_GFX_MDM_TRIANGLES : [AEGraphics.h](#)
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- AEVK_B : [AEInput.h](#)
- AEVK_BACK : [AEInput.h](#)
- AEVK_BACKQUOTE : [AEInput.h](#)
- AEVK_BACKSLASH : [AEInput.h](#)
- AEVK_C : [AEInput.h](#)
- AEVK_CAPSLOCK : [AEInput.h](#)
- AEVK_COMMA : [AEInput.h](#)
- AEVK_D : [AEInput.h](#)
- AEVK_DELETE : [AEInput.h](#)
- AEVK_DOWN : [AEInput.h](#)
- AEVK_E : [AEInput.h](#)
- AEVK_END : [AEInput.h](#)

- AEVK_EQUAL : AEInput.h
- AEVK_ESCAPE : AEInput.h
- AEVK_F : AEInput.h
- AEVK_F1 : AEInput.h
- AEVK_F10 : AEInput.h
- AEVK_F11 : AEInput.h
- AEVK_F12 : AEInput.h
- AEVK_F2 : AEInput.h
- AEVK_F3 : AEInput.h
- AEVK_F4 : AEInput.h
- AEVK_F5 : AEInput.h
- AEVK_F6 : AEInput.h
- AEVK_F7 : AEInput.h
- AEVK_F8 : AEInput.h
- AEVK_F9 : AEInput.h
- AEVK_G : AEInput.h
- AEVK_H : AEInput.h
- AEVK_HOME : AEInput.h
- AEVK_I : AEInput.h
- AEVK_INSERT : AEInput.h
- AEVK_J : AEInput.h
- AEVK_K : AEInput.h
- AEVK_L : AEInput.h
- AEVK_LALT : AEInput.h
- AEVK_LBRACKET : AEInput.h
- AEVK_LBUTTON : AEInput.h
- AEVK_LCTRL : AEInput.h
- AEVK_LEFT : AEInput.h
- AEVK_LSHIFT : AEInput.h
- AEVK_M : AEInput.h
- AEVK_MBUTTON : AEInput.h
- AEVK_MINUS : AEInput.h
- AEVK_N : AEInput.h
- AEVK_NUM_DIVIDE : AEInput.h
- AEVK_NUM_MINUS : AEInput.h
- AEVK_NUM_MULTIPLY : AEInput.h
- AEVK_NUM_PERIOD : AEInput.h
- AEVK_NUM_PLUS : AEInput.h
- AEVK_NUMLOCK : AEInput.h
- AEVK_NUMPAD0 : AEInput.h

- AEVK_NUMPAD1 : [AEInput.h](#)
- AEVK_NUMPAD2 : [AEInput.h](#)
- AEVK_NUMPAD3 : [AEInput.h](#)
- AEVK_NUMPAD4 : [AEInput.h](#)
- AEVK_NUMPAD5 : [AEInput.h](#)
- AEVK_NUMPAD6 : [AEInput.h](#)
- AEVK_NUMPAD7 : [AEInput.h](#)
- AEVK_NUMPAD8 : [AEInput.h](#)
- AEVK_NUMPAD9 : [AEInput.h](#)
- AEVK_O : [AEInput.h](#)
- AEVK_P : [AEInput.h](#)
- AEVK_PAGEDOWN : [AEInput.h](#)
- AEVK_PAGEUP : [AEInput.h](#)
- AEVK_PAUSE : [AEInput.h](#)
- AEVK_PERIOD : [AEInput.h](#)
- AEVK_PRINTSCREEN : [AEInput.h](#)
- AEVK_Q : [AEInput.h](#)
- AEVK_QUOTE : [AEInput.h](#)
- AEVK_R : [AEInput.h](#)
- AEVK_RALT : [AEInput.h](#)
- AEVK_RBACKET : [AEInput.h](#)
- AEVK_RBUTTON : [AEInput.h](#)
- AEVK_RCTRL : [AEInput.h](#)
- AEVK_RETURN : [AEInput.h](#)
- AEVK_RIGHT : [AEInput.h](#)
- AEVK_RSHIFT : [AEInput.h](#)
- AEVK_S : [AEInput.h](#)
- AEVK_SCROLLLOCK : [AEInput.h](#)
- AEVK_SEMICOLON : [AEInput.h](#)
- AEVK_SLASH : [AEInput.h](#)
- AEVK_SPACE : [AEInput.h](#)
- AEVK_T : [AEInput.h](#)
- AEVK_TAB : [AEInput.h](#)
- AEVK_U : [AEInput.h](#)
- AEVK_UP : [AEInput.h](#)
- AEVK_V : [AEInput.h](#)
- AEVK_W : [AEInput.h](#)
- AEVK_X : [AEInput.h](#)
- AEVK_Y : [AEInput.h](#)
- AEVK_Z : [AEInput.h](#)

- AEWrap() : **AEMath.h**

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File List		File Members			
All	Functions	Variables	Typedefs	Enumerations	Enumerator
Macros					
a	d	e	f	g	h
i	p	r	s	t	u
w					

Here is a list of all file members with links to the files they belong to:

- d -

- DECLARE_FUNCTION_FOR_ANDROID : [AExport.h](#) , [AEGraphics.h](#)
- DECLARE_FUNCTION_FOR_ANDROID_2_INT : [AExport.h](#) , [AEGraphics.h](#)

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All	Functions	Variables	Typedefs	Enumerations	Enumerator
Macros					
a	d	e	f	g	h
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w					

Here is a list of all file members with links to the files they belong to:

- e -

- EPSILON : [AEEExport.h](#)
- EXPORT_ANDROID : [AEEExport.h](#)
- EXPORT_WINDOWS : [AEEExport.h](#)

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Macros					
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i	p	r	s	t	u
w					

Here is a list of all file members with links to the files they belong to:

- f -

- f32 : [AETypes.h](#)
- f64 : [AETypes.h](#)

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All	Functions	Variables	Typedefs	Enumerations	Enumerator
Macros					
a	d	e	f	g	h
i	p	r	s	t	u
w					

Here is a list of all file members with links to the files they belong to:

- g -

- gAEGameStateCurr : [AEGameStateMgr.h](#)
- gAEGameStateInit : [AEGameStateMgr.h](#)
- gAEGameStateNext : [AEGameStateMgr.h](#)
- gAEGameStatePrev : [AEGameStateMgr.h](#)
- gAESysAppActive : [AESystem.h](#)
- gAESysWindowHandle : [AESystem.h](#)
- ghAESysAppInstance : [AESystem.h](#)
- gpAESysWinClassName : [AESystem.h](#)
- gpAESysWinTitle : [AESystem.h](#)

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File List		File Members			
All	Functions	Variables	Typedefs	Enumerations	Enumerator
Macros					
a	d	e	f	g	h
i	p	r	s	t	u
w					

Here is a list of all file members with links to the files they belong to:

- h -

- HALF_PI : [AEEExport.h](#)

Alpha Engine

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File List		File Members			
All	Functions	Variables	Typedefs	Enumerations	Enumerator
Macros					
a	d	e	f	g	h
i	p	r	s	t	u
w					

Here is a list of all file members with links to the files they belong to:

- i -

- IMPLEMENT_FUNCTION_FOR_ANDROID : [AExport.h](#)
- IMPLEMENT_FUNCTION_FOR_ANDROID_2_INT : [AExport.h](#)
- isEqual : [AEUtil.h](#)
- isZero : [AEUtil.h](#)

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File List		File Members										
All	Functions	Variables	Typedefs	Enumerations	Enumerator							
Macros												
a	d	e	f	g	h	i	p	r	s	t	u	w

Here is a list of all file members with links to the files they belong to:

- p -

- PI : [AEEExport.h](#)
- PRINT : [AEEExport.h](#)
- PRINT_INFO : [AEEExport.h](#)

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Main Page		Classes		Files								
File List		File Members										
All	Functions	Variables	Typedefs	Enumerations	Enumerator							
Macros												
a	d	e	f	g	h	i	p	r	s	t	u	w

Here is a list of all file members with links to the files they belong to:

- r -

- ReadFromFile() : [AEUtil.h](#)

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Main Page		Classes		Files								
File List		File Members										
All	Functions	Variables	Typedefs	Enumerations	Enumerator							
Macros												
a	d	e	f	g	h	i	p	r	s	t	u	w

Here is a list of all file members with links to the files they belong to:

- S -

- s16 : [AETypes.h](#)
- s32 : [AETypes.h](#)
- s64 : [AETypes.h](#)
- s8 : [AETypes.h](#)

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Main Page			Classes			Files						
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Macros												
a	d	e	f	g	h	i	p	r	s	t	u	w

Here is a list of all file members with links to the files they belong to:

- t -

- TWO_PI : [AEEExport.h](#)

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Main Page		Classes		Files								
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All	Functions	Variables	Typedefs	Enumerations	Enumerator							
Macros												
a	d	e	f	g	h	i	p	r	s	t	u	w

Here is a list of all file members with links to the files they belong to:

- u -

- u16 : [AETypes.h](#)
- u32 : [AETypes.h](#)
- u64 : [AETypes.h](#)
- u8 : [AETypes.h](#)

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All	Functions	Variables	Typedefs	Enumerations	Enumerator							
Macros												
a	d	e	f	g	h	i	p	r	s	t	u	w

Here is a list of all file members with links to the files they belong to:

- **W** -

- winClass : [AESystem.h](#)

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a	d	r				

- a -

- AEACos() : [AEMath.h](#)
- AEAnimatedCircleToStaticCircle() : [AEMath.h](#)
- AEAnimatedCircleToStaticLineSegment() : [AEMath.h](#)
- AEAnimatedPointToStaticCircle() : [AEMath.h](#)
- AEAnimatedPointToStaticLineSegment() : [AEMath.h](#)
- AEASin() : [AEMath.h](#)
- AEATan() : [AEMath.h](#)
- AEBuildLineSegment2() : [AELineSegment2.h](#)
- AECalcDistCircleToCircle() : [AEMath.h](#)
- AECalcDistCircleToRect() : [AEMath.h](#)
- AECalcDistPointToCircle() : [AEMath.h](#)
- AECalcDistPointToConvexPoly() : [AEMath.h](#)
- AECalcDistPointToLineSeg() : [AEMath.h](#)
- AECalcDistPointToRect() : [AEMath.h](#)
- AECalcDistRectToRect() : [AEMath.h](#)
- AEClamp() : [AEMath.h](#)
- AECos() : [AEMath.h](#)
- AEDegToRad() : [AEMath.h](#)
- AEFrameRateControllerEnd() : [AEFrameRateController.h](#)
- AEFrameRateControllerGetFrameCount() : [AEFrameRateController.h](#)
- AEFrameRateControllerGetFrameTime() : [AEFrameRateController.h](#)
- AEFrameRateControllerInit() : [AEFrameRateController.h](#)
- AEFrameRateControllerReset() : [AEFrameRateController.h](#)

- AEFramerateControllerStart() : **AEFrameRateController.h**
- AEGameStateMgrAdd() : **AEGameStateMgr.h**
- AEGameStateMgrInit() : **AEGameStateMgr.h**
- AEGameStateMgrUpdate() : **AEGameStateMgr.h**
- AEGetTime() : **AEUtil.h**
- AEGfxAxis() : **AEGraphics.h**
- AEGfxBox() : **AEGraphics.h**
- AEGfxCollInterp() : **AEGraphics.h**
- AEGfxCone() : **AEGraphics.h**
- AEGfxEnd() : **AEGraphics.h**
- AEGfxExit() : **AEGraphics.h**
- AEGfxGetCamPosition() : **AEGraphics.h**
- AEGfxGetWinMaxX() : **AEGraphics.h**
- AEGfxGetWinMaxY() : **AEGraphics.h**
- AEGfxGetWinMinX() : **AEGraphics.h**
- AEGfxGetWinMinY() : **AEGraphics.h**
- AEGfxInit() : **AEGraphics.h**
- AEGfxLine() : **AEGraphics.h**
- AEGfxMeshDraw() : **AEGraphics.h**
- AEGfxMeshEnd() : **AEGraphics.h**
- AEGfxMeshFree() : **AEGraphics.h**
- AEGfxMeshStart() : **AEGraphics.h**
- AEGfxPoint() : **AEGraphics.h**
- AEGfxPrint() : **AEGraphics.h**
- AEGfxQuad() : **AEGraphics.h**
- AEGfxReset() : **AEGraphics.h**
- AEGfxSaveTextureToFile() : **AEGraphics.h**
- AEGfxSetBackgroundColor() : **AEGraphics.h**
- AEGfxSetBlendColor() : **AEGraphics.h**
- AEGfxSetBlendMode() : **AEGraphics.h**
- AEGfxSetCamPosition() : **AEGraphics.h**
- AEGfxSetPosition() : **AEGraphics.h**
- AEGfxSetRenderMode() : **AEGraphics.h**
- AEGfxSetTextureMode() : **AEGraphics.h**
- AEGfxSetTintColor() : **AEGraphics.h**
- AEGfxSetTransform() : **AEGraphics.h**
- AEGfxSetTransform3D() : **AEGraphics.h**
- AEGfxSetTransparency() : **AEGraphics.h**
- AEGfxSphere() : **AEGraphics.h**
- AEGfxStart() : **AEGraphics.h**

- AEGfxTextureLoad() : **AEGraphics.h**
- AEGfxTextureLoadFromMemory() : **AEGraphics.h**
- AEGfxTextureSet() : **AEGraphics.h**
- AEGfxTextureUnload() : **AEGraphics.h**
- AEGfxTri() : **AEGraphics.h**
- AEGfxTriAdd() : **AEGraphics.h**
- AEGfxVertexAdd() : **AEGraphics.h**
- AEInputCheckCurr() : **AEInput.h**
- AEInputCheckPrev() : **AEInput.h**
- AEInputCheckReleased() : **AEInput.h**
- AEInputCheckTriggered() : **AEInput.h**
- AEInputExit() : **AEInput.h**
- AEInputGetCursorPosition() : **AEInput.h**
- AEInputGetCursorPositionDelta() : **AEInput.h**
- AEInputInit() : **AEInput.h**
- AEInputReset() : **AEInput.h**
- AEInputShowCursor() : **AEInput.h**
- AEInputUpdate() : **AEInput.h**
- AEInRange() : **AEMath.h**
- AEIsPowOf2() : **AEMath.h**
- AELogBase2() : **AEMath.h**
- AEMax() : **AEMath.h**
- AEMin() : **AEMath.h**
- AEMtx33Concat() : **AEMtx33.h**
- AEMtx33Determinant() : **AEMtx33.h**
- AEMtx33GetCol() : **AEMtx33.h**
- AEMtx33GetRow() : **AEMtx33.h**
- AEMtx33Identity() : **AEMtx33.h**
- AEMtx33Inverse() : **AEMtx33.h**
- AEMtx33InvTranspose() : **AEMtx33.h**
- AEMtx33MultVec() : **AEMtx33.h**
- AEMtx33MultVecArray() : **AEMtx33.h**
- AEMtx33MultVecArraySR() : **AEMtx33.h**
- AEMtx33MultVecSR() : **AEMtx33.h**
- AEMtx33Orthogonalize() : **AEMtx33.h**
- AEMtx33Rot() : **AEMtx33.h**
- AEMtx33RotDeg() : **AEMtx33.h**
- AEMtx33Scale() : **AEMtx33.h**
- AEMtx33ScaleApply() : **AEMtx33.h**
- AEMtx33SetCol() : **AEMtx33.h**

- AEMtx33SetRow() : [AEMtx33.h](#)
- AEMtx33Trans() : [AEMtx33.h](#)
- AEMtx33TransApply() : [AEMtx33.h](#)
- AEMtx33Transpose() : [AEMtx33.h](#)
- AENextPowOf2() : [AEMath.h](#)
- AERadToDeg() : [AEMath.h](#)
- AERandFloat() : [AEUtil.h](#)
- AEReflectAnimatedCircleOnStaticCircle() : [AEMath.h](#)
- AEReflectAnimatedCircleOnStaticLineSegment() : [AEMath.h](#)
- AEReflectAnimatedPointOnStaticCircle() : [AEMath.h](#)
- AEReflectAnimatedPointOnStaticLineSegment() : [AEMath.h](#)
- AESin() : [AEMath.h](#)
- AESTaticPointToStaticLineSegment() : [AEMath.h](#)
- AESysDoesWindowExist() : [AESystem.h](#)
- AESysExit() : [AESystem.h](#)
- AESysFrameEnd() : [AESystem.h](#)
- AESysFrameStart() : [AESystem.h](#)
- AESysGetWindowHandle() : [AESystem.h](#)
- AESysInit() : [AESystem.h](#)
- AESysReset() : [AESystem.h](#)
- AESysSetWindowTitle() : [AESystem.h](#)
- AETan() : [AEMath.h](#)
- AETestCircleToCircle() : [AEMath.h](#)
- AETestCircleToRect() : [AEMath.h](#)
- AETestPointToCircle() : [AEMath.h](#)
- AETestPointToRect() : [AEMath.h](#)
- AETestRectToRect() : [AEMath.h](#)
- AEVec2Add() : [AEVec2.h](#)
- AEVec2CrossProductMag() : [AEVec2.h](#)
- AEVec2Distance() : [AEVec2.h](#)
- AEVec2DotProduct() : [AEVec2.h](#)
- AEVec2FromAngle() : [AEVec2.h](#)
- AEVec2Length() : [AEVec2.h](#)
- AEVec2Lerp() : [AEVec2.h](#)
- AEVec2Neg() : [AEVec2.h](#)
- AEVec2Normalize() : [AEVec2.h](#)
- AEVec2Project() : [AEVec2.h](#)
- AEVec2ProjectPerp() : [AEVec2.h](#)
- AEVec2Scale() : [AEVec2.h](#)
- AEVec2ScaleAdd() : [AEVec2.h](#)

- AVec2ScaleSub() : [AEVec2.h](#)
- AVec2Set() : [AEVec2.h](#)
- AVec2SquareDistance() : [AEVec2.h](#)
- AVec2SquareLength() : [AEVec2.h](#)
- AVec2Sub() : [AEVec2.h](#)
- AVec2Test() : [AEVec2.h](#)
- AVec2Zero() : [AEVec2.h](#)
- AWrap() : [AEMath.h](#)

- d -

- DECLARE_FUNCTION_FOR_ANDROID() : [AEGraphics.h](#)
- DECLARE_FUNCTION_FOR_ANDROID_2_INT() : [AEGraphics.h](#)

- r -

- ReadFromFile() : [AEUtil.h](#)

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Macros						

- AEGameStateDraw : [AEGameStateMgr.h](#)
- AEGameStateFree : [AEGameStateMgr.h](#)
- AEGameStateInit : [AEGameStateMgr.h](#)
- AEGameStateLoad : [AEGameStateMgr.h](#)
- AEGameStateUnload : [AEGameStateMgr.h](#)
- AEGameStateUpdate : [AEGameStateMgr.h](#)
- gAEGameStateCurr : [AEGameStateMgr.h](#)
- gAEGameStateInit : [AEGameStateMgr.h](#)
- gAEGameStateNext : [AEGameStateMgr.h](#)
- gAEGameStatePrev : [AEGameStateMgr.h](#)
- gAESysAppActive : [AESystem.h](#)
- gAESysWindowHandle : [AESystem.h](#)
- ghAESysAppInstance : [AESystem.h](#)
- gpAESysWinClassName : [AESystem.h](#)
- gpAESysWinTitle : [AESystem.h](#)
- winClass : [AESystem.h](#)

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Macros					

- AEGfxSurface : [AEGraphics.h](#)
- AEGfxTexture : [AEGraphics.h](#)
- AEGfxVertexBuffer : [AEGraphics.h](#)
- AEGfxVertexList : [AEGraphics.h](#)
- AELineSegment2 : [AELineSegment2.h](#)
- AEMtx33 : [AEMtx33.h](#)
- AEVec2 : [AEVec2.h](#)
- f32 : [AETypes.h](#)
- f64 : [AETypes.h](#)
- s16 : [AETypes.h](#)
- s32 : [AETypes.h](#)
- s64 : [AETypes.h](#)
- s8 : [AETypes.h](#)
- u16 : [AETypes.h](#)
- u32 : [AETypes.h](#)
- u64 : [AETypes.h](#)
- u8 : [AETypes.h](#)

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- AEGfxBlendMode : [AEGraphics.h](#)
- AEGfxMeshDrawMode : [AEGraphics.h](#)
- AEGfxRenderMode : [AEGraphics.h](#)
- AEGfxTextureMode : [AEGraphics.h](#)

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Macros					

- AE_GFX_BM_ADD : [AEGraphics.h](#)
- AE_GFX_BM_BLEND : [AEGraphics.h](#)
- AE_GFX_BM_NONE : [AEGraphics.h](#)
- AE_GFX_BM_NUM : [AEGraphics.h](#)
- AE_GFX_MDM_LINES : [AEGraphics.h](#)
- AE_GFX_MDM_LINES_STRIP : [AEGraphics.h](#)
- AE_GFX_MDM_NUM : [AEGraphics.h](#)
- AE_GFX_MDM_POINTS : [AEGraphics.h](#)
- AE_GFX_MDM_TRIANGLES : [AEGraphics.h](#)
- AE_GFX_RM_COLOR : [AEGraphics.h](#)
- AE_GFX_RM_NONE : [AEGraphics.h](#)
- AE_GFX_RM_NUM : [AEGraphics.h](#)
- AE_GFX_RM_TEXTURE : [AEGraphics.h](#)
- AE_GFX_TM_AVERAGE : [AEGraphics.h](#)
- AE_GFX_TM_PRECISE : [AEGraphics.h](#)

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All	Functions	Variables	Typedefs	Enumerations	Enumerator
Macros					
a	d	e	h	i	p t

- a -

- AE_API : [AExport.h](#)
- AE_ASSERT : [AEEngine.h](#)
- AE_ASSERT_ALLOC : [AEEngine.h](#)
- AE_ASSERT_MESG : [AEEngine.h](#)
- AE_ASSERT_PARM : [AEEngine.h](#)
- AE_FATAL_ERROR : [AEEngine.h](#)
- AE_GS_QUIT : [AEGameStateMgr.h](#)
- AE_GS_RESTART : [AEGameStateMgr.h](#)
- AE_WARNING : [AEEngine.h](#)
- AE_WARNING_MESG : [AEEngine.h](#)
- AE_WARNING_PARM : [AEEngine.h](#)
- AECosDeg : [AEMath.h](#)
- AEASinDeg : [AEMath.h](#)
- AEATanDeg : [AEMath.h](#)
- AECosDeg : [AEMath.h](#)
- AEMtx33RowCol : [AEMtx33.h](#)
- AESinDeg : [AEMath.h](#)
- AETanDeg : [AEMath.h](#)
- AEVK_0 : [AEInput.h](#)
- AEVK_1 : [AEInput.h](#)
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- AEVK_3 : [AEInput.h](#)
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- AEVK_5 : [AEInput.h](#)
- AEVK_6 : [AEInput.h](#)

- AEVK_7 : AEInput.h
- AEVK_8 : AEInput.h
- AEVK_9 : AEInput.h
- AEVK_A : AEInput.h
- AEVK_B : AEInput.h
- AEVK_BACK : AEInput.h
- AEVK_BACKQUOTE : AEInput.h
- AEVK_BACKSLASH : AEInput.h
- AEVK_C : AEInput.h
- AEVK_CAPSLOCK : AEInput.h
- AEVK_COMMA : AEInput.h
- AEVK_D : AEInput.h
- AEVK_DELETE : AEInput.h
- AEVK_DOWN : AEInput.h
- AEVK_E : AEInput.h
- AEVK_END : AEInput.h
- AEVK_EQUAL : AEInput.h
- AEVK_ESCAPE : AEInput.h
- AEVK_F : AEInput.h
- AEVK_F1 : AEInput.h
- AEVK_F10 : AEInput.h
- AEVK_F11 : AEInput.h
- AEVK_F12 : AEInput.h
- AEVK_F2 : AEInput.h
- AEVK_F3 : AEInput.h
- AEVK_F4 : AEInput.h
- AEVK_F5 : AEInput.h
- AEVK_F6 : AEInput.h
- AEVK_F7 : AEInput.h
- AEVK_F8 : AEInput.h
- AEVK_F9 : AEInput.h
- AEVK_G : AEInput.h
- AEVK_H : AEInput.h
- AEVK_HOME : AEInput.h
- AEVK_I : AEInput.h
- AEVK_INSERT : AEInput.h
- AEVK_J : AEInput.h
- AEVK_K : AEInput.h
- AEVK_L : AEInput.h
- AEVK_LALT : AEInput.h

- AEVK_LBRACKET : AEInput.h
- AEVK_LBUTTON : AEInput.h
- AEVK_LCTRL : AEInput.h
- AEVK_LEFT : AEInput.h
- AEVK_LSHIFT : AEInput.h
- AEVK_M : AEInput.h
- AEVK_MBUTTON : AEInput.h
- AEVK_MINUS : AEInput.h
- AEVK_N : AEInput.h
- AEVK_NUM_DIVIDE : AEInput.h
- AEVK_NUM_MINUS : AEInput.h
- AEVK_NUM_MULTIPLY : AEInput.h
- AEVK_NUM_PERIOD : AEInput.h
- AEVK_NUM_PLUS : AEInput.h
- AEVK_NUMLOCK : AEInput.h
- AEVK_NUMPAD0 : AEInput.h
- AEVK_NUMPAD1 : AEInput.h
- AEVK_NUMPAD2 : AEInput.h
- AEVK_NUMPAD3 : AEInput.h
- AEVK_NUMPAD4 : AEInput.h
- AEVK_NUMPAD5 : AEInput.h
- AEVK_NUMPAD6 : AEInput.h
- AEVK_NUMPAD7 : AEInput.h
- AEVK_NUMPAD8 : AEInput.h
- AEVK_NUMPAD9 : AEInput.h
- AEVK_O : AEInput.h
- AEVK_P : AEInput.h
- AEVK_PAGEDOWN : AEInput.h
- AEVK_PAGEUP : AEInput.h
- AEVK_PAUSE : AEInput.h
- AEVK_PERIOD : AEInput.h
- AEVK_PRINTSCREEN : AEInput.h
- AEVK_Q : AEInput.h
- AEVK_QUOTE : AEInput.h
- AEVK_R : AEInput.h
- AEVK_RALT : AEInput.h
- AEVK_RBRACKET : AEInput.h
- AEVK_RBUTTON : AEInput.h
- AEVK_RCTRL : AEInput.h
- AEVK_RETURN : AEInput.h

- AEVK_RIGHT : [AEInput.h](#)
- AEVK_RSHIFT : [AEInput.h](#)
- AEVK_S : [AEInput.h](#)
- AEVK_SCROLLLOCK : [AEInput.h](#)
- AEVK_SEMICOLON : [AEInput.h](#)
- AEVK_SLASH : [AEInput.h](#)
- AEVK_SPACE : [AEInput.h](#)
- AEVK_T : [AEInput.h](#)
- AEVK_TAB : [AEInput.h](#)
- AEVK_U : [AEInput.h](#)
- AEVK_UP : [AEInput.h](#)
- AEVK_V : [AEInput.h](#)
- AEVK_W : [AEInput.h](#)
- AEVK_X : [AEInput.h](#)
- AEVK_Y : [AEInput.h](#)
- AEVK_Z : [AEInput.h](#)

- d -

- DECLARE_FUNCTION_FOR_ANDROID : [AExport.h](#)
- DECLARE_FUNCTION_FOR_ANDROID_2_INT : [AExport.h](#)

- e -

- EPSILON : [AExport.h](#)
- EXPORT_ANDROID : [AExport.h](#)
- EXPORT_WINDOWS : [AExport.h](#)

- h -

- HALF_PI : [AExport.h](#)

- i -

- IMPLEMENT_FUNCTION_FOR_ANDROID : [AExport.h](#)
- IMPLEMENT_FUNCTION_FOR_ANDROID_2_INT : [AExport.h](#)
- isEqual : [AEUtil.h](#)
- isZero : [AEUtil.h](#)

- p -

- PI : [AEEExport.h](#)
- PRINT : [AEEExport.h](#)
- PRINT_INFO : [AEEExport.h](#)

- t -

- TWO_PI : [AEEExport.h](#)

Alpha Engine

Main Page	Classes	Files	
Class List	Class Members		

AEGfxTexture Member List

This is the complete list of members for **AEGfxTexture**, including all inherited members.

mpName **AEGfxTexture**
mpSurface **AEGfxTexture**

Alpha Engine

Main Page	Classes	Files
File List	File Members	
include		

AEGraphics.h

[Go to the documentation of this file.](#)

```
1  /*****
   *****/
15 /*****
   *****/
16
17 #ifndef AE_GRAPHICS_H
18 #define AE_GRAPHICS_H
19
20 // -----
   -----
21 // Defines
22
24 typedef enum
25 {
26     AE_GFX_RM_NONE,
27     AE_GFX_RM_COLOR,
28     AE_GFX_RM_TEXTURE,
29
30     AE_GFX_RM_NUM
31 } AEGfxRenderMode;
32
33
34 // -----
   -----
35
37 typedef enum
```

```

38 | {
39 |     AE_GFX_BM_NONE = 0,
40 |     AE_GFX_BM_BLEND,
41 |     AE_GFX_BM_ADD,
42 |
43 |     AE_GFX_BM_NUM
44 | }AEGfxBlendMode;
45 |
46 | // -----
47 |
48 | typedef enum
49 | {
50 |     AE_GFX_TM_PRECISE = 0,
51 |     AE_GFX_TM_AVERAGE
52 | }AEGfxTextureMode;
53 |
54 | // -----
55 |
56 | typedef enum
57 | {
58 |     AE_GFX_MDM_POINTS = 0,
59 |     AE_GFX_MDM_LINES,
60 |     AE_GFX_MDM_LINES_STRIP,
61 |     AE_GFX_MDM_TRIANGLES,
62 |
63 |     // Keep this one last
64 |     AE_GFX_MDM_NUM
65 | }AEGfxMeshDrawMode;
66 |
67 | // -----
68 | // Struct/Class definitions
69 |
70 | typedef struct AEGfxVertexBuffer
    AEGfxVertexBuffer;

```

```

71 |
72 | typedef struct AEGfxVertexList
73 | {
74 |     AEGfxVertexBuffer      *mpVtxBuffer;
75 |     u32 vtxNum;
76 | }AEGfxVertexList;
77 |
78 | // -----
    | -----
79 |
80 | typedef struct AEGfxSurface AEGfxSurface;
81 |
82 | typedef struct AEGfxTexture
83 | {
84 |     AEGfxSurface *mpSurface;
85 |     s8 mpName[256];
86 | }AEGfxTexture;
87 |
88 | // -----
    | -----
89 | // Extern variables
90 |
91 | // -----
    | -----
92 | // Function prototypes
93 | // -----
    | -----
94 |
95 | #ifdef __cplusplus
96 |
97 | extern "C"
98 | {
99 | #endif
100 |
101 | // -----
    | -----
102 |

```

```

103  /*****
    *****/
122  /*****
    *****/
123  AE_API s32 AEGfxInit(s32 Width, s32 Height);
124  DECLARE_FUNCTION_FOR_ANDROID_2_INT(AEGfxInit,
    s32 Width, s32 Height);
125
126  /*****
    *****/
137  /*****
    *****/
138  AE_API void AEGfxReset();
139
140  /*****
    *****/
151  /*****
    *****/
152  AE_API void AEGfxExit();
153
154  /*****
    *****/
165  /*****
    *****/
166  AE_API void AEGfxStart();
167  DECLARE_FUNCTION_FOR_ANDROID(AEGfxStart);
168
169  /*****
    *****/
180  /*****
    *****/
181  AE_API void AEGfxEnd();
182  DECLARE_FUNCTION_FOR_ANDROID(AEGfxEnd);
183
184  /*****
    *****/
204  /*****

```

```

    *****/
205 | AE_API void AEGfxSetBackgroundColor(f32 Red,
    f32 Green, f32 Blue);
206 |
207 | /***/
    *****/
223 | /***/
    *****/
224 | AE_API void
    AEGfxSetRenderMode(AEGfxRenderMode RenderMode);
225 |
226 | /***/
    *****/
238 | /***/
    *****/
239 | AE_API void AEGfxSetBlendMode(AEGfxBlendMode
    BlendMode);
240 |
241 | /***/
    *****/
250 | /***/
    *****/
251 | AE_API f32 AEGfxGetWinMinX(void);
252 |
253 | /***/
    *****/
262 | /***/
    *****/
263 | AE_API f32 AEGfxGetWinMaxX(void);
264 |
265 | /***/
    *****/
274 | /***/
    *****/
275 | AE_API f32 AEGfxGetWinMinY(void);
276 |
277 | /***/

```

```

    *****/
286 | /*****
    *****/
287 | AE_API f32 AEGfxGetWinMaxY(void);
288 |
289 | /*****
    *****/
304 | /*****
    *****/
305 | AE_API void AEGfxSetCamPosition(f32 X, f32
    Y);
306 |
307 | /*****
    *****/
322 | /*****
    *****/
323 | AE_API void AEGfxGetCamPosition(f32 *pX, f32
    *pY);
324 |
325 | // Sets/Gets the camera distance, used to
    zoom in/out
326 | //AE_API void AEGfxSetCamZoom(f32 Distance);
327 | //AE_API f32 AEGfxGetCamZoom();
328 |
329 | /*****
    *****/
344 | /*****
    *****/
345 | AE_API void AEGfxSetPosition(f32 X, f32 Y);
346 |
347 | /*****
    *****/
363 | /*****
    *****/
364 | AE_API void AEGfxSetTransform(f32
    pTransform[3][3]);
365 |

```

```

366 | /*****
      | *****/
381 | /*****
      | *****/
382 | AE_API void AEGfxSetTransform3D(f32
      | pTransform[4][4]);
383 |
384 | /*****
      | *****/
400 | /*****
      | *****/
401 | AE_API void AEGfxSetTransparency(f32 Alpha);
402 |
403 | /*****
      | *****/
429 | /*****
      | *****/
430 | AE_API void AEGfxSetBlendColor(f32 Red, f32
      | Green, f32 Blue, f32 Alpha);
431 |
432 | /*****
      | *****/
458 | /*****
      | *****/
459 | AE_API void AEGfxSetTintColor(float Red,
      | float Green, float Blue, float Alpha);
460 |
461 | /*****
      | *****/
473 | /*****
      | *****/
474 | AE_API void AEGfxMeshStart ();
475 |
476 | /*****
      | *****/
536 | /*****
      | *****/

```

```

537 | AE_API void AEGfxTriAdd      (f32 x0, f32 y0,
    |      u32 c0, f32 tu0, f32 tv0,
538 |                                f32
    |      x1, f32 y1, u32 c1, f32 tu1, f32 tv1,
539 |                                f32
    |      x2, f32 y2, u32 c2, f32 tu2, f32 tv2);
540 |
541 | /*****
    | *****/
571 | /*****
    | *****/
572 | AE_API void AEGfxVertexAdd  (f32 x0, f32 y0,
    |      u32 c0, f32 tu0, f32 tv0);
573 |
574 | /*****
    | *****/
586 | /*****
    | *****/
587 | AE_API AEGfxVertexList* AEGfxMeshEnd      ();
588 |
589 | /*****
    | *****/
608 | /*****
    | *****/
609 | AE_API void AEGfxMeshDraw  (AEGfxVertexList*
    |      pVertexList, AEGfxMeshDrawMode MeshDrawMode);
610 |
611 | /*****
    | *****/
626 | /*****
    | *****/
627 | AE_API void AEGfxMeshFree  (AEGfxVertexList*
    |      pVertexList);
628 |
629 | /*****
    | *****/
642 | /*****

```



```

        *****/
643 | AE_API AEGfxTexture*
    AEGfxTextureLoad(const s8 *pFileName);
644 |
645 | /***/
    *****/
666 | /***/
    *****/
667 | AE_API void AEGfxTextureSet(AEGfxTexture
    *pTexture, f32 offset_x, f32 offset_y);
668 |
669 | /***/
    *****/
681 | /***/
    *****/
682 | AE_API void AEGfxTextureUnload(AEGfxTexture
    *pTexture);
683 |
684 | /***/
    *****/
704 | /***/
    *****/
705 | AE_API AEGfxTexture*
    AEGfxTextureLoadFromMemory(u8 *pColors, u32
    width, u32 Height);
706 |
707 | /***/
    *****/
724 | /***/
    *****/
725 | AE_API void
    AEGfxSaveTextureToFile(AEGfxTexture* pTexture,
    s8 *pFileName);
726 |
727 | /***/
    *****/
739 | /***/

```

```

*****/
740 AE_API void
    AEGfxSetTextureMode(AEGfxTextureMode
    TextureMode);
741
742 /*****
    *****/
769 /*****
    *****/
770 AE_API void AEGfxPoint      (f32 x0, f32 y0,
    f32 z0, u32 c0);
771
772 /*****
    *****/
832 /*****
    *****/
833 AE_API void AEGfxLine      (f32 x0, f32 y0,
    f32 z0, f32 r0, f32 g0, f32 b0, f32 a0,
834                                     f32
    x1, f32 y1, f32 z1, f32 r1, f32 g1, f32 b1, f32
    a1);
835
836 /*****
    *****/
890 /*****
    *****/
891 AE_API void AEGfxTri      (f32 x0, f32 y0,
    f32 z0, u32 c0,
892                                     f32
    x1, f32 y1, f32 z1, u32 c1,
893                                     f32
    x2, f32 y2, f32 z2, u32 c2);
894
895 /*****
    *****/
962 /*****
    *****/

```

```

963 | AE_API void AEGfxQuad      (f32 x0, f32 y0,
    | f32 z0, u32 c0,
964 |                               f32
    | x1, f32 y1, f32 z1, u32 c1,
965 |                               f32
    | x2, f32 y2, f32 z2, u32 c2,
966 |                               f32
    | x3, f32 y3, f32 z3, u32 c3);
967 |
968 | /*****
    | *****/
1012 | /*****
    | *****/
1013 | AE_API void AEGfxBox      (f32 x0, f32 y0,
    | f32 z0, f32 sizeX, f32 sizeY, f32 sizeZ, u32
    | c0, u32 c1);
1014 |
1015 | /*****
    | *****/
1059 | /*****
    | *****/
1060 | AE_API void AEGfxSphere   (f32 x0, f32 y0,
    | f32 z0,
1061 |                               f32
    | radius, u32 c0, u32 c1,
1062 |                               u32
    | division);
1063 |
1064 | /*****
    | *****/
1121 | /*****
    | *****/
1122 | AE_API void AEGfxCone      (f32 x0, f32 y0,
    | f32 z0,
1123 |                               f32
    | x1, f32 y1, f32 z1,
1124 |                               f32

```

```

radius, u32 c0, u32 c1, u32 division);
1125 |
1126 | /*****
      *****/
1145 | /*****
      *****/
1146 | AE_API void AEGfxAxis      (f32 scale);
1147 |
1148 | /*****
      *****/
1171 | /*****
      *****/
1172 | AE_API u32 AEGfxColInterp (u32 c0, u32 c1,
      f32 t);
1173 |
1174 | /*****
      *****/
1201 | /*****
      *****/
1202 | AE_API void AEGfxPrint      (s32 x, s32 y,
      u32 color, s8* pStr);
1203 |
1204 | // -----
      -----
1205 |
1206 | #ifdef __cplusplus
1207 | }
1208 | #endif
1209 |
1210 | // -----
      -----
1211 |
1212 | #endif // AE_GRAPHICS_H
1213 |

```

Alpha Engine

Main Page	Classes	Files	
Class List	Class Members		

AEGfxVertexList Member List

This is the complete list of members for [AEGfxVertexList](#), including all inherited members.

mpVtxBuffer	AEGfxVertexList
vtxNum	AEGfxVertexList

Generated on Sat Jan 4 2014 02:06:22 for Alpha Engine by [doxygen](#) 1.8.5

Alpha Engine

Main Page	Classes	Files	
Class List	Class Members		

AELineSegment2 Member List

This is the complete list of members for [AELineSegment2](#), including all inherited members.

mN	AELineSegment2
mNdotP0	AELineSegment2
mP0	AELineSegment2
mP1	AELineSegment2

Alpha Engine

Main Page	Classes	Files
File List	File Members	
include >		

AELineSegment2.h

[Go to the documentation of this file.](#)

```
1  /** *****  
    ***** */  
15 /** *****  
    ***** */  
16  
17 #ifndef AE_LS2_H  
18 #define AE_LS2_H  
19  
20 // -----  
    -----  
21  
22 typedef struct AELineSegment2  
23 {  
24     AVec2 mP0;  
25     AVec2 mP1;  
26     AVec2 mN;  
27     float mNdotP0;  
28 }AELineSegment2;  
29  
30  
31 // -----  
    -----  
32 #ifdef __cplusplus  
33 extern "C"  
34 {  
35 #endif
```

```

36 |
37 | /*****
    | *****/
63 | /*****
    | *****/
64 | AE_API s32 AEBuildLineSegment2(AELineSegment2
    | *pLS, AEVec2 *pPt0, AEVec2 *pPt1);
65 |
66 | #ifdef __cplusplus
67 | }
68 | #endif
69 |
70 | // -----
    | -----
71 |
72 | #endif // VEC2_H

```


Alpha Engine

Main Page	Classes	Files	
Class List	Class Members		

AEMtx33 Member List

This is the complete list of members for [AEMtx33](#), including all inherited members.

m [AEMtx33](#)

Alpha Engine

Main Page	Classes	Files
File List	File Members	
include >		

AEMtx33.h

[Go to the documentation of this file.](#)

```
1  /*****
   *****/
15 /*****
   *****/
16
17 #ifndef AE_MTX33_H
18 #define AE_MTX33_H
19
20 // -----
   -----
21 // Defines
22
23 #define AEMtx33RowCol(pMtx, row, col) (pMtx)-
   >m[(row)][(col)]
24
25 // -----
   -----
26 // Struct/Class definitions
27
36 typedef struct AEMtx33
37 {
38     f32 m[3][3];
39 }AEMtx33;
40
41 // -----
   -----
```

```

42 |
43 | #ifdef __cplusplus
44 | extern "C"
45 | {
46 | #endif
47 |
48 | // -----
   | -----
49 |
50 | /*****
   | *****/
62 | /*****
   | *****/
63 | AE_API void AEMtx33Identity      (AEMtx33*
   | pResult);
64 |
65 | /*****
   | *****/
81 | /*****
   | *****/
82 | AE_API void AEMtx33Transpose    (AEMtx33*
   | pResult, AEMtx33* pMtx);
83 |
84 | /*****
   | *****/
100 | /*****
   | *****/
101 | AE_API f32 AEMtx33Inverse       (AEMtx33*
   | pResult, AEMtx33* pMtx);
102 |
103 | /*****
   | *****/
119 | /*****
   | *****/
120 | AE_API void AEMtx33InvTranspose (AEMtx33*
   | pResult, AEMtx33* pMtx);
121 |

```

```

122 | /*****
    | *****/
142 | /*****
    | *****/
143 | AE_API void AEMtx33Concat      (AEMtx33*
    | pResult, AEMtx33* pMtx0, AEMtx33* pMtx1);
144 |
145 | /*****
    | *****/
163 | /*****
    | *****/
164 | AE_API void AEMtx33Orthogonalize (AEMtx33*
    | pResult, AEMtx33* pMtx);
165 |
166 | /*****
    | *****/
178 | /*****
    | *****/
179 | AE_API f32 AEMtx33Determinant  (AEMtx33*
    | pMtx);
180 |
181 | // -----
    | -----
182 |
183 | /*****
    | *****/
205 | /*****
    | *****/
206 | AE_API void AEMtx33SetCol      (AEMtx33*
    | pResult, u32 col, AVec2* pVec);
207 |
208 | /*****
    | *****/
230 | /*****
    | *****/
231 | AE_API void AEMtx33SetRow      (AEMtx33*
    | pResult, u32 row, AVec2* pVec);

```

```

232 |
233 | /*****
    *****/
254 | /*****
    *****/
255 | AE_API void AEMtx33GetCol      (AEVec2*
    pResult, AEMtx33* pMtx, u32 col);
256 |
257 | /*****
    *****/
278 | /*****
    *****/
279 | AE_API void AEMtx33GetRow      (AEVec2*
    pResult, AEMtx33* pMtx, u32 row);
280 |
281 | // -----
    -----
282 |
283 | /*****
    *****/
303 | /*****
    *****/
304 | AE_API void AEMtx33Trans      (AEMtx33*
    pResult, f32 x, f32 y);
305 |
306 | /*****
    *****/
331 | /*****
    *****/
332 | AE_API void AEMtx33TransApply (AEMtx33*
    pResult, AEMtx33* pMtx, f32 x, f32 y);
333 |
334 | /*****
    *****/
354 | /*****
    *****/
355 | AE_API void AEMtx33Scale      (AEMtx33*

```

```

    pResult, f32 x, f32 y);
356 |
357 | /*****
    *****/
382 | /*****
    *****/
383 | AE_API void AEMtx33ScaleApply      (AEMtx33*
    pResult, AEMtx33* pMtx, f32 x, f32 y);
384 |
385 | /*****
    *****/
402 | /*****
    *****/
403 | AE_API void AEMtx33Rot              (AEMtx33*
    pResult, f32 angle);
404 |
405 | /*****
    *****/
422 | /*****
    *****/
423 | AE_API void AEMtx33RotDeg           (AEMtx33*
    pResult, f32 angle);
424 |
425 | // -----
    -----
426 |
427 | /*****
    *****/
447 | /*****
    *****/
448 | AE_API void AEMtx33MultVec          (AEVec2*
    pResult, AEMtx33* pMtx, AEVec2* pVec);
449 |
450 | /*****
    *****/
477 | /*****
    *****/

```

```

478 | AE_API void AEMtx33MultVecArray    (AEVec2*
      pResult, AEMtx33* pMtx, AEVec2* pVec, u32
      count);
479 |
480 |
481 | AE_API void AEMtx33MultVecSR      (AEVec2*
      pResult, AEMtx33* pMtx, AEVec2* pVec);
482 | AE_API void AEMtx33MultVecArraySR (AEVec2*
      pResult, AEMtx33* pMtx, AEVec2* pVec, u32
      count);
483 |
484 | // -----
      -----
485 |
486 |
487 |
488 |
489 | #ifdef __cplusplus
490 | }
491 | #endif
492 |
493 | #endif // MTX_H

```

Alpha Engine

Main Page	Classes	Files	
Class List	Class Members		

AEVec2 Member List

This is the complete list of members for **AEVec2**, including all inherited members.

x **AEVec2**

y **AEVec2**

Alpha Engine

Main Page	Classes	Files
File List	File Members	
include >		

AEVec2.h

[Go to the documentation of this file.](#)

```
1  /*****
   *****/
15 /*****
   *****/
16
17 #ifndef AE_VEC2_H
18 #define AE_VEC2_H
19
20 #include "AExport.h"
21 #include "ATypes.h"
22
23 // -----
   -----
24
25 //AE_API typedef struct AEVec2
26 typedef struct AEVec2
27 {
28     f32 x, y;
29 }AEVec2;
30
31 // -----
   -----
32 #ifdef __cplusplus
33 extern "C"
34 {
35 #endif
```

```

36 |
37 | //For testing? Function purpose unclear
38 | AE_API s32 AEVec2Test                (s32 i1,
    | s32 i2);
39 |
40 | /*****
    | *****/
52 | /*****
    | *****/
53 | AE_API void AEVec2Zero                (AEVec2*
    | pResult);
54 |
55 | /*****
    | *****/
75 | /*****
    | *****/
76 | AE_API void AEVec2Set                (AEVec2*
    | pResult, f32 x, f32 y);
77 |
78 | /*****
    | *****/
94 | /*****
    | *****/
95 | AE_API void AEVec2Neg                (AEVec2*
    | pResult, AEVec2* pVec0);
96 |
97 | /*****
    | *****/
117 | /*****
    | *****/
118 | AE_API void AEVec2Add                (AEVec2*
    | pResult, AEVec2* pVec0, AEVec2* pVec1);
119 |
120 | /*****
    | *****/
140 | /*****
    | *****/

```

```

141 | AE_API void AEVec2Sub                (AEVec2*
      | pResult, AEVec2* pVec0, AEVec2* pVec1);
142 |
143 | /*****
      | *****/
159 | /*****
      | *****/
160 | AE_API void AEVec2Normalize          (AEVec2*
      | pResult, AEVec2* pVec0);
161 |
162 | /*****
      | *****/
182 | /*****
      | *****/
183 | AE_API void AEVec2Scale              (AEVec2*
      | pResult, AEVec2* pVec0, f32 s);
184 |
185 | /*****
      | *****/
211 | /*****
      | *****/
212 | AE_API void AEVec2ScaleAdd           (AEVec2*
      | pResult, AEVec2* pVec0, AEVec2* pVec1, f32 s);
213 |
214 | /*****
      | *****/
240 | /*****
      | *****/
241 | AE_API void AEVec2ScaleSub           (AEVec2*
      | pResult, AEVec2* pVec0, AEVec2* pVec1, f32 s);
242 |
243 | /*****
      | *****/
263 | /*****
      | *****/
264 | AE_API void AEVec2Project            (AEVec2*
      | pResult, AEVec2* pVec0, AEVec2* pVec1);

```

```

265 |
266 | /*****
    *****/
287 | /*****
    *****/
288 | AE_API void AEVec2ProjectPerp      (AEVec2*
    pResult, AEVec2* pVec0, AEVec2* pVec1);
289 |
290 | /*****
    *****/
319 | /*****
    *****/
320 | AE_API void AEVec2Lerp            (AEVec2*
    pResult, AEVec2* pVec0, AEVec2* pVec1, f32 t);
321 |
322 | /*****
    *****/
334 | /*****
    *****/
335 | AE_API f32 AEVec2Length          (AEVec2*
    pVec0);
336 |
337 | /*****
    *****/
349 | /*****
    *****/
350 | AE_API f32 AEVec2SquareLength    (AEVec2*
    pVec0);
351 |
352 | /*****
    *****/
368 | /*****
    *****/
369 | AE_API f32 AEVec2Distance        (AEVec2*
    pVec0, AEVec2* pVec1);
370 |
371 | /*****

```

```

    *****/
387 | /*****
    *****/
388 | AE_API f32 AEVec2SquareDistance      (AEVec2*
    pVec0, AEVec2* pVec1);
389 |
390 | /*****
    *****/
406 | /*****
    *****/
407 | AE_API f32 AEVec2DotProduct          (AEVec2*
    pVec0, AEVec2* pVec1);
408 |
409 | /*****
    *****/
426 | /*****
    *****/
427 | AE_API f32 AEVec2CrossProductMag     (AEVec2*
    pVec0, AEVec2* pVec1);
428 |
429 | /*****
    *****/
445 | /*****
    *****/
446 | AE_API void AEVec2FromAngle          (AEVec2*
    pResult, f32 angle);
447 |
448 | #ifdef __cplusplus
449 | }
450 | #endif
451 |
452 | // -----
    -----
453 |
454 | #endif // VEC2_H

```

Alpha Engine

Main Page	Classes	Files
File List	File Members	
include		

AEEngine.h

[Go to the documentation of this file.](#)

```
1  /*****
   *****/
29 /*****
   *****/
30
31 #ifndef AE_ENGINE_H
32 #define AE_ENGINE_H
33
34 // -----
   -----
35 // Includes
36 #include <stdlib.h>
37 #include <stdio.h>
38 #include <string.h>
39 #include <assert.h>
40
41 #include <windows.h>
42
43 #include "AExport.h"
44
45 // -----
   -----
46 // assert defines
47
48 #ifndef AE_FINAL    //User should define
   AE_FINAL to remove asserts
```

```

49 |
50 | // -----
   | -----
51 |
52 | #define AE_ASSERT(x)
   | \
53 | {
   | \
54 |     if((x) == 0)
   | \
55 |     {
   | \
56 |         PRINT("AE_ASSERT: %s\nLine: %d\nFunc:
   | %s\nFile: %s\n", \
57 |             #x, __LINE__, __FUNCTION__,
   | __FILE__);
58 |         exit(1);
   | \
59 |     }
   | \
60 | }
61 |
62 | // -----
   | -----
63 |
64 | #define AE_ASSERT_MESG(x, ...)
   | \
65 | {
   | \
66 |     if((x) == 0)
   | \
67 |     {
   | \
68 |         PRINT("AE_ASSERT_MESG: %s\nLine:
   | %d\nFunc: %s\nFile: %s\n", \
69 |             #x, __LINE__, __FUNCTION__,
   | __FILE__);

```

```
70 |         PRINT("Mesg: " __VA_ARGS__);
```

```
71 |         PRINT("\n");
```

```
72 |         exit(1);
```

```
73 |     }
```

```
74 | }
```

```
75 |
```

```
76 | // -----  
-----
```

```
77 |
```

```
78 | #define AE_ASSERT_PARM(x)
```

```
79 | {
```

```
80 |     if((x) == 0)
```

```
81 |     {
```

```
82 |         PRINT("AE_ASSERT_PARM: %s\nLine: %d\nFunc: %s\nFile: %s\n", \
```

```
83 |             #x, __LINE__, __FUNCTION__, \
```

```
__FILE__);
```

```
84 |         exit(1);
```

```
85 |     }
```

```
86 | }
```

```
87 |
```

```
88 | // -----  
-----
```

```
89 |
```

```
90 | #define AE_ASSERT_ALLOC(x)
```

```
91 | {
```



```

\
92 |     if((x) == 0)
\
93 |     {
\
94 |         PRINT("AE_ASSERT_ALLOC: %s\nLine:
%d\nFunc: %s\nFile: %s\n", \
95 |             #x, __LINE__, __FUNCTION__,
__FILE__);
\
96 |         exit(1);
\
97 |     }
\
98 | }
99 |
100 |
101 | // -----
-----

102 |
103 | #define AE_WARNING(x)
\
104 | {
\
105 |     if((x) == 0)
\
106 |     {
\
107 |         PRINT("AE_WARNING: %s\nLine:
%d\nFunc: %s\nFile: %s\n", \
108 |             #x, __LINE__, __FUNCTION__,
__FILE__);
\
109 |     }
\
110 | }
111 |
112 | // -----
-----

```

```

113 |
114 | #define AE_WARNING_MESG(x, ...)
    | \
115 | {
    | \
116 |     if((x) == 0)
    | \
117 |     {
    | \
118 |         PRINT("AE_WARNING_MESG: %s\nLine:
    | %d\nFunc: %s\nFile: %s\n", \
119 |             #x, __LINE__, __FUNCTION__,
    | __FILE__);
120 |         PRINT("Mesg: " __VA_ARGS__);
    | \
121 |         PRINT("\n");
    | \
122 |     }
    | \
123 | }
124 |
125 | // -----
    | -----
126 |
127 | #define AE_WARNING_PARM(x)
    | \
128 | {
    | \
129 |     if((x) == 0)
    | \
130 |     {
    | \
131 |         PRINT("AE_WARNING_PARM: %s\nLine:
    | %d\nFunc: %s\nFile: %s\n", \
132 |             #x, __LINE__, __FUNCTION__,
    | __FILE__);
133 |     }

```

```

\
134 }
135
136 // -----
-----
137
138 #else // AE_FINAL
139
140 // -----
-----
141
142 #define AE_ASSERT(x)
143 #define AE_ASSERT_MESG(x, ...)
144 #define AE_ASSERT_PARM(x)
145 #define AE_ASSERT_ALLOC(x)
146
147 #define AE_WARNING(x)
148 #define AE_WARNING_MESG(x, ...)
149 #define AE_WARNING_PARM(x)
150 #define AE_WARNING_ALLOC(x)
151
152 // -----
-----
153
154 #endif // AE_FINAL
155
156 // -----
-----
157
158 #define AE_FATAL_ERROR(...) \
159 { \
160     PRINT("AE_FATAL_ERROR: "__VA_ARGS__); \
161     exit(1); \
162 }
163
164 // -----
-----

```

```
165 // Alpha engine includes
166
167 #include "AETypes.h" //Typedefs
168 #include "AEMath.h" //Maths library
169 #include "AEUtil.h" //Utility library
170 #include "AEFrameRateController.h" //Frame
    controller
171 #include "AESystem.h" //System library
172 #include "AEGraphics.h" //Graphics library
173 #include "AEInput.h" //Input library
174 #include "AEGameStateMgr.h" //Gamestates
    manager
175
176 // -----
    -----
177
178 #endif // AE_ENGINE_H
179
```

Alpha Engine

Main Page	Classes	Files
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include >		

AEExport.h

[Go to the documentation of this file.](#)

```
1  /*****
   *****/
15 /*****
   *****/
16
17 #ifndef AE_EXPORT_H
18 #define AE_EXPORT_H
19
20 #ifndef EPSILON
21     #define EPSILON 0.00001f
22 #endif
23
24 #ifndef PI
25     #define PI      3.1415926f
26 #endif
27
28 #define HALF_PI (PI * 0.5f)
29 #define TWO_PI  (PI * 2.0f)
30
31
32 #define EXPORT_WINDOWS      1
33 #define EXPORT_ANDROID     0
34
35 #if(1 == EXPORT_WINDOWS)
36
37     #ifdef AE_FINAL
```

```

38 |         #define PRINT(...)
39 |     #else
40 |         #define PRINT(...)
    | printf(__VA_ARGS__)
41 |     #endif
42 |
43 |     #ifdef AE_FINAL
44 |         #define PRINT_INFO(...)
45 |     #else
46 |         #define PRINT_INFO(...) PRINT("File:
    | %s\nLine: %d\nFunc: %s\n\n", \
47 |
    | __FILE__, __LINE__, __FUNCTION__);
48 |     #endif
49 |
50 |
51 |
52 | // #ifdef AE_EXPORTS
53 |     #define AE_API __declspec(dllexport)
54 | // #else
55 | //     #define AE_API __declspec(dllimport)
56 | // #define AE_API
57 | // #endif
58 |
59 |     #define
    | DECLARE_FUNCTION_FOR_ANDROID(functionName)
60 |     #define
    | IMPLEMENT_FUNCTION_FOR_ANDROID(functionName)
61 |
62 |     #define
    | DECLARE_FUNCTION_FOR_ANDROID_2_INT(functionName
    | , paramType1, paramType2)
63 |     #define
    | IMPLEMENT_FUNCTION_FOR_ANDROID_2_INT(functionNa
    | me, paramType1, paramType2)
64 |
65 | #elif(1 == EXPORT_ANDROID)

```

```

66 |
67 |     #include <jni.h>
68 |     #include <android/log.h>
69 |     #define AE_API
70 |     #define LOG_TAG     "AlphaEngine-Lib"
71 |     #define LOGI(...)
        __android_log_print(ANDROID_LOG_INFO, LOG_TAG, __
        VA_ARGS__)
72 |     #define LOGE(...)
        __android_log_print(ANDROID_LOG_ERROR, LOG_TAG, _
        _VA_ARGS__)
73 |
74 |     #ifdef AE_FINAL
75 |         #define PRINT(...)
76 |     #else
77 |         #define PRINT(...) LOGI(__VA_ARGS__)
78 |     #endif
79 |
80 |
81 |
82 |     #define
        DECLARE_FUNCTION_FOR_ANDROID(functionName) \
83 |         JNIEXPORT void
        Java_com_example_alphaengine_AEGLRenderer_##fun
        ctionName(JNIEnv * env, jobject obj);
84 |
85 |     #define
        IMPLEMENT_FUNCTION_FOR_ANDROID(functionName) \
86 |         JNIEXPORT void
        Java_com_example_alphaengine_AEGLRenderer_##fun
        ctionName(JNIEnv * env, jobject obj) \
87 |         { \
88 |             functionName(); \
89 |         }
90 |
91 |
92 |     #define

```

```

    DECLARE_FUNCTION_FOR_ANDROID_2_INT(functionName
    , paramType1, paramType2) \
93 |         JNIEXPORT s32
    Java_com_example_alphaengine_AEGLRenderer_##fun
    ctionName(JNIEnv * env, jobject obj,
    paramType1, paramType2);
94 |
95 |     #define
    IMPLEMENT_FUNCTION_FOR_ANDROID_2_INT(functionNa
    me, paramType1, paramType2) \
96 |         JNIEXPORT s32
    Java_com_example_alphaengine_AEGLRenderer_##fun
    ctionName(JNIEnv * env, jobject obj, paramType1
    param1, paramType2 param2)      \
97 |         {          \
98 |             return functionName(param1,
    param2);          \
99 |         }
100 |
101 | #endif
102 |
103 |
104 |
105 | #endif          // File

```


Alpha Engine

Main Page	Classes	Files
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include		

AEFrameRateController.h

[Go to the documentation of this file.](#)

```
1  /*****
   *****/
15 /*****
   *****/
16
17 #ifndef AE_FRAME_RATE_CONTROLLER_H
18 #define AE_FRAME_RATE_CONTROLLER_H
19
20 // -----
   -----
21 // Externs
22
23 // -----
   -----
24 // Function prototypes
25 // -----
   -----
26
27 #ifdef __cplusplus
28
29 extern "C"
30 {
31 #endif
32
33 // -----
   -----
```

```

34 |
35 | // Frame management
36 |
37 | /*****
    *****/
51 | /*****
    *****/
52 | AE_API void AEFrameRateControllerInit    (u32
    FrameRateMax);
53 |
54 | /*****
    *****/
65 | /*****
    *****/
66 | AE_API void AEFrameRateControllerReset  ();
67 |
68 | /*****
    *****/
80 | /*****
    *****/
81 | AE_API void AEFrameRateControllerStart  ();
82 |
83 | /*****
    *****/
95 | /*****
    *****/
96 | AE_API void AEFrameRateControllerEnd    ();
97 |
98 | /*****
    *****/
107 | /*****
    *****/
108 | AE_API f64
    AEFrameRateControllerGetFrameTime();
109 |
110 | /*****
    *****/

```

```

119 | /*****
      | *****/
120 | AE_API u32
      | AEFrameRateControllerGetFrameCount();
121 |
122 | // -----
      | -----
123 |
124 | #ifdef __cplusplus
125 | }
126 | #endif
127 |
128 | // -----
      | -----
129 |
130 | #endif // AE_FRAME_RATE_CONTROLLER_H
131 |

```

Alpha Engine

Main Page	Classes	Files
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include >		

AEGameStateMgr.h

[Go to the documentation of this file.](#)

```
1  /*****
   *****/
15 /*****
   *****/
16
17 #ifndef AE_GAME_STATE_MGR_H
18 #define AE_GAME_STATE_MGR_H
19
20 // -----
   -----
21 // defines and enums
22
23 #define AE_GS_RESTART    0xFFFFFFFFE
24 #define AE_GS_QUIT      0xFFFFFFFFF
25
26 // -----
   -----
27 // externs
28
29 extern AE_API u32 gAEGameStateInit;
30 extern AE_API u32 gAEGameStateCurr;
31 extern AE_API u32 gAEGameStatePrev;
32 extern AE_API u32 gAEGameStateNext;
33
34 // -----
   -----
```

```

35 |
36 | extern AE_API void (*AEGameStateLoad)(void);
37 | extern AE_API void (*AEGameStateInit)(void);
38 | extern AE_API void (*AEGameStateUpdate)
    | (void);
39 | extern AE_API void (*AEGameStateDraw)(void);
40 | extern AE_API void (*AEGameStateFree)(void);
41 | extern AE_API void (*AEGameStateUnload)
    | (void);
42 |
43 | // -----
    | -----
44 | // Function prototypes
45 | // -----
    | -----
46 |
47 | #ifdef __cplusplus
48 |
49 | extern "C"
50 | {
51 | #endif
52 | // -----
    | -----
53 |
54 | /*****
    | *****/
93 | /*****
    | *****/
94 | AE_API void AEGameStateMgrAdd(u32
    | gameStateIdx,
95 |                               void (*pLoad)
    | ()),
96 |                               void (*pInit)
    | ()),
97 |                               void (*pUpdate)
    | ()),
98 |                               void (*pDraw)

```

```

    ( ),
99 |                                     void (*pFree)
    ( ),
100 |                                     void (*pUnload)
    ());
101 |
102 | /*****
    *****/
120 | /*****
    *****/
121 | AE_API void AEGameStateMgrInit(u32
    gameStateInit);
122 |
123 | /*****
    *****/
135 | /*****
    *****/
136 | AE_API void AEGameStateMgrUpdate();
137 |
138 | // -----
    -----
139 |
140 | #ifdef __cplusplus
141 | }
142 | #endif
143 |
144 | // -----
    -----
145 |
146 | #endif // AE_GAME_STATE_MGR_H

```

Alpha Engine

Main Page	Classes	Files
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include >		

AEInput.h

[Go to the documentation of this file.](#)

```
1  /*****
   *****/
15 /*****
   *****/
16
17 #ifndef AE_INPUT_H
18 #define AE_INPUT_H
19
20 // -----
   -----
21 // Defines/Enums
22
23 // These defines don't match the direct input
   defines and you should be using these
24 // defines instead of the ones in "dinput.h"
25 // For more key codes go to
   http://msdn.microsoft.com/en-
   us/library/windows/desktop/dd375731(v=vs.85).as
   px
26
27 #define AEVK_LBUTTON          VK_LBUTTON
28 #define AEVK_RBUTTON          VK_RBUTTON
29 #define AEVK_MBUTTON          VK_MBUTTON
30
31 #define AEVK_BACK              VK_BACK
32 #define AEVK_TAB               VK_TAB
```

```
33 #define AEVK_RETURN VK_RETURN
34 #define AEVK_LSHIFT VK_LSHIFT
35 #define AEVK_RSHIFT VK_RSHIFT
36 #define AEVK_LCTRL VK_LCONTROL
37 #define AEVK_RCTRL VK_RCONTROL
38 #define AEVK_LALT VK_LMENU
39 #define AEVK_RALT VK_RMENU
40 #define AEVK_PRINTSCREEN VK_SNAPSHOT
41 #define AEVK_SCROLLLOCK VK_SCROLL
42 #define AEVK_PAUSE VK_PAUSE
43 #define AEVK_CAPSLOCK VK_CAPITAL
44
45 #define AEVK_ESCAPE VK_ESCAPE
46
47 #define AEVK_SPACE VK_SPACE
48 #define AEVK_PAGEUP VK_PRIOR
49 #define AEVK_PAGEDOWN VK_NEXT
50 #define AEVK_END VK_END
51 #define AEVK_HOME VK_HOME
52 #define AEVK_LEFT VK_LEFT
53 #define AEVK_UP VK_UP
54 #define AEVK_RIGHT VK_RIGHT
55 #define AEVK_DOWN VK_DOWN
56 #define AEVK_INSERT VK_INSERT
57 #define AEVK_DELETE VK_DELETE
58
59 #define AEVK_0 0x30
60 #define AEVK_1 0x31
61 #define AEVK_2 0x32
62 #define AEVK_3 0x33
63 #define AEVK_4 0x34
64 #define AEVK_5 0x35
65 #define AEVK_6 0x36
66 #define AEVK_7 0x37
67 #define AEVK_8 0x38
68 #define AEVK_9 0x39
69
```


70	#define AEVK_A	0x41
71	#define AEVK_B	0x42
72	#define AEVK_C	0x43
73	#define AEVK_D	0x44
74	#define AEVK_E	0x45
75	#define AEVK_F	0x46
76	#define AEVK_G	0x47
77	#define AEVK_H	0x48
78	#define AEVK_I	0x49
79	#define AEVK_J	0x4A
80	#define AEVK_K	0x4B
81	#define AEVK_L	0x4C
82	#define AEVK_M	0x4D
83	#define AEVK_N	0x4E
84	#define AEVK_O	0x4F
85	#define AEVK_P	0x50
86	#define AEVK_Q	0x51
87	#define AEVK_R	0x52
88	#define AEVK_S	0x53
89	#define AEVK_T	0x54
90	#define AEVK_U	0x55
91	#define AEVK_V	0x56
92	#define AEVK_W	0x57
93	#define AEVK_X	0x58
94	#define AEVK_Y	0x59
95	#define AEVK_Z	0x5A
96		
97	#define AEVK_NUMPAD0	VK_NUMPAD0
98	#define AEVK_NUMPAD1	VK_NUMPAD1
99	#define AEVK_NUMPAD2	VK_NUMPAD2
100	#define AEVK_NUMPAD3	VK_NUMPAD3
101	#define AEVK_NUMPAD4	VK_NUMPAD4
102	#define AEVK_NUMPAD5	VK_NUMPAD5
103	#define AEVK_NUMPAD6	VK_NUMPAD6
104	#define AEVK_NUMPAD7	VK_NUMPAD7
105	#define AEVK_NUMPAD8	VK_NUMPAD8
106	#define AEVK_NUMPAD9	VK_NUMPAD9

```

107
108 #define AEVK_NUM_MULTIPLY    VK_MULTIPLY
109 #define AEVK_NUM_PLUS        VK_ADD
110 #define AEVK_NUM_MINUS       VK_SUBTRACT
111 #define AEVK_NUM_PERIOD      VK_DECIMAL
112 #define AEVK_NUM_DIVIDE      VK_DIVIDE
113 #define AEVK_NUMLOCK         VK_NUMLOCK
114
115 #define AEVK_F1               VK_F1
116 #define AEVK_F2               VK_F2
117 #define AEVK_F3               VK_F3
118 #define AEVK_F4               VK_F4
119 #define AEVK_F5               VK_F5
120 #define AEVK_F6               VK_F6
121 #define AEVK_F7               VK_F7
122 #define AEVK_F8               VK_F8
123 #define AEVK_F9               VK_F9
124 #define AEVK_F10              VK_F10
125 #define AEVK_F11              VK_F11
126 #define AEVK_F12              VK_F12
127
128 #define AEVK_SEMICOLON        VK_OEM_1
129 #define AEVK_SLASH            VK_OEM_2
130 #define AEVK_BACKQUOTE        VK_OEM_3
131 #define AEVK_LBRACKET         VK_OEM_4
132 #define AEVK_BACKSLASH        VK_OEM_5
133 #define AEVK_RBRACKET         VK_OEM_6
134 #define AEVK_QUOTE            VK_OEM_7
135
136 #define AEVK_EQUAL             VK_OEM_PLUS
137 #define AEVK_MINUS             VK_OEM_MINUS
138 #define AEVK_PERIOD            VK_OEM_PERIOD
139 #define AEVK_COMMA             VK_OEM_COMMA
140
141 // -----
// -----
142 // Function prototypes

```

```

143 |
144 | #ifdef __cplusplus
145 |
146 | extern "C"
147 | {
148 | #endif
149 |
150 | // -----
    -----
151 |
152 | /*****
    *****/
164 | /*****
    *****/
165 | AE_API s32 AEInputInit();
166 |
167 | /*****
    *****/
178 | /*****
    *****/
179 | AE_API void AEInputReset();
180 |
181 | /*****
    *****/
192 | /*****
    *****/
193 | AE_API void AEInputUpdate();
194 |
195 | /*****
    *****/
206 | /*****
    *****/
207 | AE_API void AEInputExit();
208 |
209 | /*****
    *****/
226 | /*****

```

```

*****/
227 | AE_API u8 AEInputCheckCurr      (u8 key);
228 |
229 | /*****
*****/
246 | /*****
*****/
247 | AE_API u8 AEInputCheckPrev      (u8 key);
248 |
249 | /*****
*****/
266 | /*****
*****/
267 | AE_API u8 AEInputCheckTriggered (u8 key);
268 |
269 | /*****
*****/
286 | /*****
*****/
287 | AE_API u8 AEInputCheckReleased  (u8 key);
288 |
289 | /*****
*****/
306 | /*****
*****/
307 | AE_API void AEInputGetCursorPosition(s32 *pX,
s32 *pY);
308 |
309 | /*****
*****/
326 | /*****
*****/
327 | AE_API void AEInputGetCursorPositionDelta(s32
*pDeltaX, s32 *pDeltaY);
328 |
329 | /*****
*****/

```

```

344  /*****
      *****/
345  AE_API void AEInputShowCursor(s32 Show);
346
347  // -----
      -----
348
349  #ifdef __cplusplus
350  }
351  #endif
352
353  // -----
      -----
354
355  #endif // AE_INPUT_H
356

```

Alpha Engine

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include		

AEMath.h

[Go to the documentation of this file.](#)

```
1  /** *****
    ***** */
15 /** *****
    ***** */
16
17 #ifndef AE_MATH_H
18 #define AE_MATH_H
19
20 // -----
    -----
21
22 #include "AEVec2.h" //Vector 2D
23 #include "AEMtx33.h" //Matrix 3x3
24 #include "AELineSegment2.h" //LineSegment 2D
25
26 #include <float.h>
27
28 #include "math.h"
29
30 // -----
    -----
31 #ifdef __cplusplus
32
33 extern "C"
34 {
35 #endif
```

```

36 |
37 | //AE_API void MathInit();
38 |
39 | // -----
   | -----
40 |
41 | /*****
   | *****/
53 | /*****
   | *****/
54 | AE_API f32 AEDegToRad(f32 x);
55 |
56 | /*****
   | *****/
68 | /*****
   | *****/
69 | AE_API f32 AERadToDeg(f32 x);
70 |
71 | /*****
   | *****/
83 | /*****
   | *****/
84 | AE_API f32 AESin      (f32 x);
85 |
86 | /*****
   | *****/
98 | /*****
   | *****/
99 | AE_API f32 AECos      (f32 x);
100 |
101 | /*****
   | *****/
113 | /*****
   | *****/
114 | AE_API f32 AETan      (f32 x);
115 |
116 | /*****

```

```

***** /
128 | /*****
***** /
129 | AE_API f32 AEASin    (f32 x);
130 |
131 | /*****
***** /
143 | /*****
***** /
144 | AE_API f32 AEACos    (f32 x);
145 |
146 | /*****
***** /
158 | /*****
***** /
159 | AE_API f32 AEATan    (f32 x);
160 |
161 | // -----
-----

162 |
164 |     #define AESinDeg(x)
    AESin(AEDegToRad(x))
166 |     #define AECosDeg(x)
    AECos(AEDegToRad(x))
167 |     #define AETanDeg(x)
    AETan(AEDegToRad(x))
168 |     #define AEASinDeg(x)
    AERadToDeg(AEASin(x))
169 |     #define AEACosDeg(x)
    AERadToDeg(AEACos(x))
170 |     #define AEATanDeg(x)
    AERadToDeg(AEATan(x))
171 |
172 |
173 | // -----
-----

174 |

```



```

175 | /*****
      *****/
197 | /*****
      *****/
198 | AE_API u32 AEIsPowOf2 (u32 x);
199 |
200 | /*****
      *****/
221 | /*****
      *****/
222 | AE_API u32 AENextPowOf2(u32 x);
223 |
224 | /*****
      *****/
238 | /*****
      *****/
239 | AE_API u32 AELogBase2 (u32 x);
240 |
241 | /*****
      *****/
263 | /*****
      *****/
264 | AE_API f32 AEClamp (f32 X, f32 Min, f32
      Max);
265 |
266 | /*****
      *****/
290 | /*****
      *****/
291 | AE_API f32 AEWrap (f32 x, f32 x0, f32
      x1);
292 |
293 | /*****
      *****/
311 | /*****
      *****/
312 | AE_API f32 AEMin (f32 x, f32 y);

```

```

313 |
314 |
315 | /*****
    *****/
333 | /*****
    *****/
334 | AE_API f32 AEMax      (f32 x, f32 y);
335 |
336 | /*****
    *****/
359 | /*****
    *****/
360 | AE_API s32 AEInRange  (f32 x, f32 x0, f32
    x1);
361 |
362 | // -----
    -----
363 |
364 | /*****
    *****/
394 | /*****
    *****/
395 | AE_API f32 AECalcDistPointToCircle
    (AEVec2* pPos, AEVec2* pCtr, f32 radius);
396 |
397 | /*****
    *****/
438 | /*****
    *****/
439 | AE_API f32 AECalcDistPointToRect
    (AEVec2* pPos, AEVec2* pRect, f32 sizeX, f32
    sizeY);
440 |
441 | /*****
    *****/
469 | /*****
    *****/

```

```

470 | AE_API f32 AECalcDistPointToLineSeg
    | (AEVec2* pPos, AEVec2* pLine0, AEVec2* pLine1);
471 |
472 | /*****
    | *****/
504 | /*****
    | *****/
505 | AE_API f32 AECalcDistPointToConvexPoly
    | (AEVec2* pPos, AEVec2* pVtx, u32 vtxNum);
506 |
507 | /*****
    | *****/
540 | /*****
    | *****/
541 | AE_API f32 AECalcDistCircleToCircle
    | (AEVec2* pCtr0, f32 radius0, AEVec2* pCtr1, f32
    | radius1);
542 |
543 | /*****
    | *****/
587 | /*****
    | *****/
588 | AE_API f32 AECalcDistCircleToRect
    | (AEVec2* pCtr, f32 radius, AEVec2* pRect, f32
    | sizeX, f32 sizeY);
589 |
590 | /*****
    | *****/
641 | /*****
    | *****/
642 | AE_API f32 AECalcDistRectToRect
    | (AEVec2* pRect0, f32 sizeX0, f32 sizeY0,
    | AEVec2* pRect1, f32 sizeX1, f32 sizeY1, AEVec2*
    | pNormal);
643 |
644 | /* Functions not defined
645 | AE_API f32 AECalcDistCircleToLineSeg

```

```

        (AEVec2* pPos, AEVec2* pLine0, AEVec2* pLine1);
646 | AE_API f32 AECalcDistCircleToConvexPoly
        (AEVec2* pPos, AEVec2* pVtx, u32 vtxNum);
647 | */
648 |
649 | // -----
        -----
650 |
651 | /*****
        *****/
678 | /*****
        *****/
679 | AE_API s32 AETestPointToCircle
        (AEVec2* pPos, AEVec2* pCtr, f32 radius);
680 |
681 | /*****
        *****/
716 | /*****
        *****/
717 | AE_API s32 AETestPointToRect
        (AEVec2* pPos, AEVec2* pRect, f32 sizeX, f32
        sizeY);
718 |
719 | /*****
        *****/
750 | /*****
        *****/
751 | AE_API s32 AETestCircleToCircle
        (AEVec2* pCtr0, f32 radius0, AEVec2* pCtr1, f32
        radius1);
752 |
753 | /*****
        *****/
794 | /*****
        *****/
795 | AE_API s32 AETestCircleToRect
        (AEVec2* pCtr, f32 radius, AEVec2* pRect, f32

```

```

sizeX, f32 sizeY);
796 |
797 | /*****
      *****/
841 | /*****
      *****/
842 | AE_API s32 AETestRectToRect
      (AEVec2* pRect0, f32 sizeX0, f32 sizeY0,
      AEVec2* pRect1, f32 sizeX1, f32 sizeY1);
843 |
844 | // -----
      -----
845 |
846 | /*****
      *****/
870 | /*****
      *****/
871 | AE_API f32
      AESTaticPointToStaticLineSegment(AEVec2 *pPos,
      AELineSegment2 *pLine);
872 |
873 | /*****
      *****/
906 | /*****
      *****/
907 | AE_API f32
      AEAnimatedPointToStaticLineSegment(AEVec2
      *pStart, AEVec2 *pEnd, AELineSegment2 *pLine,
      AEVec2 *pInter);
908 |
909 | /*****
      *****/
948 | /*****
      *****/
949 | AE_API f32
      AEAnimatedCircleToStaticLineSegment(AEVec2
      *pStart, AEVec2 *pEnd, f32 radius,

```

```

    AELineSegment2 *pLine, AEVec2 *pInter);
950
951  /*****
    *****/
989  /*****
    *****/
990  AE_API f32
    AEReflectAnimatedPointOnStaticLineSegment(AEVec2
    *pStart, AEVec2 *pEnd, AELineSegment2 *pLine,
    AEVec2 *pInter, AEVec2 *pReflect);
991
992  /*****
    *****/
1037 /*****
    *****/
1038 AE_API f32
    AEReflectAnimatedCircleOnStaticLineSegment(AEVec2
    *pStart, AEVec2 *pEnd, f32 radius,
    AELineSegment2 *pLine, AEVec2 *pInter, AEVec2
    *pReflect);
1039
1040 /*****
    *****/
1078 /*****
    *****/
1079 AE_API f32
    AEAnimatedPointToStaticCircle(AEVec2 *pStart,
    AEVec2 *pEnd, AEVec2 *pCtr, f32 radius, AEVec2
    *pInter);
1080
1081 /*****
    *****/
1124 /*****
    *****/
1125 AE_API f32
    AEReflectAnimatedPointOnStaticCircle(AEVec2
    *pStart, AEVec2 *pEnd, AEVec2 *pCtr, f32

```

```

    radius, AEVec2 *pInter, AEVec2 *pReflect);
1126 |
1127 | /*****
    *****/
1169 | /*****
    *****/
1170 | AE_API f32
    AAnimatedCircleToStaticCircle(AEVec2 *pCtr0s,
    AEVec2 *pCtr0e, f32 radius0, AEVec2 *pCtr1, f32
    radius1, AEVec2 *pInter);
1171 |
1172 | /*****
    *****/
1220 | /*****
    *****/
1221 | AE_API f32
    AReflectAnimatedCircleOnStaticCircle(AEVec2
    *pCtr0s, AEVec2 *pCtr0e, f32 radius0, AEVec2
    *pCtr1, f32 radius1, AEVec2 *pInter, AEVec2
    *pReflect);
1222 |
1223 |
1224 |
1225 | /*
1226 | // sweep a circle with radius 'radius' from
    ctr0 -> ctr1 againts a point
1227 | // * return -ve if circle does not touch the
    point at any time
1228 | AE_API f32 AESweepCircleToPoint (AEVec2*
    pCtr0, AEVec2* pCtr1, f32 radius, AEVec2* pP);
1229 |
1230 | // sweep a circle with radius 'radius' from
    ctr0 -> ctr1 againts a line segment
1231 | // * return -ve if circle does not intersect
    the line segment at any time
1232 | AE_API f32 AESweepCircleToLineSeg (AEVec2*
    pCtr0, AEVec2* pCtr1, f32 radius, AEVec2* pP0,

```

```

    AEVec2* pP1, AEVec2* pN);
1233 |
1234 |
1235 | //T0 TEST
1236 | //Sweeps a moving point against a static line
1237 | AE_API f32 AESweepPointToLine      (AEVec2
    *pPos, AEVec2 *pVel, AEVec2 *pPnt, AEVec2
    *pDirection);
1238 |
1239 | //T0 TEST
1240 | //Sweeps a moving circle against a static
    line
1241 | AE_API f32 AESweepCircleToLine      (AEVec2
    *pCtr, f32 radius, AEVec2 *pVel, AEVec2 *pPnt,
    AEVec2 *pDirection);
1242 |
1243 | //T0 TEST
1244 | //Reflects a moving point on a static line.
    Returns 0 if there is no
1245 | //collision between the point and the line.
1246 | AE_API s32 AEReflectPointOnLine (AEVec2
    *pPos, AEVec2 *pVel, AEVec2 *pPnt, AEVec2
    *pDirection, AEVec2 *pNewPosition, AEVec2
    *pNewVelocity);
1247 |
1248 |
1249 | //T0 TEST
1250 | //Reflects a moving circle on a static line.
    Returns 0 if there is no
1251 | //collision between the circle and the line.
1252 | AE_API s32 AEReflectCircleOnLine      (AEVec2
    *pCtr, f32 radius, AEVec2 *pVel, AEVec2 *pPnt,
    AEVec2 *pDirection, AEVec2 *pNewPosition,
    AEVec2 *newVelocity);
1253 | */
1254 | // -----
    -----

```



```
1255 |
1256 | #ifdef __cplusplus
1257 | }
1258 | #endif
1259 |
1260 | // -----
1261 |
1262 | #endif // AE_MATH_H
```

Alpha Engine

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include >		

AESystem.h

[Go to the documentation of this file.](#)

```
1  /*****
   *****/
15 /*****
   *****/
16
17 #ifndef AE_SYSTEM_H
18 #define AE_SYSTEM_H
19
20 // -----
   -----
21
22 // window related variables
23 extern HINSTANCE      ghAESysAppInstance;
24 extern HWND           gAESysWindowHandle;
25 extern WNDCLASS       winClass;
26
27 extern const s8*      gpAESysWinTitle;
28 extern const s8*      gpAESysWinClassName;
29
30 extern AE_API s32 gAESysAppActive;
31
32 // -----
   -----
33 #ifdef __cplusplus
34 extern "C"
35 {
```

```

36 | #endif
37 |
38 | /*****
    *****/
80 | /*****
    *****/
81 | AE_API s32 AESysInit (HINSTANCE
    hAppInstance, s32 show, s32 WinWidth, s32
    WinHeight, s32 CreateConsole, u32 FrameRateMax,
    LRESULT (CALLBACK *pWinCallBack)(HWND hWnd,
    UINT msg, WPARAM wp, LPARAM lp));
82 |
83 | /*****
    *****/
95 | /*****
    *****/
96 | AE_API void AESysReset ();
97 |
98 | // Already called in AESysFrameEnd
99 | //AE_API void AESysUpdate ();
100 |
101 | /*****
    *****/
113 | /*****
    *****/
114 | AE_API void AESysExit ();
115 |
116 | /*****
    *****/
128 | /*****
    *****/
129 | AE_API void AESysFrameStart();
130 |
131 | /*****
    *****/
143 | /*****
    *****/

```

```

144 | AE_API void AESysFrameEnd();
145 |
146 | /*****
    *****/
155 | /*****
    *****/
156 | AE_API HWND AESysGetWindowHandle    ();
157 |
158 | //AE_API s32* AESysGetAppActive    ();
159 |
160 | /*****
    *****/
173 | /*****
    *****/
174 | AE_API void AESysSetWindowTitle    (const s8
    *pTitle);
175 |
176 | /*****
    *****/
186 | /*****
    *****/
187 | AE_API s32 AESysDoesWindowExist    ();
188 |
189 | // -----
    -----
190 |
191 |
192 |
193 | // -----
    -----
194 |
195 |
196 | #ifdef __cplusplus
197 | }
198 | #endif
199 |
200 | #endif // AE_SYSTEM_H

```


Alpha Engine

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AETypes.h

[Go to the documentation of this file.](#)

```
1  /*****
   *****/
15 /*****
   *****/
16
17 #ifndef AE_TYPES_H
18 #define AE_TYPES_H
19
20 // -----
   -----
21 // typedef types
22
23 typedef char s8;
24 typedef unsigned char u8;
25 typedef signed short s16;
26 typedef unsigned short u16;
27 typedef signed int s32;
28 typedef unsigned int u32;
29 typedef signed long long s64;
30 typedef unsigned long long u64;
31 typedef float f32;
32 typedef double f64;
33
34 // -----
   -----
35
```

```
36 | #endif //AE_TYPES_H
```

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Alpha Engine

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AEUtil.h

[Go to the documentation of this file.](#)

```
1  /*****
   *****/
15 /*****
   *****/
16 #ifndef AE_UTIL_H
17 #define AE_UTIL_H
18
19 // -----
   -----
20 #ifdef __cplusplus
21 extern "C"
22 {
23 #endif
24
25 /*****
   *****/
38 /*****
   *****/
39 AE_API f64 AEGetTime(f64* pTime);
40
41 /*****
   *****/
50 /*****
   *****/
51 AE_API f32 AERandFloat();
52
```



```

53 |
54 | #define isZero(x) ((x < EPSILON) && (x > -
    | EPSILON))
55 |
56 | #define isEqual(x,y) (((x >= y) ? (x-y) : (y-
    | x)) < EPSILON)
57 |
58 |
59 |
60 |
61 | #ifdef __cplusplus
62 | }
63 | #endif
64 |
65 | /*****
    | *****/
82 | /*****
    | *****/
83 | s8* ReadFromFile(const s8 *fileName);
84 |
85 | // -----
    | -----
86 |
87 | #endif // AE_UTIL_H
88 |
89 |

```

Alpha Engine

[Main Page](#)[Classes](#)[Files](#)[include](#)

include Directory Reference

Files

file [AEngine.h](#) [code]
Header file for the Alpha Engine.

file [AExport.h](#) [code]
Header file for the library settings.

file [AFrameRateController.h](#) [code]
Header file for the frame rate controller.

file [AGameStateMgr.h](#) [code]
Header file for the game state manager.

file [AGraphics.h](#) [code]
Header file for the graphics library.

file [AInput.h](#) [code]
Header file for the input library.

file [ALineSegment2.h](#) [code]
Header file for the 2D line segment library.

file [AMath.h](#) [code]
Header file for the math library.

file [AMtx33.h](#) [code]
Header file for the 3x3 matrix library.

file [ASystem.h](#) [code]
Header file for the system library.

file [ATypes.h](#) [code]
Header file for the typedefs.

file **AEUtil.h** [\[code\]](#)
Header file for the utility library.

file **AEVec2.h** [\[code\]](#)
Header file for the 2D vector library.